



SEW
EURODRIVE

Operating instructions



Decentralized Drive Systems
MOVIMOT® MM..D



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1 General information

1.1 Structure of the safety notes

1.1.1 Meaning of signal words

The following table shows the graduation and meaning of the signal words in the safety notes.

Signal word	Meaning	Consequences if not observed
⚠ DANGER	Imminent danger	Death or severe injuries
⚠ WARNING	Possibly dangerous situation	Death or severe injuries
⚠ CAUTION	Possibly dangerous situation	Minor injuries
NOTICE	Possible damage to property	Damage to the product or its environment

1.1.2 Meaning of the hazard symbols

The hazard symbols in the safety notes have the following meaning:

Hazard symbol	Meaning
	General hazard
	Warning of dangerous electrical voltage
	Warning of hot surfaces
	Warning of automatic startup

2 Safety notes

2.1 Target group

Specialist for mechanical work

Any mechanical work may be performed only by adequately qualified specialists. Specialists in the context of this documentation are persons who are familiar with the design, mechanical installation, troubleshooting, and maintenance of the product, and who possess the following qualifications:

- Qualifications in the field of mechanics in accordance with the national regulations
- Familiarity with this documentation

Specialist for electrotechnical work

Any electrotechnical work may be performed only by electrically skilled persons with a suitable education. Electrically skilled persons in the context of this documentation are persons who are familiar with electrical installation, startup, troubleshooting, and maintenance of the product, and who possess the following qualifications:

- Qualifications in the field of electrical engineering in accordance with the national regulations
- Familiarity with this documentation

Additional qualifications

In addition to that, these persons must be familiar with the valid safety regulations and laws, as well as with the requirements of the standards, directives, and laws specified in this documentation.

The persons must have the express authorization of the company to operate, program, parameterize, label, and ground devices, systems, and circuits in accordance with the standards of safety technology.

Instructed persons

All work in the areas of transport, storage, installation, operation and waste disposal may only be carried out by persons who are trained and instructed appropriately. These instructions must enable the persons to carry out the required activities and work steps safely and in accordance with regulations.

2.2 IT security

2.2.1 Contact



SEW-EURODRIVE offers the following communication channels for IT security:

- Report incidents regarding cybersecurity by e-mail to cert@sew-eurodrive.com or via the contact form on the Product Security Management website (<http://go.sew/psm>).
- Security advisories can be found in the SEW-EURODRIVE Online Support.
 - For automatic updates on new and changed security advisories, subscribe to the newsletter on the Product Security Management page (<http://go.sew/psm>).
- If you need support with the configuration, contact SEW-EURODRIVE Service.

2.2.2 IT security of the product



The IT security of the product is only guaranteed when used in an environment secured by defense-in-depth strategies.

Further information, e.g. regarding additional organizational measures to meet regulatory requirements, refer to "IT security in the context of regulatory requirements" (→ 8).

Possible hazards

Access points for manipulations

The device has interfaces that allow remote access to non-safety functions. In this context, "remote access" means that access is made available directly or indirectly via the local communication interfaces of the device with a software function beyond the physical limits of machine, inverter, and brake. These interfaces allow all parameters to be changed without a safety protocol.

Potential hazards

Potential hazards posed by unauthorized individuals with remote access to the software functions include:

- Manipulation of the speed, resulting in accelerations and decelerations.
- Unintended actuation of the power section, resulting in hazardous movement at the motor shaft.
- Unintended actuation of the brake (brake release), resulting in hazardous movement at the motor shaft.
- Excessive heating of the device and motor, resulting in thermal destruction.

Technically excluded hazards

The following hazards due to remote access by an unauthorized person are technically excluded:

- Danger due to electric shock due to corruption of general electrical safety, e.g. the separation between high and extra-low voltage.

2.2.3 IT security of the environment



For drive and control components that are integrated in a network (e.g. fieldbus, Wi-Fi, or Ethernet network), settings can even be made from more remote locations. This entails the danger of a parameter change that is not visible externally resulting in unexpected, but not uncontrolled system behavior, which in turn may impact negatively on operational safety and reliability, system availability, or data security.

Observe the following:

- The IT security of the product is only guaranteed when used in an environment secured by defense-in-depth strategies.
- Particularly in networked systems based on Wi-Fi or Ethernet and at engineering interfaces, ensure that unauthorized access is prevented. Using IT-specific security standards, such as network segmentation, adds to the security of the ports.
 - For information on the communication interfaces of the device, refer to this documentation.
 - In particular, refer to chapter "Ports and services" (→ 17) regarding the provided services of the communication interfaces.
- Ensure that clear responsibility for security is guaranteed during operation. SEW-EURODRIVE recommends an IT security management system in accordance with ISO/IEC 27001 and ISO/IEC 62443-2-4.

2.2.4 IT security in the context of regulatory requirements



Below you will find information on adhering to cybersecurity requirements with regard to various regulations.

EU Machinery Regulation

The EU Machinery Regulation (Regulation 2023/1230, "MR") sets special requirements on safety components and machines to protect them from corruption.

The described device integrates safety components that can be used to reduce hazards in machines. The safety subfunctions are implemented only electronically, without the use of software. The functionality of the safety-related components cannot therefore be corrupted via software.

Observe the following:

- Perform a risk assessment and risk minimization of the machine according to ISO 12100.
- Implement suitable technical and organizational measures to prevent unauthorized access to safety-relevant and non-safety-relevant functions, if their manipulation can lead to a hazard according to the risk assessment (see "Possible hazards" (→ 7)).

Strictly observe the following documentation:

- "Cybersecurity for generation B inverters" manual

Protection of the STO control

The safety subfunction STO is implemented only electronically, without the use of software. The software functions of the device have no effect on the STO safety subfunction. A potential attacker has no means of compromising the safety subfunctions by manipulating software or data that is transmitted to the device.

Observe the following:

- Secure the machine and its components that control the STO safety subfunction against possible compromise.

EU Data Act

The product offers "Access by Design" for all data generated by the product and thus meets the requirements of the EU Data Act (Regulation 2023/2851):

Storing data	• Data in the product is stored until it is actively deleted or overwritten. • Log and scope data is automatically overwritten in the designated ring buffers as soon as they are full. • Scope data is only stored in the device-internal RAM and is deleted after the device is restarted.
Accessing data	• All data can be read from the product using freely available engineering software from SEW-EURODRIVE or via local interfaces or network connections. Corresponding HMI systems and external controllers can also access the data of the product.
Deleting data	• For information on deleting data, refer to "IT security guidelines for secure disposal" (→ 86).
Data transmission	• The product does not automatically transfer data to devices in its environment.
Quality of service	• The device has different qualities of service for data communication: – Cyclic communication to control the device. A few bytes are transferred real-time capably and cyclically. – Acyclic access to all idle data stored on the device. • The response time depends on the communication interface used. • The cycle time is determined by the controlling or requesting device, and is usually between 1 ms and 100 ms.

For information regarding the data generated by the product, stored internally and transferred to other devices in the environment, as well as regarding deletion of data, refer to "IT security guidelines for secure disposal" (→ 86).

For more information on the EU Data Act, refer to the following documentation:

- "Cybersecurity for generation B inverters" manual

2.3 Designated use

The product is intended for installation in electrical systems or machines.

If the product is installed in electrical systems or machinery, startup is prohibited until it has been verified that the machine complies with local laws and regulations.

The standards given in the declaration of conformity apply to the product.

The systems can be mobile or stationary.

The product can be used to operate the following motors in industrial and commercial systems:

- AC asynchronous motors with squirrel-cage rotor

Technical data and information on the connection conditions are provided on the nameplate and in chapter "Technical data" in the documentation. Always comply with the data and conditions.

Unintended or improper use of the product may result in severe injury to persons and damage to property.

Do not use the product as a climbing aid.

2.3.1 Lifting applications

To avoid danger of fatal injury by falling hoists, observe the following points when using the product in lifting applications:

- The product is not designed for use as a safety device in lifting applications.
- Use additional monitoring systems or mechanical protection devices.

2.3.2 Restrictions of use

The following applications are prohibited unless the device is explicitly designed for such use:

- Use in potentially explosive areas
- Use in areas exposed to harmful oils, acids, gases, vapors, dust, and radiation
- Use in applications with impermissibly high mechanical vibration and shock loads
- Use at an elevation of more than 4000 m above sea level

The product can be used at altitudes above 1000 m above sea level up to 4000 m above sea level under the following conditions:

- The reduction of the nominal output current and/or line voltage is taken into account as per chapter "Technical data" in the associated product manual.
- Above 2000 m above sea level, the air and creepage distances are only sufficient for overvoltage class II according to EN 60664. At altitudes above 2000 m above sea level, limiting measures must therefore be taken that reduce the line side overvoltage from category III to category II for the entire system.
- If a protective electrical separation is required, implement it outside the product at altitudes of more than 2000 m above sea level.

2.4 Functional safety technology

The product optionally includes the STO safety subfunction.

The product is not permitted to perform any safety function without higher-level safety systems.

Observe the product manual of the product for use of the STO safety subfunction or other safety subfunctions.

2.5 Transportation

Inspect the shipment for damage as soon as you receive the delivery. Inform the shipping company immediately about any damage. If the product or the packaging is damaged, do not assemble, install, connect, or start up the product. If the packaging is damaged, the product itself may also be damaged.

Observe the following notes when transporting the device:

- Ensure that the product is not subject to mechanical impact.

If necessary, use suitable, sufficiently dimensioned handling equipment.

Observe the information on climatic conditions in chapter "Technical data" of the documentation.

The lifting eyebolts are designed to carry only the weight of the motor without gear unit. Tighten installed lifting eyebolts. Mounted gear units have separate suspension attachments, which must be used according to the gear unit operating instructions when lifting the gearmotor. Do not mount any additional loads.

2.6 Installation/assembly

Ensure that the product is installed and cooled in accordance with the regulations in the documentation.

Protect the product from excessive mechanical strain. The product and its mounted components must not protrude into the path of persons or vehicles. Ensure that no components are deformed or no insulation spaces are modified, particularly during transportation. Electrical components must not be mechanically damaged or destroyed.

Observe the notes in chapter "Mechanical installation" in the documentation.

2.7 Electrical installation

Ensure that all of the required covers are correctly attached after the electrical installation.

Make sure that protective measures and protection devices comply with the applicable regulations (e.g. EN 60204-1 or EN 61800-5-1).

2.7.1 Required protective measure

Make sure that the product is correctly attached to the ground connection.

2.7.2 Voltage test

To ensure the insulation is in order, perform voltage tests for the drives according to EN 61800-5-1:2007 prior to startup.

2.8 Protective separation

The product meets all requirements for protective separation of power and electronics connections in accordance with IEC 61800-5-1. The connected signal circuits must meet requirements according to SELV (**S**afety **E**xtra **L**ow **V**oltage) or PELV (**P**rotective **E**xtra **L**ow **V**oltage) to ensure protective separation. The installation must meet the requirements for protective separation.

In order to avoid exceeding the permitted contact voltages in SELV or PELV power circuits in the event of an error, continuous equipotential bonding is required in the vicinity of these power circuits. If this is not possible, other protective measures must be taken. These protective measures are described in IEC 61800-5-1.

2.9 Startup/operation

Observe the safety notes in chapters "Startup" (→ 43) and "Operation" in this documentation.

Make sure the connection boxes are closed and screwed before connecting the supply voltage.

Depending on the degree of protection, products may have live, uninsulated, and sometimes moving or rotating parts as well as hot surfaces during operation.

When the system is switched on, dangerous voltages are present on all voltage-controlled product parts as well as any cables and terminals that are connected. This also applies even when the product is inhibited and the motor is in an idle state. Do not touch the components during operation.

Do not separate the connection to the product during operation. This may result in dangerous electric arcs damaging the product.

If you disconnect the product from the voltage supply, do not touch any live components or power connections because capacitors might still be charged. Observe the following minimum switch-off time:

1 minute.

Observe the corresponding information signs on the product.

The fact that the operation LED and other display elements are no longer illuminated does not indicate that the product has been disconnected from the supply system and no longer carries any voltage.

Mechanical blocking or internal protective functions of the product can cause a motor standstill. Eliminating the cause of the problem or performing a reset may result in the drive restarting automatically. If, for safety reasons, this is not permitted for the drive-controlled machine, first disconnect the product from the supply system and then start troubleshooting.

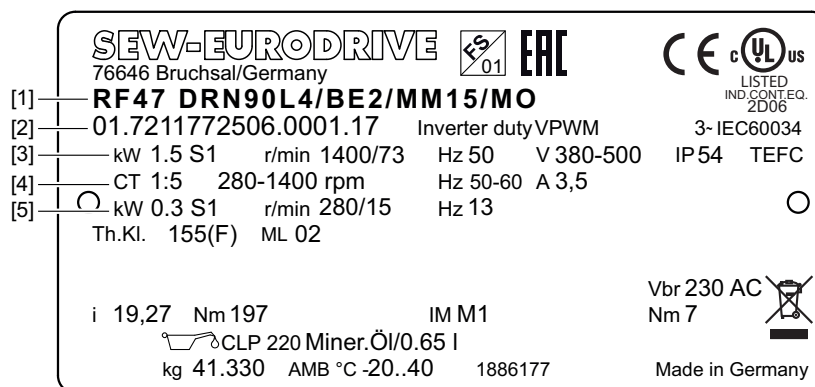
Risk of burns: The surface temperature of the product can exceed 60 °C during operation. Do not touch the product during operation. Let the product cool down before touching it.

3 Unit design

3.1 Type designation MOVIMOT® drive

3.1.1 Nameplate

The following figure gives an example of a MOVIMOT® drive nameplate. The nameplate is located on the motor.



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	Value	Meaning
[1]	RF47 DRN90L4..	Type designation
[2]	01.412153807..	Serial number
	Inverter duty VPWM	Suitability for inverter operation
	3~IEC60034	Number of phases and applied rated and power standards
[3]	kW 1.5 S1	Rated power of the drive unit/operating mode according to EN 60034-1
	r/min 1400/73	Rated speed of the drive unit, motor/gear unit
	Hz 50	Rated motor frequency
	V 380-500	Nominal input voltage of the drive unit
	IP54	Degree of protection according to IEC 60034-5
	TEFC	Type of motor cooling according to EN 60034-6
[4]	CT 1:5	Speed setting range at constant torque
	280-1400 rpm	Speed range of drive unit at constant torque
	Hz 50-60	Drive unit input frequency
	A 3.5	Nominal input current of the drive unit
[5]	kW 0.3 S1	Power rating of drive unit at lower limit speed/operating mode according to EN 60034-1
	r/min 280/15	Lower limit speed of the drive unit
	Hz 13	Motor frequency at lower limit speed

3.1.2 Type designation

The following table shows an example of the type designation of the MOVIMOT® drive **RF47 DRN90L4BE2/MM15/MO**:

RF	Gear unit series
47	Gear unit size
DRN..	Motor series (DR2S, DRS.., DRN..)
90L	Motor size
4	Number of motor poles
BE2	Additional motor feature (brake)
/	
MM15	MOVIMOT® inverter
/	
MO	Additional feature: inverter ¹⁾

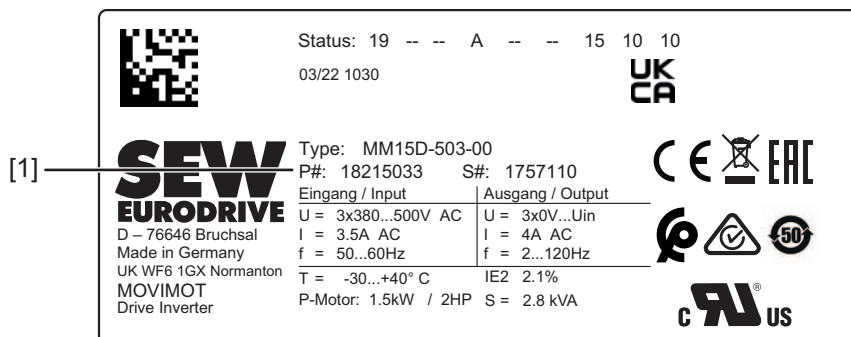
1) The nameplate only displays options installed at the factory.

The available designs can be found in the "MOVIMOT® gearmotors" catalog.

3.2 MOVIMOT® inverter type designation

3.2.1 Nameplate

The following figure gives an example of a MOVIMOT® inverter nameplate:



36028798976891275

[1] Part number

3.2.2 Type designation

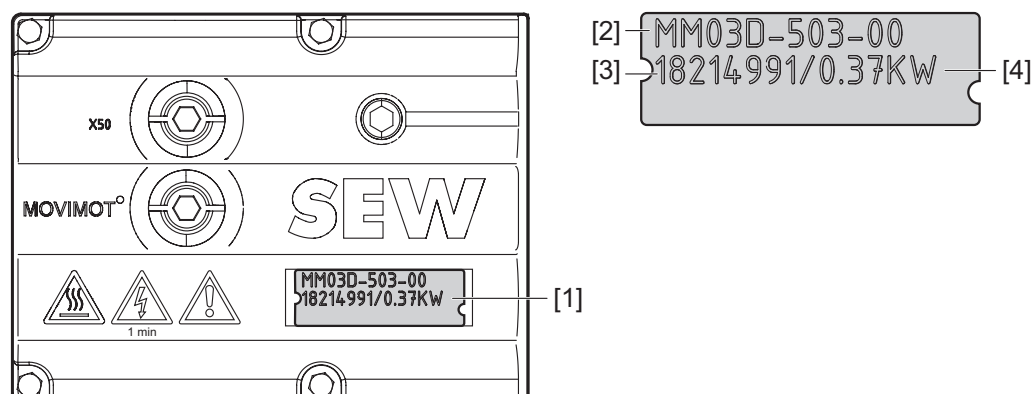
The following table shows an example of the type designation of the MOVIMOT® inverter **MM15D-503-00**:

MM	Series	MM = MOVIMOT®
15	Motor power	15 = 1.5 kW
D	Version D	
—		
50	Connection voltage	50 = AC 380 – 500 V 23 = AC 200 – 240 V
3	Connection type	3 = 3-phase
—		
00	Design	00 = Standard

The available designs can be found in the "MOVIMOT® gearmotors" catalog.

3.2.3 Unit identification

The unit identification [1] on the top of the MOVIMOT® inverter provides information about the inverter type [2], inverter part number [3], device power [4].



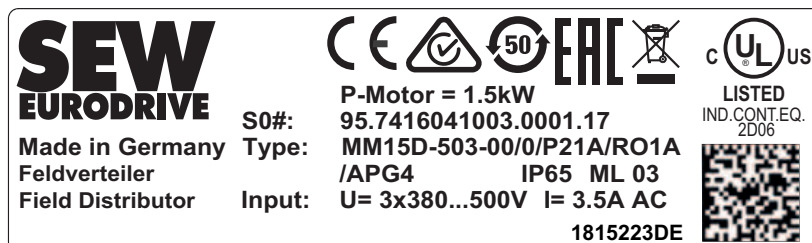
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3.3 Type designation of the "mounted close to the motor" design

3.3.1 Nameplate

Order-specific
nameplate

The following figure provides an example of an order-specific nameplate of the MOVIMOT® inverter for mounting close to the motor:



General name-
plate

The following figure provides an example of a general nameplate of the MOVIMOT® inverter for mounting close to the motor:

Input:	Output to next Field Distributor:
U= 3x200...500V I _{max} = –	U= – I _{max} = –
Input:	Output to drive:
U= 3x200...500V I _{max} = 1,3...3,5A AC f= 50...60Hz	U= 3x0...U _{input} I _{max} = 1,6...4,0A AC P-Motor= 0,25...1,5kW

3.3.2 Type designation

The following table shows the type designation for the MOVIMOT® inverter **MM15D-503-00/0/P21/RO1A/APG4** with mounting close to the motor:

MM15D-503-00	MOVIMOT® inverter
/	
0	Connection type 0 = $\curvearrowright$ 1 = $\triangle$
/	
P21A	Adapter for mounting close to the motor
/	
RO1A	Connection box design
/	
APG4	Connector for connection to the motor

3.4 Ports and services



The product has no Wi-Fi or Ethernet-based ports or services.

For information on other communication interfaces, refer to the relevant chapters of this documentation.

3.5 Markings

The following table shows an example of the markings on the nameplate.

	CE marking to state compliance with European directives (see EU declaration of conformity or EU declaration of incorporation).
	Products and accessories may fall within the scope of the country-specific transposition of the WEEE Directive. Dispose of the product and its accessories in accordance with the national regulations of your country.
	The UL and cUL mark indicate UL approval. cUL is equally eligible for approval by the CSA.
	cURus mark to confirm that UL (Underwriters Laboratory) and CSA (Canadian Standard Association) know the registered components.
	Confirms compliance with the official Mexican standard NOM-016-ENER-2016, energy efficiency of AC induction motors.
	The UKCA mark indicates compliance with British directives (see UK declaration of conformity or UK declaration of incorporation).
	The EAC mark indicates compliance with the requirements of the technical regulations of the Customs Union (Eurasian Economic Union), Armenia, Belarus, Kazakhstan, Kyrgyzstan, and Russia.
	The UA.TR mark declares conformity with the technical regulations of Ukraine.
	The RCM mark indicates compliance with the technical regulations of the Australian Communications and Media Authority (ACMA).
	The China RoHS mark indicates compliance with the directive SJ/T 11364-2014 regarding the restriction of use of certain hazardous substances in electrical and electronic equipment and its packaging.
	The KC mark declares compliance with §3 of Article 58-2 for the Korean Radio Wave Act.

3.5.1 FS logo



The markings on the top edge of the nameplate are only shown if

- The motor has been manufactured accordingly
- And contains one or more safety-related components.

The FS logo on the nameplate is based on the combination of safety-related components that is installed.

4 Mechanical installation

4.1 Installation notes

INFORMATION



You must observe the general safety notes.



⚠ WARNING

Improper assembly/disassembly of MOVIMOT® drives and add-on parts.

Risk of injury.

- You must observe the information regarding installation and disassembly.
- Before releasing any shaft connections, make sure there is no active torque on the shaft (tension within the system).



⚠ WARNING

Risk of injury due to unintentional start-up of the drive and danger due to electrical voltage.

Dangerous voltages may still be present for up to 1 minute after disconnection from the supply system.

- Disconnect the MOVIMOT® drive from the power supply before you start working on the unit and secure it against unintentional reconnection to the voltage supply.
- Secure the output shaft against rotation.
- Wait for at least 1 minute before removing the MOVIMOT® inverter.
- Comply with all instructions referring to the technical data and the permissible conditions where the unit is operated.
- Only use the provided attachment options when mounting the MOVIMOT® drive.
- Use only the mounting and locking elements that fit into the existing bores, threads, and countersinks.

4.2 Tools required

- Set of wrenches
- Socket wrench, SW8
- Torque wrench
- Screwdriver set
- Compensation elements (washers and spacing rings), if necessary

4.3 Installation tolerances

The following table shows the permitted tolerances of the shaft ends and flanges of the MOVIMOT® drive.

Shaft end	Flange
Diameter tolerance according to EN 50347 • ISO j6 at $\varnothing \leq 26$ mm • ISO k6 with $\varnothing \geq 38$ mm up to ≤ 48 mm • ISO m6 at $\varnothing > 55$ mm • Centering bore according to DIN 332, shape DR..	Centering shoulder tolerance according to EN 50347 • ISO j6 at $\varnothing \leq 250$ mm • ISO h6 at $\varnothing > 300$ mm

4.4 Installation requirements

Make sure that the following requirements are met before installation:

- The data on the nameplate of the drive matches the voltage supply system.
- The drive is undamaged (no damage caused by transportation or storage).
- The ambient temperature corresponds to the specifications in chapter "Technical data". Note that the temperature range of the gear unit might also be restricted, see operating instructions of the gear unit.
- The MOVIMOT® drive must not be installed under the following harmful ambient conditions:
 - In potentially explosive atmospheres
 - Oils
 - Acids
 - Gases
 - Vapors
 - Radiation
 - etc.
- When the drive is installed in abrasive ambient conditions, protect the output end oil seals against wear.

4.5 Installation of MOVIMOT® gearmotor**4.5.1 Setting up MOVIMOT®****NOTICE**

Loss of guaranteed degree of protection if the MOVIMOT® inverter is installed incorrectly or not at all.

Damage to the MOVIMOT® inverter.

- When removing the MOVIMOT® inverter from the connection box, it must be protected from dust and moisture.

Observe the following notes and regulations for installing the MOVIMOT® drive:

- Only install the MOVIMOT® drive on a level, low-vibration, and torsionally rigid support structure.
- Observe the permitted mounting position on the drive nameplate.
- Thoroughly remove any anti-corrosion agent from the shaft ends. Use a commercially available solvent for this purpose. Do not allow the solvent to penetrate the bearings and sealing rings (damage to the material).
- Align the motor carefully to avoid placing any unacceptable strain on the motor shafts. Observe the permitted overhung and axial loads specified in the "MOVIMOT® gearmotors" catalog.
- Do not jolt or hammer the shaft end.
- Use an appropriate cover to prevent objects or fluids from entering motors in vertical mounting positions.
- Ensure sufficient clearance around the unit to enable unobstructed flow of cooling air. Ensure that exhaust air warmed by other devices cannot be drawn in.
- Balance the parts that were subsequently added to the shaft with a half key (output shafts are balanced with a half key).
- The condensation drain holes are sealed with plastic plugs. Unplug them only if necessary.

Open condensation drain holes are not permitted. Higher degrees of protection are no longer valid for open condensation drain holes.

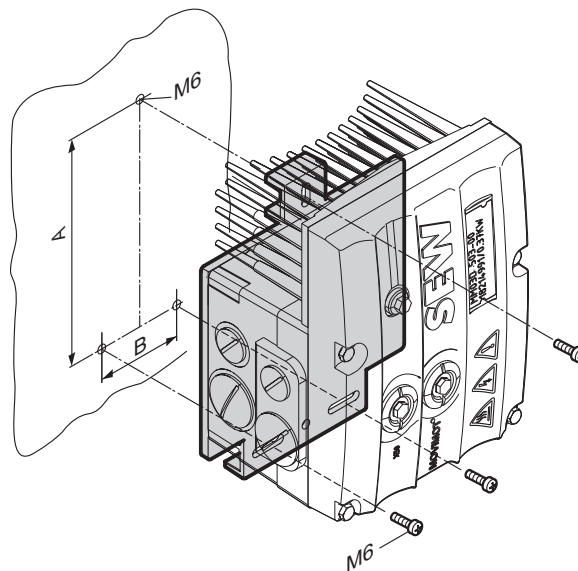
4.5.2 Installation in damp areas or outdoors

Observe the following notes for mounting the MOVIMOT® drive in damp areas or outdoors:

- Use suitable cable glands for the supply cable. If necessary, use reducers.
- Coat the thread of cable glands and screw plugs with sealing compound and tighten them well. Then coat the cable glands again.
- Seal the cable entries properly.
- Thoroughly clean the sealing surfaces of the MOVIMOT® inverter before reassembly.
- If the corrosion protection coating is damaged, restore the coating.
- Check whether the degree of protection specified on the nameplate is permitted in the ambient conditions on site.

4.6 Mounting MOVIMOT® inverter close to the motor

The following figure shows the mounting dimensions for mounting the MOVIMOT® inverter close to the motor:



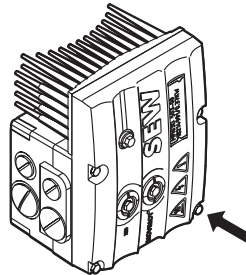
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Size	Type	A	B
1	MM03D503-00 – MM15D-503-00 MM03D233-00 – MM07D-233-00	140 mm	65 mm
2/2L	MM22D503-00 – MM40D-503-00 MM11D233-00 – MM22D-233-00	170 mm	65 mm

4.7 Tightening torques

4.7.1 MOVIMOT® inverter

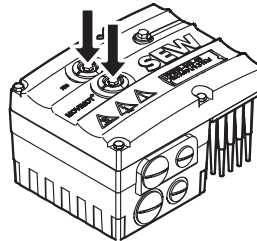
Tighten the retaining screws of the MOVIMOT® inverter to 3.0 Nm in diametrically opposite sequence.



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4.7.2 Screw plugs

Tighten the screw plugs of potentiometer f1 and connection X50 with 2.5 Nm.

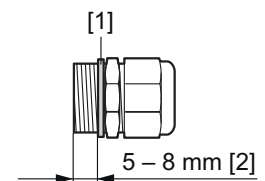


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4.7.3 Cable glands

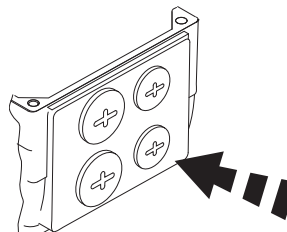
Observe the manufacturer's specifications and the following information for cable glands:

- Pay attention to the O-ring on the thread [1].
- The thread must be 5 – 8 mm long [2].



4.7.4 Screw plugs for cable entries

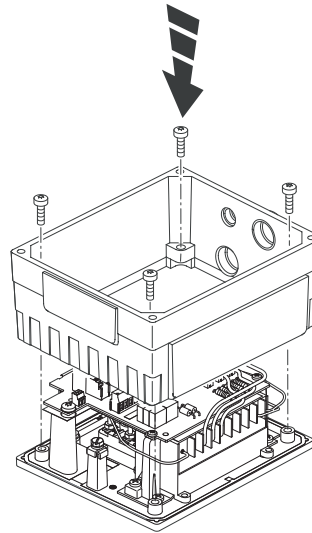
Tighten screw plugs with 2.5 Nm.



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4.7.5 Modular connection box

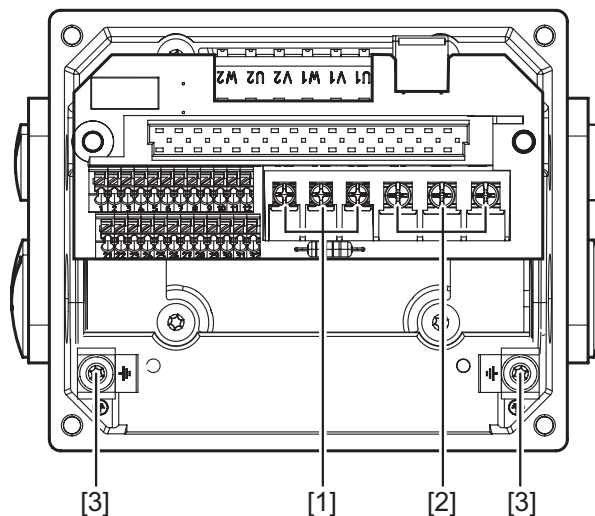
Tighten the retaining screws of the connection box on the mounting plate to 3.3 Nm.



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4.7.6 Tightening torques for terminals

Observe the following tightening torques for terminals during installation work:



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- [1] 0.8 – 1.5 Nm
- [2] 1.2 – 1.6 Nm
- [3] 2.0 – 2.4 Nm

5 Electrical installation

5.1 Installation notes

Observe the following information on electrical installation:

- Observe the general safety notes.
- Comply with all instructions referring to the technical data and the permissible conditions where the unit is operated.
- Use suitable screw fittings for the cables (use reducing adapters if necessary). With connector plug variants, you must use a suitable mating connector.
- Seal open cable entries with screw plugs.
- Use protective caps to seal plug connectors not in use.

5.2 Installation instructions

5.2.1 Connecting power supply cables

- The rated voltage and frequency of the MOVIMOT® inverter must correspond to the data of the supplying system.
- Install safety features F11/F12/F13 for line fuses at the beginning of the power supply cable behind the supply bus junction, see chapter "Connecting MOVIMOT® drive".

The following safety features are permitted for F11/F12/F13:

- Fuses in utilization category gG
- Power circuit breakers with characteristic B or C
- Motor circuit breaker

Dimension the fuses according to the cable cross section.

- Observe the information in chapter "Technical data" when selecting the fuse.
- SEW-EURODRIVE recommends using insulation monitors with pulse-code measurement in voltage supply systems with a non-grounded star point (IT systems). Using such devices prevents false tripping of the insulation monitor due to the earth capacitance of the inverter.
- Size the cable cross section according to the input current I_{grid} for rated power (see operating instructions, "Technical data" chapter).
- For ensuring the isolation and the effectiveness of preventive measures, you have to perform the checks of the valid and applicable standards (e.g. EN 60204-1 or EN 61800-5) after any wiring work for installation, conversion, repair, etc.
- When using a regenerative power supply in the system, SEW-EURODRIVE recommends a line choke in the supply line of the MOVIMOT® drive unit.

5.2.2 Permitted cable cross section of the MOVIMOT® terminals

Power terminals

Observe the permitted cable cross sections for installation:

Power terminals	
Cable cross section	1.0 mm ² – 4.0 mm ² (2 x 4.0 mm ²)
Conductor end sleeves	• For single assignment: Connect only single-wire conductors or flexible conductors with conductor end sleeves (DIN 46228, material E-CU) with or without plastic collars. • For double assignment: Connect only flexible conductors with conductor end sleeve (DIN 46228 - 1, material E-CU) without plastic collar. • Permitted length of the conductor end sleeve: at least 8 mm

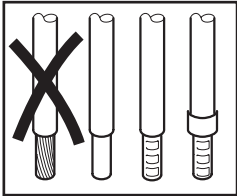
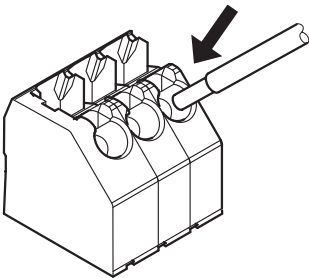
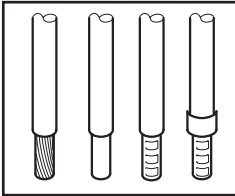
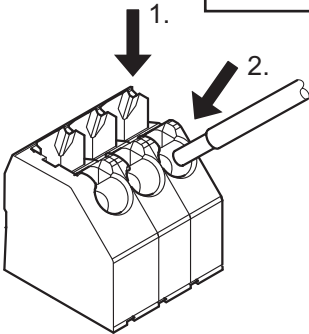
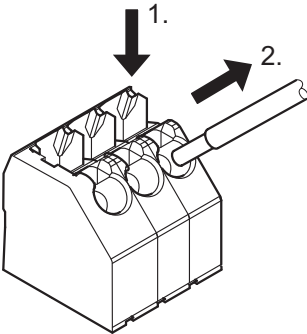
Control terminals

Observe the permitted cable cross sections for installation:

Control terminals	
Cable cross section • Single-wire conductor (bare wire) • Flexible conductor (bare litz wire) • Conductor end sleeve without plastic collar	0.5 mm ² – 1.0 mm ²
• Conductor end sleeve with plastic collar	0.5 mm ² – 0.75 mm ²
Conductor end sleeves	• Connect only single-wire conductors or flexible wire conductors with or without conductor end sleeve (DIN 46228, material E-CU). • Permitted length of the conductor end sleeve: at least 8 mm

5.2.3 Using the control terminals X5 – X6

Note the following information for actuating the control terminal clamps:

Connect conductor without pressing the activation button.	Connect conductor after pressing the activation button.
  18014399174706827	  18014399877894923
The following conductors can be installed directly (without tools) up to two cross section sizes below the nominal cross section: • Single-wire conductors • Flexible conductors with end sleeves	When connecting the following conductors, you must press the actuation button on top to open the clamping spring: • Untreated, flexible conductors • Conductors with small cross sections that cannot be plugged in directly
Removing the conductor. First press the activation button.	
	

Before removing the conductor, first press the activation button on top.

5.2.4 Selecting the residual current device

The inverter can cause a direct current in the PE conductor.

Proceed as follows to select the residual current device:

1. If using a residual current device is not mandatory according to the standards, SEW-EURODRIVE recommends not using a residual current device.
2. **⚠ WARNING!** No protection against electric shock if an incorrect type of residual current device is used. Severe or fatal injuries.
If a residual current device (residual current device RCD or residual current monitor RCM) is provided, use an all-current-sensitive RCD or RCM of type B.
3. If a residual current device is required, select the residual current device according to the requirements for protecting persons, fire protection or system protection. Observe the tripping characteristic, the deceleration and the rated tripping current of the residual current device during selection.
4. During project planning, note that leakage currents which are as low as possible occur in the system for operational reasons.
5. If the operational leakage currents in a system are too high for a single residual current device, you can split the current supply to several circuits with their own residual current devices.

5.2.5 Line contactor

NOTICE

Damage to the MOVIMOT® inverter when using the line contactor for jog mode.

Damage to the MOVIMOT® inverter.

- Do not use the line contactor for jog mode, but only for switching the inverter on and off.
 - Observe a minimum switch-off time of 2 s for the line contactor.
-
- Use only a contactor of utilization category AC3 (EN 60947-4-1) as a line contactor.

Recommendation when using an external 24 V supply: To avoid transient issues when switching on, there should be at least 2 seconds between activation of the 24 V supply and grid.

5.2.6 Information on PE connection

⚠ WARNING

Electric shock due to incorrect connection of PE.

Severe or fatal injuries.

- The permitted tightening torque for the screw is 2.0 to 2.4 Nm.
- Observe the following notes for the PE connection.

Not permitted mounting	Recommendation: Installation with forked cable lug Permitted for all cross sections	Installation with solid connection wire Permitted for cross sections up to maximum 2.5 mm ²

[1] Forked cable lug suitable for M5 PE screws

During normal operation, leakage currents ≥ 3.5 mA may occur. In order to fulfill EN 61800-5-1, observe the following information:

- The ground connection (PE) must be installed so that it meets the requirements for systems with high leakage currents.
- This usually means
 - Installing a PE connection cable with a minimum cross section of 10 mm²
 - or installing a second PE connection cable in parallel to the protective earth.

5.2.7 Connecting the 24 V supply

Supply the MOVIMOT® inverter either via an external DC 24 V supply or the MLU..A or MLG..A options.

5.2.8 Binary control

Connect the required control cables

Always use shielded cables as control cables. Route the control cables separately from the power supply cables.

5.2.9 Control via RS485 interface

The MOVIMOT® drive is controlled via the RS485 interface by one of the following controllers:

- MOVIFIT® MC
- MF..or MQ.. fieldbus interfaces
- SPS bus master
- Option MLG..A
- Option MBG11A
- Option MWA21A

INFORMATION



- Only connect a bus master to the MOVIMOT® drive.
- Use twisted pair shielded cables as control cables.
- Route the control cables separately from the power supply cables.

5.2.10 Protection devices

MOVIMOT® drives have integrated protection devices against overload and short circuit. External overload devices are not required.

5.2.11 Installation above 1000 m above sea level

MOVIMOT® drives can also be operated with line voltages of 200 – 240 V or 380 – 500 V at an altitude of 1000 – 3800 m above sea level. Therefore, observe the following basic conditions.

- At heights above 1000 m above sea level, the nominal continuous power is reduced due to reduced cooling: I_N reduction by 1% per 100 m.
- At altitudes of 2000 to 3800 m above mean sea level, you must take limiting measures which reduce the line side overvoltage from category III to category II for the entire system.

5.2.12 UL-compliant installation

The following information is provided in English and partly in French, regardless of the language of this documentation, due to UL specifications.

The UL label must be attached to the device or in close proximity to the device.

Field wiring power terminals

- Use 60/75 °C copper wire only
- Tighten terminals to 13.3 in-lbs

Short circuit current rating

Suitable for use on a circuit capable of delivering not more than 200,000 rms symmetrical amperes when protected as follows:

For 240 V systems:

250 V minimum, 25 A maximum non-semiconductor fuses or

250 V minimum, 25 A maximum inverse time circuit breakers

The max. voltage is limited to 240 V.

For 500 V systems:

500 V minimum, 25 A maximum, non-semiconductor fuses or

500 V minimum, 25 A maximum, inverse time circuit breakers

The max. voltage is limited to 500 V.

Group installation

For 240 V systems:

Suitable for group installation on a circuit capable of delivering not more than 18,000 rms symmetrical amperes when protected by 25 A maximum nonsemiconductor fuses, Class RK5 and delivering not more than 5,000 rms symmetrical amperes when protected by 25 A maximum inverse time circuit breakers.

For 500 V systems:

Suitable for group installation on a circuit capable of delivering not more than 18,000 rms symmetrical amperes when protected by 25 A maximum nonsemiconductor fuses, Class RK5 and delivering not more than 5,000 rms symmetrical amperes when protected by 25 A maximum inverse time circuit breakers.

Branch circuit protection

Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electrical Code and any additional local codes (US) or Canadian Electrical Code, Part 1 (CA).

WARNING - The opening of the branch-circuit protective device may be an indication that a fault current has been interrupted. To reduce the risk of fire or electric shock, current-carrying parts and other components of the controller should be examined and replaced if damaged. If burnout of the current element of an overload relay occurs, the complete overload relay must be replaced.

ATTENTION - LE DÉCLENCHEMENT DU DISPOSITIF DE PROTECTION DU CIRCUIT DE DÉRIVATION PEUT ÊTRE DÙ À UNE COUPURE QUI RÉSULTE D'UN COURANT DE DÉFAUT. POUR LIMITER LE RISQUE D'INCENDIE OU DE CHOC ÉLECTRIQUE, EXAMINER LES PIÈCES PORTEUSES DE COURANT ET LES AUTRES ÉLÉMENTS DU CONTRÔLEUR ET LES REMPLACER S'ILS SONT EN-DOMMAGÉS. EN CAS DE GRILLAGE DE L'ÉLÉMENT TRAVERSÉ PAR LE COURANT DANS UN RELAIS DE SURCHARGE, LE RELAIS TOUT ENTIER DOIT ÊTRE REMPLACÉ.

For maximum branch circuit protection see table below.

Series	non-semiconductor fuses	inverse time circuit breaker
Field Distributors with attached MOVIMOT® MM..D	250 V / 500 V minimum, 25 A maximum	250 V / 500 V minimum, 25 A maximum

Motor overload protection

Motor overload protection is provided by MOVIMOT® MM..D.

MOVIMOT® MM..D is provided with load and speed-sensitive overload protection and thermal memory retention upon shutdown or power loss.

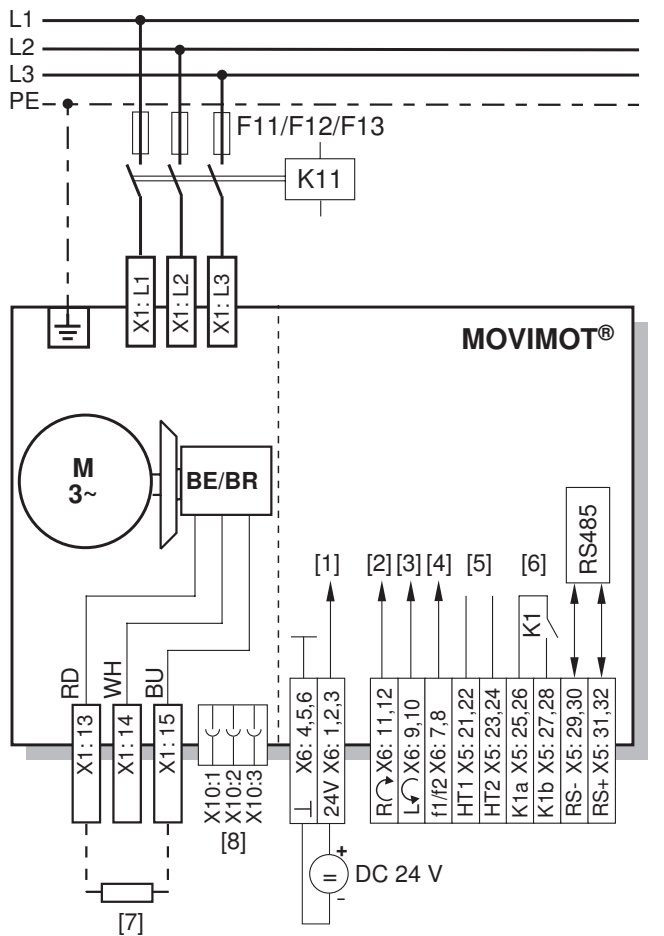
The trip current is adjusted to 140 % of the rated motor current.

Ambient temperature

The devices are suitable for an ambient temperature of 40 °C, max. 60 °C respectively 55 °C (Z.9 only) with derated output current. To determine the output current rating at higher than 40 °C, the output current should be derated 3.0 % per °C between 40 °C and 60 °C respectively 55°C (Z.9 only).

- Only use certified units with a limited output voltage ($V_{\max}$ = DC 30 V) and limited output current ($I \leq 8$ A) as an external DC 24 V voltage source.
- The UL certification only applies for the operation on voltage supply systems with voltages to ground of max. 300 V. The UL-certification does not apply to operation on voltage supply systems with a non-grounded star point (IT systems).

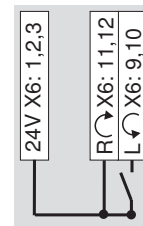
5.3 MOVIMOT® drive connection



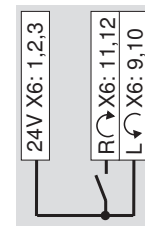
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- [1] DC 24 V supply
(external or MLU..A/MLG..A options)
- [2] CW/stop (binary input)
- [3] CCW/stop (binary input)
- [4] Setpoint changeover f1 / f2 (binary input)
- [5] HT1/HT2: Intermediate terminals for specific wiring diagrams
- [6] Ready signal
(contact closed = ready for operation)
- [7] BW.. braking resistor (only for MOVIMOT® drives without mechanical brake)
- [8] Connector for connecting the BEM or BES option

Functions of the CW/stop and CCW/stop terminals in binary control mode:

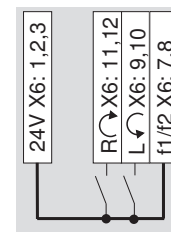
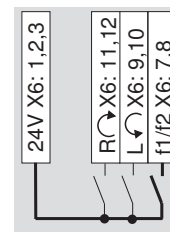


Direction of rotation
CW active



Direction of rotation
CCW active

Functions of terminals f1/f2:



Functions of the CW/stop and CCW/stop terminals with control via RS485 interface/fieldbus:



Both directions of rotation are enabled.



Only **CW**
direction of rotation is enabled.
Setpoint input for CCW rotation will stop the drive.



Only **CCW**
direction of rotation is enabled.
Setpoint specifications for CW direction of rotation cause the drive to stop.



Drive is blocked
or brought to a stop.

5.4 Connection between MOVIMOT® and motor with mounting close to the motor

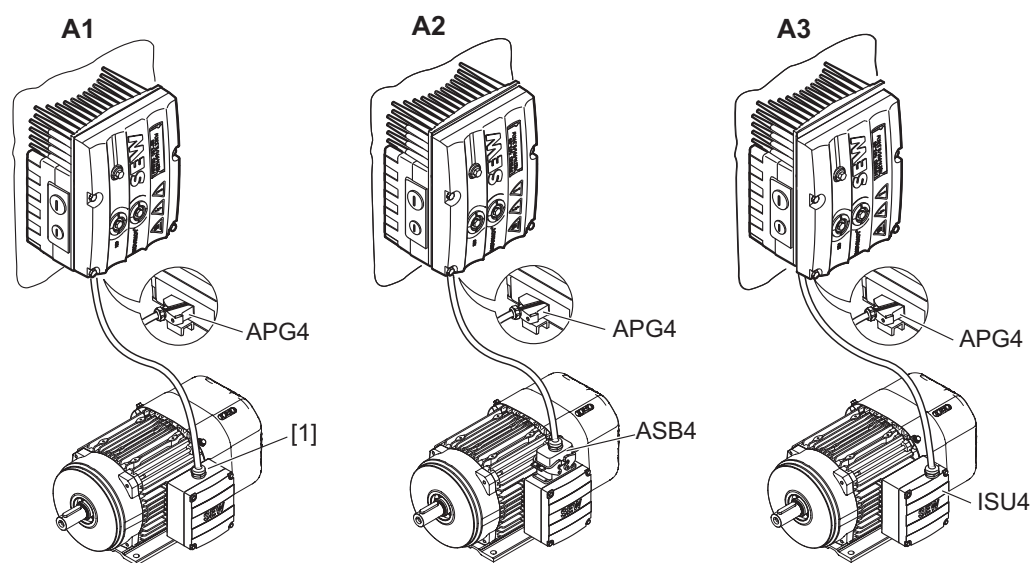
If the MOVIMOT® inverter is mounted close to the motor, the connection to the motor is realized with a prefabricated hybrid cable.

Only use hybrid cables from SEW-EURODRIVE for the connection between the MOVIMOT® inverter and the motor.

5.4.1 MOVIMOT® with APG4 connector

The APG4 design provides the following connection options to the motor, depending on the hybrid cable used:

Design	A1	A2	A3
MOVIMOT®	APG4	APG4	APG4
Motor	Cable glands/ terminals	ASB4	ISU4
Hybrid cable	01867423	05930766	08163251 △ for DR.63 0816326X △ for DR.71 – DR.132 05932785 ∟ for DR.63 05937558 ∟ for DR.71 – DR.132



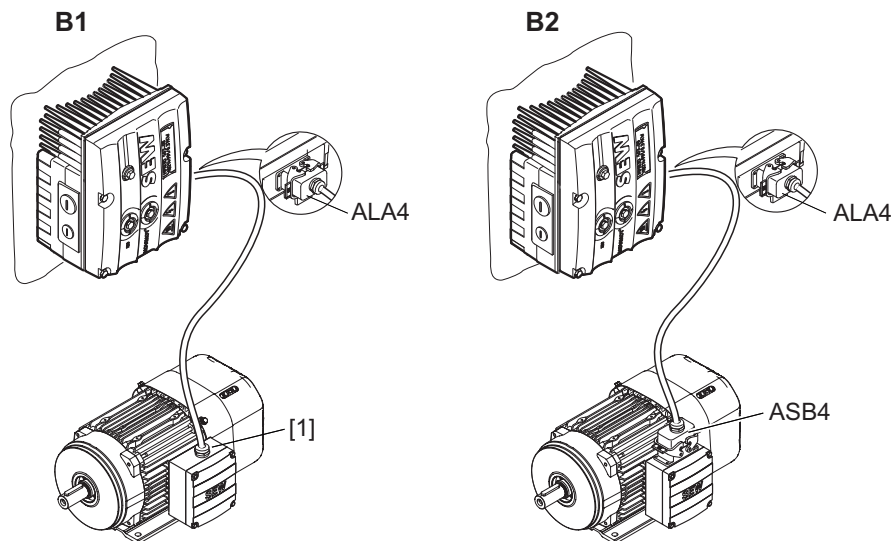
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[1] Connection via terminals

5.4.2 MOVIMOT® with ALA4 connector

The ALA4 design provides the following connection options to the motor, depending on the hybrid cable used:

Design	B1	B2
MOVIMOT®	ALA4	ALA4
Motor	Cable glands/terminals	ASB4
Hybrid cable	08179484	08162085

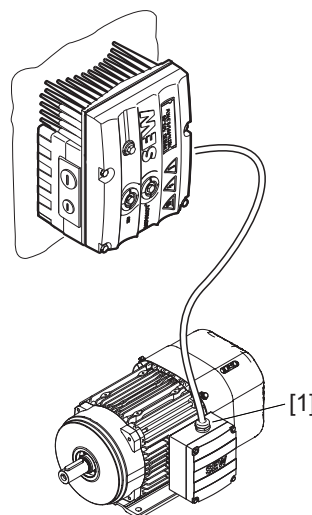


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[1] Connection via terminals

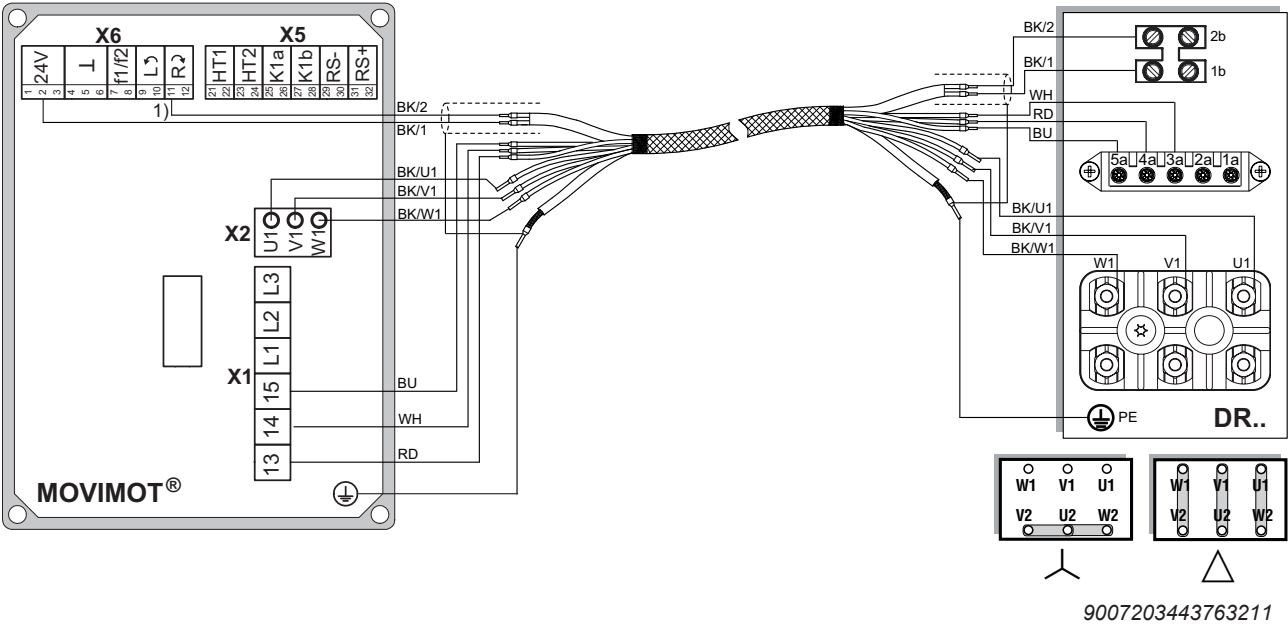
5.4.3 Connecting without connector

In the design without connector, the motor is connected directly via the terminals of the MOVIMOT®.



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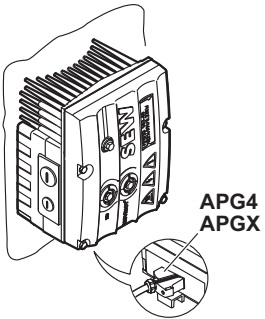
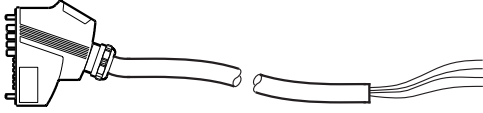
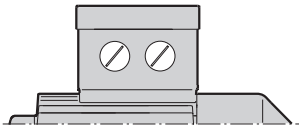
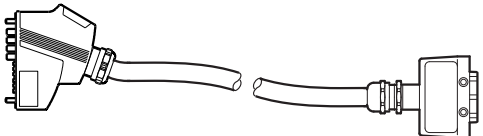
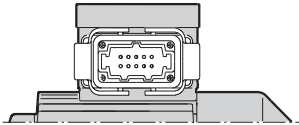
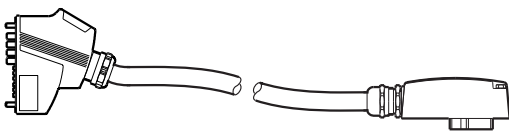
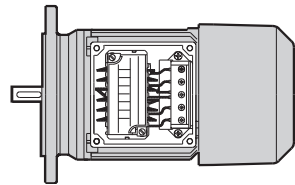
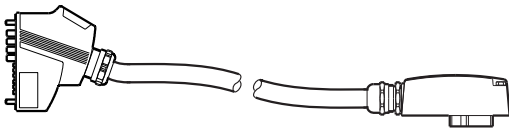
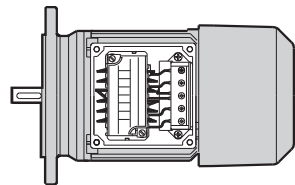
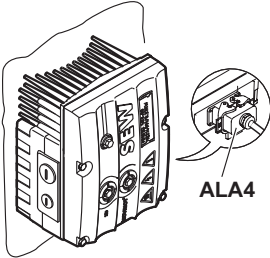
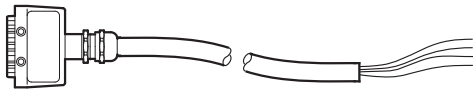
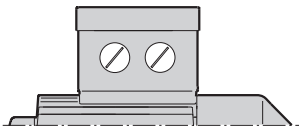
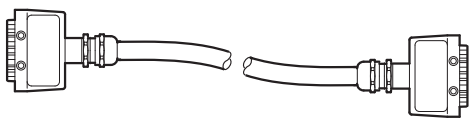
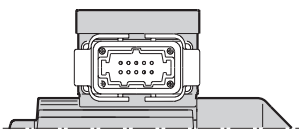
[1] Connection via terminals

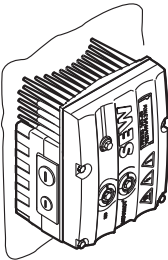
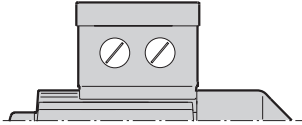
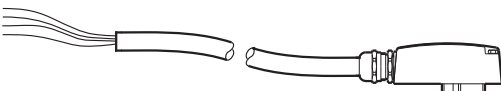
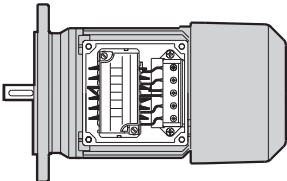
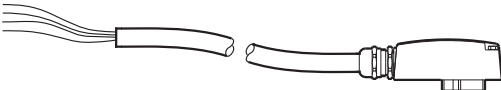
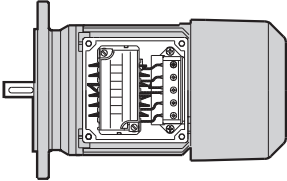
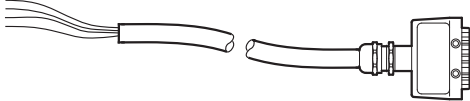
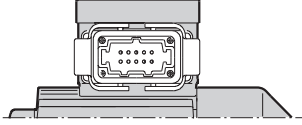


MOVIMOT®		Hybrid cable	DR.. motor
Terminal		Wire color/designation	Terminal
X2	U1	Black/U1	U1
	V1	Black/V1	V1
	W1	Black/W1	W1
X1	13	Red/13	4a
	14	White/14	3a
	15	Blue/15	5a
X6	24 V	Black/1	1b
	R or L ¹⁾	Black/2	2b
PE connection		Green/yellow + shield end (inner shield)	PE connection

1) Connect the TH cable to terminal "R" (=> clockwise rotation) or "L" (=> counterclockwise rotation) depending on the required direction of rotation.

5.4.4 Overview of connection between MOVIMOT® and motor with mounting close to the motor

MOVIMOT® inverter	Connection cable	Drive
MM../P2.A/RO.A/PG4 MM../P2.A/RO.A/PGX 	Part number DR.71 – DR.100: 01867423 Part number DR.112 – DR.132: 18116620 	AC motors with cable gland 
	Part number: 05930766 	AC motors with ASB4 connector 
	Part number: 05932785 (∟) Part number: 08163251 (Δ) 	AC motors with ISU4 connector size DR.63 
	Part number: 05937558 (∟) Part number: 0816326X (Δ) 	AC motors with ISU4 connector size DR.71 – 132 
MM../P2.A/RE.A/ALA4 	Part number: 08179484 	AC motors with cable gland 
	Part number: 08162085 	AC motors with ASB4 connector 

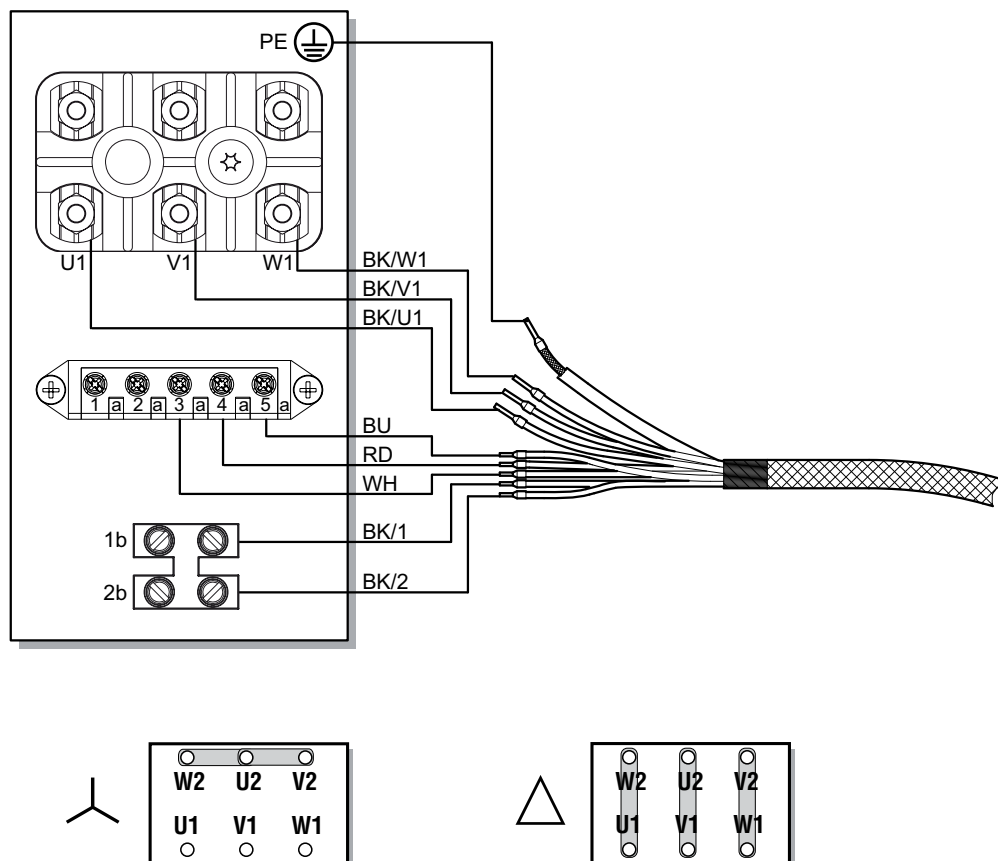
MOVIMOT® inverter	Connection cable	Drive
MM../P2.A/.. 	Part number: 08184380 	AC motors with cable gland 
	Part number: 08187843 (∩) Part number: 08165262 (△) 	AC motors with ISU4 connector size DR.63 
	Part number 08185336 (∩) Part number: 08178178 (△) 	AC motors with ISU4 connector size DR.71 – 132 
	Part number: 05931142 	AC motors with ASB4 connector 

5.4.5 Hybrid cable connection

The following table shows the conductor assignment of the hybrid cables with part numbers 01867423 and 08179484 and the corresponding motor terminals of the motor DR..:

Motor terminal motor DR..	Wire color/hybrid cable designation
U1	Black/U1
V1	Black/V1
W1	Black/W1
4a	Red/13
3a	White/14
5a	Blue/15
1b	Black/1
2b	Black/2
PE connection	Green/yellow + shield end (inner shield)

The following figure shows how to connect the hybrid cable to the terminal box of the DR.. motor:



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INFORMATION

Do not install an external brake rectifier with brakemotors.

With brakemotors, the MOVIMOT® inverter controls the brake directly.

NOTICE

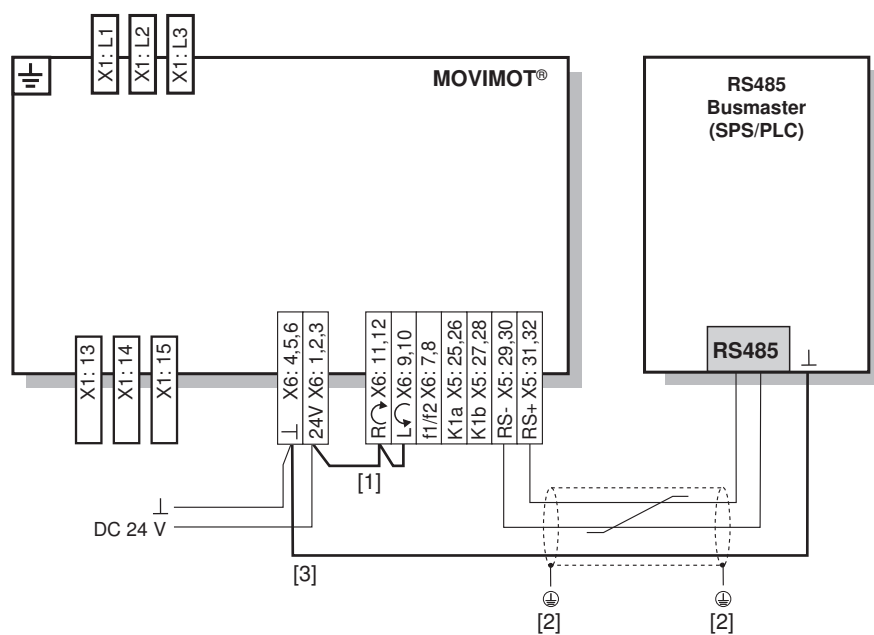
Damage to the drive due to a ground fault.

Damage to property

- During installation, avoid conductive connections between the motor output and the ground potential.
- During installation, avoid conductive connections between the brake output and the ground potential.

5.5 Connection of the RS485 bus master

The following figure shows how to connect an RS485 bus master:



36028797343253515

- [1] Observe direction of rotation enable.
See chapter "Connection of MOVIMOT® drive" (→ 34),
Functions of the CW/Stop and CCW/Stop terminals with control via RS485 interface
- [2] EMC metal cable gland
- [3] MOVIMOT®/RS485 master equipotential bonding

5.6 PC/laptop connection

MOVIMOT® drives are equipped with an X50 diagnostic interface (RJ10 connector) for startup, parameterization and service.

The diagnostic interface [1] is located underneath the screw plug on top of the MOVIMOT® inverter.

Before inserting the connector into the diagnostic interface, unscrew the screw plug.

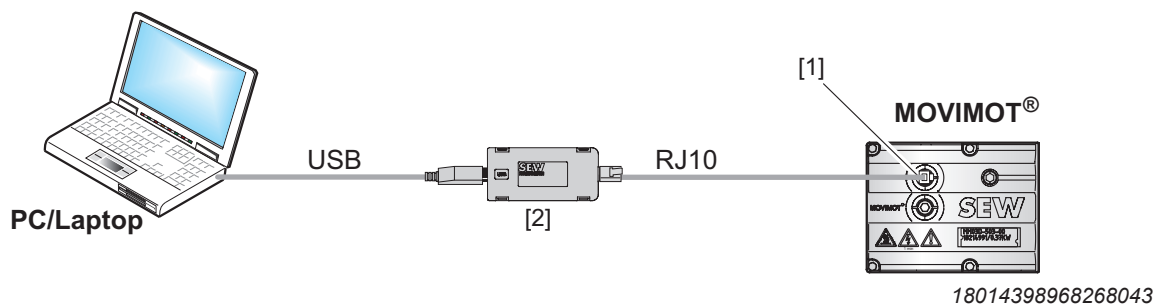
⚠ CAUTION! The ensured degree of protection will be lost if the screw plug of the X50 diagnostic interface is not installed. Damage to the MOVIMOT® drive.

If no screw plug is screwed into the diagnostic interface, you must ensure that no moisture and dust can penetrate the MOVIMOT® drive.

⚠ WARNING! Risk of burns due to hot surfaces of the MOVIMOT® drive (in particular the heat sink). Severe injury.

Wait for the MOVIMOT® drive to cool down sufficiently before touching it.

The diagnostic interface is connected to a commercially available PC/laptop with one of the following interface adapters [2] with a USB interface



[1] Diagnostic interface

[2] Interface adapter

Scope of delivery:

- Interface adapter
- Cables with RJ10 connector
- USB interface cable

The following interface adapters are available:

Designation	Part number
USM21A	28231449
USB11A	08248311

6 Startup

6.1 Overview

You can select one of the following modes for starting up MOVIMOT® drives:

- When you select **Easy mode**, the MOVIMOT® drive is started up quickly and easily using DIP switches S1, S2 and switches f2, t1.
- An extended scope of parameters is available for startup in **Expert mode**. You can use the MOVITOOLS® MotionStudio software or the DBG hand-held terminal to adjust the parameters to the application.

For more information on startup in expert mode, refer to chapter ""Expert" startup with parameter function" (→ 65).

6.2 General information concerning startup

INFORMATION



You must comply with the general safety notes in chapter "Safety notes" during start-up.



⚠ WARNING

Risk of crushing due to missing or defective protective covers.

Severe or fatal injuries.

- Install the protective covers of the plant according to the instructions, see the operating instructions of the gear unit.
- Never start the unit if the protective covers are not installed.



⚠ WARNING

Electric shock from capacitors that have not been fully discharged.

Severe or fatal injuries.

- Disconnect the inverter from the power. Observe the minimum switch-off time after disconnection from the supply system:
 - **1 minute**



⚠ WARNING

Device malfunction due to incorrect device setting.

Severe or fatal injuries.

- Comply with the startup instructions.
- The installation must be carried out by qualified personnel only.
- Always use the appropriate functional settings.



⚠ WARNING

Danger of burns due to hot surfaces of the device (e.g. the heat sink).

Severe injuries.

- Do not touch the device until it has cooled down sufficiently.

INFORMATION



To ensure fault-free operation, do not disconnect or connect power or signal lines during operation.

INFORMATION



- Remove status LED paint protection cap before startup. Remove paint protection film from the nameplates before startup.
- Observe a minimum switch-off time of 2 seconds for the K11 line contactor.

6.3 Easy startup

6.3.1 Requirements

The following prerequisites are required for startup:

- The MOVIMOT® drive must be installed correctly both mechanically and electrical-ly.
- Appropriate safety measures prevent the drives from starting up unintentionally.
- Appropriate safety measures must be taken to prevent risk of injury or damage to the machine.

6.3.2 Description of the control elements

Setpoint potentiometer f1

NOTICE

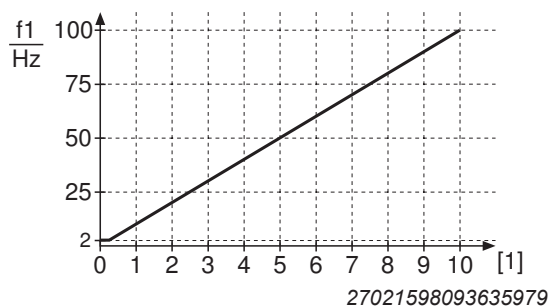
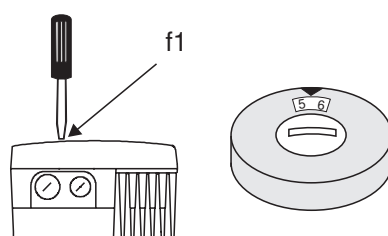
Loss of guaranteed degree of protection if the screw plugs on the f1 setpoint potentiometer and diagnostic interface are not installed or not installed correctly.

Damage to the MOVIMOT® inverter.

- After setting the setpoint, make sure the screw plug of the setpoint potentiometer has a seal and screw it in.

The potentiometer f1 has different functions depending on the operating mode:

- Binary control: Setting setpoint f1
(f1 selected via terminal f1/f2 X6:7,8 = "0")
- Control via RS485: Setting maximum frequency $f_{\max}$

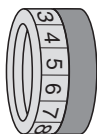


[1] Potentiometer setting

Switch f2

The switch f2 has different functions depending on the operating mode:

- Binary control: Setting setpoint f2
(f2 is selected via terminal f1/f2 X6:7,8 = "1")
- Control via RS485: Minimum frequency setting $f_{\min}$



Switch f2											
Detent setting	0	1	2	3	4	5	6	7	8	9	10
Setpoint f2 Hz	5	7	10	15	20	25	35	50	60	70	100
Minimum frequency Hz	2	5	7	10	12	15	20	25	30	35	40

Switch t1

Use switch t1 to set the acceleration of the MOVIMOT® drive. The ramp time is based on a setpoint step change of 1500 min⁻¹ (50 Hz).



Switch t1											
Detent position	0	1	2	3	4	5	6	7	8	9	10
Ramp time t1 s	0.1	0.2	0.3	0.5	0.7	1	2	3	5	7	10

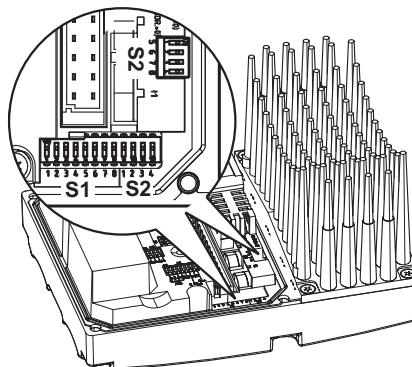
DIP switches S1 and S2

NOTICE

Damage to the DIP switches caused by unsuitable tools.

Damage to the DIP switches.

- Set the DIP switches only using suitable tools, such as a slotted screwdriver with a blade width of ≤ 3 mm.
- The force used for setting the DIP switches must not exceed 5 N.



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DIP switch S1:

S1	1	2	3	4	5	6	7	8
Meaning	Binary coding RS485 unit address				Motor protection	Motor performance level	PWM frequency	No load damping
	2 ⁰	2 ¹	2 ²	2 ³				
ON	1	1	1	1	Off	Motor one stage smaller	Variable (16, 8, 4 kHz)	On
OFF	0	0	0	0	On	Motor adjusted	4 kHz	Off

DIP switch S2:

S2	1	2	3	4	5	6	7	8
Meaning	Brake type	Brake released without enable	Operating mode	Speed monitoring	Binary encoding additional functions			
					2 ⁰	2 ¹	2 ²	2 ³
ON	Optional brake	On	V/f	On	1	1	1	1
OFF	Standard brake	Off	VFC	Off	0	0	0	0

6.3.3 Description of the DIP switches S1

DIP switches S1/1 – S1/4

Selecting the RS485 address of the MOVIMOT® drive via binary coding

Decimal address	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
S1/1	–	X	–	X	–	X	–	X	–	X	–	X	–	X	–	X
S1/2	–	–	X	X	–	–	X	X	–	–	X	X	–	–	X	X
S1/3	–	–	–	–	X	X	X	X	–	–	–	–	X	X	X	X
S1/4	–	–	–	–	–	–	–	–	X	X	X	X	X	X	X	X

☒ = ON

☐ = OFF

Set the following addresses depending on how the MOVIMOT® inverter is controlled:

Control	RS485 address
Binary control	0
Via keypad (MLG..A, MBG..A)	1
Via RS485 master	1 – 15
Via MWF11A setpoint converter	1 – 15

DIP switch S1/5

Motor protection switched on / switched off

When the MOVIMOT® inverter is installed (close to) the motor, the motor protection must be deactivated.

To ensure motor protection, a TH (bimetallic thermostat) must be used. The TH opens the sensor circuit when the nominal response temperature is reached (see field distributor manual).

DIP switch S1/6

Lower motor power rating

- When activated, the DIP switch S1/6 allows the MOVIMOT® inverter to be assigned to a motor with a lower motor power rating. The nominal device power remains unchanged.
- When using a motor with a lower power rating, the MOVIMOT® inverter is a power level higher from the motor's perspective. The overload capacity of the drive may be increased as a result. For a short time, a larger current can be impressed, which results in higher torques.
- The aim of the DIP switch S1/6 is to achieve short-term utilization of the motor's peak torque. The current limit of the respective device is always the same regardless of the switch position. The motor protection function is adjusted depending on the switch position.
- Stall protection for the motor is not possible in this operating mode at S1/6 = "ON".
- The necessary setting for the DIP switch S1/6 depends on the motor type and therefore also on the drive ID module in the MOVIMOT® inverter.

First check the drive ID module type in the MOVIMOT® inverter. Set the DIP switch S1/6 according to the following table.

Motor with operating point 400 V/50 Hz

Applies to MOVIMOT® with the following drive ID modules:

Drive ID module			Motor	
Identification	Identification color	Part number	Line voltage V	Line frequency Hz
DR2S/400/50	Light gray/white striped	28249720	230/400	50
DRS/400/50	White	18214371	230/400	50
DRE/400/50	Orange	18214398	230/400	50
DRP/230/400	Brown	18217907	230/400	50
DRN/400/50	Light blue	28222040	230/400	50
DRU/400/50	Dark brown/white striped	28291646	230/400	50

Setting of DIP switch S1/6:

Power kW	Motor type	MOVIMOT® MM..D-503-00 inverter			
		Motor in Δ -connection		Motor in Δ -connection	
		S1/6 = OFF	S1/6 = ON	S1/6 = OFF	S1/6 = ON
0.25	DR2S63M4/.. DR63L4/.. DRE80S4/.. DRN71MS4	—	MM03D..	MM03D..	MM05D..
0.37	DR2S71MS4/.. DRS71S4/.. DRE80S4/.. DRN71M4	MM03D..	MM05D..	MM05D..	MM07D..
0.55	DR2S71M4/.. DRS71M4/.. DRE80M4/.. DRN80MK4	MM05D..	MM07D..	MM07D..	MM11D..
0.75	DR2S80MK4/.. DRS80S4/.. DRE80M4/.. DRP90M4/.. DRN80M4/.. DRU90S4/..	MM07D..	MM11D..	MM11D..	MM15D..
1.1	DR2S80M4/.. DRS80M4/.. DRE90M4/.. DRP90L4/.. DRN90S4/.. DRU100LSR4/..	MM11D..	MM15D..	MM15D..	MM22D..
1.5	DR2S90S4/.. DRS90M4/.. DRE90L4/.. DRP100M4/.. DRN90L4/.. DRU100LS4/..	MM15D..	MM22D..	MM22D..	MM30D..
2.2	DR2S90L4/.. DRS90L4/.. DRE100M4/.. DRP100L4/.. DRN100LS4/.. DRU100L4/..	MM22D..	MM30D..	MM30D..	MM40D..
3.0	DR2S100LS4/.. DRS100M4/.. DRE100LC4/.. DRP112M4/.. DRN100L4/.. DRU112M4/..	MM30D..	MM40D..	MM40D..	—
4.0	DR2S100L4/.. DRS100LC4/.. DRE132S4/.. DRN112M4/.. DRU132S4/..	MM40D..	—	—	—

Motor with operating point 460 V/60 Hz

Applies to MOVIMOT® with the following drive ID modules:

Drive ID module			Motor	
Identification	Identification color	Part number	Line voltage V	Line frequency Hz
DR2S/460/60	Yellow/white striped	28249739	266/460	60
DRS/460/60	Yellow	18214401	266/460	60
DRE/460/60	Green	18214428	266/460	60
DRP/266/460	Beige	18217915	266/460	60
DRN/460/60	Blue/white striped	28241819	266/460	60
DRU/460/60	Light brown/white striped	28312406	266/460	60

Setting of DIP switch S1/6:

Power kW	Motor type	MOVIMOT® MM..D-503-00 inverter			
		Motor in Δ -connection		Motor in Δ -connection	
		S1/6 = OFF	S1/6 = ON	S1/6 = OFF	S1/6 = ON
0.25	DR2S63M4/.. DRN71MS4/..	—	MM03D..	MM03D..	MM05D..
0.37	DR2S71MS4/.. DRS71S4/.. DRN71M4/..	MM03D..	MM05D..	MM05D..	MM07D..
0.55	DR2S71M4/.. DRS71M4/.. DRN80MK4/..	MM05D..	MM07D..	MM07D..	MM11D..
0.75	DR2S80MK4/.. DRS80S4/.. DRE80M4/.. DRP90M4/.. DRN80M4/.. DRU90S4/..	MM07D..	MM11D..	MM11D..	MM15D..
1.1	DR2S80M4/.. DRS80M4/.. DRE90M4/.. DRP90L4/.. DRN90S4/.. DRU90L4/..	MM11D..	MM15D..	MM15D..	MM22D..
1.5	DR2S90S4/.. DRS90M4/.. DRE90L4/.. DRP90L4/.. DRN90L4/.. DRU100LS4/..	MM15D..	MM22D..	MM22D..	MM30D..
2.2	DR2S90L4/.. DRS90L4/.. DRE100L4/.. DRP112M4/.. DRN100L4/.. DRU112MR4/..	MM22D..	MM30D..	MM30D..	MM40D..
3.0	DRU112M4/..	MM30D..	MM40D..	—	—
3.7	DR2S100LS4/.. DRS100M4/.. DRE100LC4/.. DRP132S4/.. DRN100L4/..	MM30D..	MM40D..	—	—
4.0	DR2S100L4/.. DRS100LC4/.. DRE132S4/.. DRN112M4/.. DRU132S4/..	MM40D..	—	—	—

Motor with 50/60 Hz voltage range

Applies to MOVIMOT® with the following drive ID modules:

Drive ID module			Motor	
Identification	Identification color	Part number	Line voltage V	Line frequency Hz
DRS/DRE/50/60	Violet	18214444	220 – 240/ 380 – 415	50
			254 – 277/ 440 – 480	60
DRS/DRN/50/60	Pastel green	28241827	220 – 230/ 380 – 400	50
			266/460	60
DRN/50/60	Violet/white striped	28249747	220 – 230/ 380 – 400	50
			266/460	60

Setting of DIP switch S1/6:

Power rating kW	Motor type	MOVIMOT® MM..D-503-00 inverter			
		Motor in Δ connection		Motor in Δ connection	
		S1/6 = OFF	S1/6 = ON	S1/6 = OFF	S1/6 = ON
0.25	DR63L4/.. DRN71MS4/..	–	MM03D..	MM03D..	MM05D..
0.37	DRS71S4/.. DRN71M4/..	MM03D..	MM05D..	MM05D..	MM07D..
0.55	DRS71M4/.. DRN80MK4/..	MM05D..	MM07D..	MM07D..	MM11D..
0.75	DRE80M4/.. DRN80M4/..	MM07D..	MM11D..	MM11D..	MM15D..
1.1	DRE90M4/.. DRN90S4/..	MM11D..	MM15D..	MM15D..	MM22D..
1.5	DRE90L4/.. DRN90L4/..	MM15D..	MM22D..	MM22D..	MM30D..
2.2	DRE100L4/.. DRN100LM4/..	MM22D..	MM30D..	MM30D..	MM40D..
3.0	DRE100LC4/.. DRN100L4/..	MM30D..	MM40D..	MM40D..	–
4.0	DRE132S4/.. DRN112M4/..	MM40D..	–	–	–

Motor with operating point 380 V/60 Hz (ABNT regulation for Brazil)

Applies to MOVIMOT® with the following drive ID modules:

Drive ID module			Motor	
Identification	Identification color	Part number	Line voltage V	Line frequency Hz
DRS/DRE/380/60	Red	18234933	220/380	60
DRN/380/60	Red/white striped	28240227	220/380	60

Setting of DIP switch S1/6:

Power kW	Motor type	MOVIMOT® MM..D-503-00 inverter			
		Motor in Δ -connection		Motor in Δ -connection	
		S1/6 = OFF	S1/6 = ON	S1/6 = OFF	S1/6 = ON
0.25	DRN71MS4/..	–	MM03D..	MM03D..	MM05D..
0.37	DRS71S4/.. DRN71M4/..	MM03D..	MM05D..	MM05D..	MM07D..
0.55	DRS71M4/.. DRN80MK4/..	MM05D..	MM07D..	MM07D..	MM11D..
0.75	DRE80S4/.. DRN80M4/..	MM07D..	MM11D..	MM11D..	MM15D..
1.1	DRE80M4/.. DRN90S4/..	MM11D..	MM15D..	MM15D..	MM22D..
1.5	DRE90M4/.. DRN90L4/..	MM15D..	MM22D..	MM22D..	MM30D..
2.2	DRE90L4/.. DRN100LM4/..	MM22D..	MM30D..	MM30D..	MM40D..
3.0	DRE100M4/.. DRN100L4/..	MM30D..	MM40D..	MM40D..	–
4.0	DRE100L4/.. DRN100L4/..	MM40D..	–	–	–

Motor with operating point 400 V/50 Hz and LSPM technology

Applies to MOVIMOT® with the following drive ID module:

Drive ID module			Motor	
Identification	Identification color	Part number	Line voltage V	Line frequency Hz
DRU...J/400/50	Gray	28203194	230/400	50

Setting of DIP switch S1/6:

Power kW	Motor type	MOVIMOT® MM..D-503-00 inverter			
		Motor in Δ -connection		Motor in Δ -connection	
		S1/6 = OFF	S1/6 = ON	S1/6 = OFF	S1/6 = ON
0.25	DRU71SJ/..	–	MM03D..	MM03D..	MM05D..
0.37	DRU71MJ4/..	MM03D..	MM05D..	MM05D..	MM07D..
0.55	DRU80SJ4/..	MM05D..	MM07D..	MM07D..	MM11D..
0.75	DRU80MJ4/..	MM07D..	MM11D..	MM11D..	MM15D..
1.1	DRU90MJ4/..	MM11D..	MM15D..	MM15D..	MM22D..
1.5	DRU90LJ4/..	MM15D..	MM22D..	MM22D..	MM30D..
2.2	DRU100MJ4/..	MM22D..	MM30D..	MM30D..	MM40D..
3.0	DRU100LJ4/..	MM30D..	MM40D..	MM40D..	–

DIP switch S1/7

Setting the maximum PWM frequency

- When DIP switch S1/7 is set to "OFF", the MOVIMOT® works with the PWM frequency of 4 kHz.
- When DIP switch S1/7 is set to "ON", the MOVIMOT® works with the PWM frequency of 16 kHz (low-noise). MOVIMOT® incrementally switches back to lower clock frequencies depending on the heat sink temperature and the load on the inverter.

DIP switch S1/8

No-load vibration damping

When setting DIP switch S1/8 to "ON", this function reduces resonance vibrations when in no-load operation.

6.3.4 Description of the DIP switches S2

DIP switch S2/1

Brake type

- When using the standard brake, the DIP switch S2/1 must be set to "OFF".
- When using the optional brake, the DIP switch S2/1 must be set to "ON".

Motor				Standard brake [type] S2/1 = OFF	Optional brake [type] S2/1 = ON
400 V/50 Hz 460 V/60 Hz 50/60 Hz voltage range		380 V/60 Hz ABNT Brazil	400 V/50 Hz LSPM Technology		
DR63L4				BR03	–
DR2S63M4				BE03	BE03
	DRN71MS4	DRN71MS4		BE03	BE05
DRS71S4 DRE80S4	DR2S71MS4 DRN71M4 DRN71MK4	DRS71S4 DRN71M4	DRE71SJ4 DRU71SJ4 DRU71MJ4	BE05	BE1
DRS71M4 DRS80S4 DRE80M4	DR2S71M4 DR2S80MK4 DRN80MK4 DRN80M4	DRS71M4 DRE80S4 DRN80MK4 DRN80M4	DRE71MJ4 DRU80SJ4	BE1	BE05
DRP90M4			DRU80MJ4	BE1	BE2
DRS80M4 DRE90M4 DRP90L4	DR2S80M4 DRN90S4	DRE80M4 DRN90S4	DRE80SJ4 DRU90MJ4	BE2	BE1
DRS90M4 DRE90L4	DR2S90S4 DRN90L4	DRE90M4 DRN90L4	DRE80MJ4	BE2	BE1
DRP100M4			DRU90LJ4	BE2	BE5
DRS90L4 DRE100M4 DRE100L4 DRP100L4	DR2S90L4 DRN100LS4	DRE90L4	DRE90MJ4 DRE90LJ4 DRU100MJ4	BE5	BE2
DRS100M4 DRS100L4 DRS100LC4 DRE100LC4	DR2S100LS4 DR2S100L4 DRN100L4 DRN100LM4	DRE100M4 DRE100L4 DRN100L4 DRN100LM4	DRE100MJ4 DRU100LJ4	BE5	BE2
DRP112M4 DRE132S4 DRP112S4	DRN112M4			BE5	BE11
DRU90S	DRU90S4			BE1	BE05
DRU100LSR4	DRU90L4			BE2	BE1
DRU100LS4	DRU100LS4			BE2	BE1
DRU100L4				BE5	BE2
DRU112M4	DRU112MR4 DRU112M4			BE5	BE11
DRU132S4	DRU132S4			BE5	BE11

Preferred brake voltage

MOVIMOT® type (inverter)	Preferred Brake voltage
MOVIMOT® MM..D-503, size 1 (MM03.. – MM15..)	230 V
MOVIMOT® MM..D-503, size 2 (MM22.. – MM40..)	120 V
MOVIMOT® MM..D-233, sizes 1 and 2 (MM03.. – MM22..)	

DIP switch S2/2

Brake release without enable

When setting DIP switch S2/2 to "ON", it is possible to release the brake even if there is no drive enabled.

Binary control functions

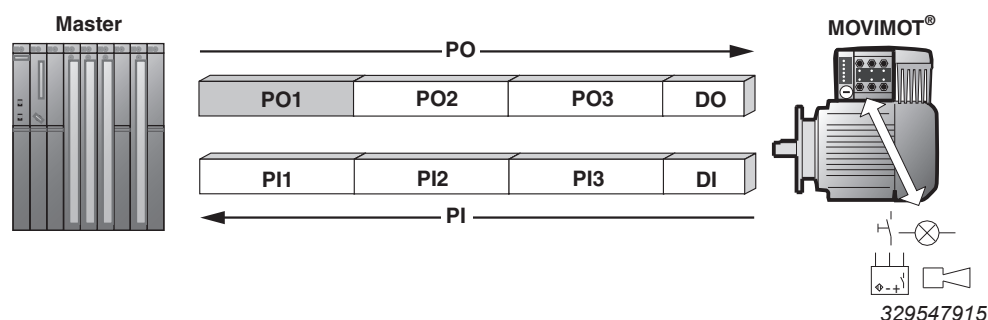
In binary control, you can release the brake by setting the signal at terminal f1/f2 X6:7,8 subject to the following preconditions:

Terminal state			Enable status	Fault status	Brake function
R ↻ X6:11,12	L ↻ X6:9,10	f1/f2 X6:7,8			
"1" "0"	"0" "1"	"0"	Device enabled	No device fault	The MOVIMOT® inverter controls the brake. Setpoint f1
"1" "0"	"0" "1"	"1"	Device enabled	No device fault	The MOVIMOT® inverter controls the brake. Setpoint f2
"1" "0"	"1" "0"	"0"	Unit not enabled	No device fault	Brake is applied.
"1"	"1"	"1"	Unit not enabled	No device fault	Brake is applied.
"0"	"0"	"1"	Device not enabled	No device fault	Brake is released for manual movement. ¹⁾
All states possible			Unit not enabled	Device fault	Brake is applied.

1) In "Expert" mode the parameter P600 (terminal configuration) must be set to "0" (default) => "setpoint changeover, CCW/stop, CW/stop".

Functions with control via RS485

With control via RS485, the brake is released via the control word:



PO = Process output data

PO1 = Control word

PO2 = Speed [%]

PO3 = Ramp

DO = Binary outputs

PI = Process input data

PI1 = Status word 1

PI2 = Output current

PI3 = Status word 2

DI = Binary inputs

By setting bit 8 in the control word, the brake can be released if the following conditions are met:

								Basic control block							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Control word															
Not assigned ¹⁾						Bit "9"	Bit "8"	Not assigned ¹⁾	"1" = Reset	Not assigned ¹⁾			"1 1 0" = Enable otherwise stop		
								Virtual terminals for releasing the brake without drive enable Virtual terminals for applying the brake and inhibiting the output stage Control command "Stop"							

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1) Recommendation for all bits that are not assigned = "0"

Enable state	Fault status	Status of bit 8 in control word	Brake function
Device enabled	No unit error/ no communication timeout	"0"	The MOVIMOT® inverter controls the brake.
Device enabled	No unit error/ no communication timeout	"1"	The MOVIMOT® inverter controls the brake.
Unit not enabled	No unit error/ no communication timeout	"0"	Brake is applied.
Unit not enabled	No unit error/ no communication timeout	"1"	Brake is released for manual movement.
Unit not enabled	Unit error/ communication timeout	"1" or "0"	Brake is applied.

Setpoint selection for binary control

Setpoint selection for binary control depending on the status of terminal f1/f2 X6: 7,8:

Enable status	Terminal f1/f2 X6:7,8	Active setpoint
Unit enabled	Terminal f1/f2 X6:7,8 = "0"	Setpoint potentiometer f1 active
Unit enabled	Terminal f1/f2 X6:7,8 = "1"	Setpoint potentiometer f2 active

Behavior if unit not ready

If the unit is not ready, the brake is always applied irrespective of the status of terminal f1/f2 X6:7,8 or bit 8 in the control word.

LED display

The status LED flashes periodically at a fast rate ($t_{on} : t_{off} = 100 \text{ ms} : 300 \text{ ms}$) if the brake has been released for manual movement. This applies both for binary control and for control via RS485.

DIP switch S2/3

Operating mode

- DIP switch S2/3 = "OFF": VFC operation for 4-pole motors
- DIP switch S2/3 = "ON": V/f operation reserved for special cases

DIP switch S2/4

Speed monitoring

Speed monitoring (S2/4 = "ON") protects the drive when it is blocked.

If the drive is operated at the current limit for longer than 1 second when speed monitoring is active (S2/4 = "ON"), the MOVIMOT® inverter trips the speed monitoring fault. The status LED of the MOVIMOT® inverter signals the error by slowly flashing red (error code 08). This error only occurs if the current limit is reached continuously for the duration of the delay time.

DIP switches S2/5 – S2/8

Additional functions

You can activate additional functions by binary coding of the DIP switches S2/5 to S2/8. For a description of the additional functions, refer to the product manual. Activate the possible additional functions as follows:

Decimal value	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
S2/5	–	X	–	X	–	X	–	X	–	X	–	X	–	X	–	X
S2/6	–	–	X	X	–	–	X	X	–	–	X	X	–	–	X	X
S2/7	–	–	–	–	X	X	X	X	–	–	–	–	X	X	X	X
S2/8	–	–	–	–	–	–	–	–	X	X	X	X	X	X	X	X

X = ON

– = OFF

6.3.5 Startup with binary control



▲ WARNING

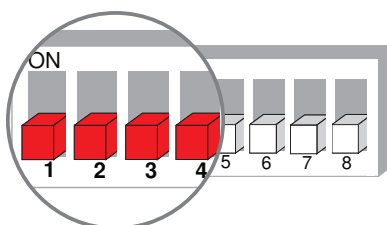
Electric shock from capacitors that have not been fully discharged.

Severe or fatal injuries.

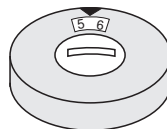
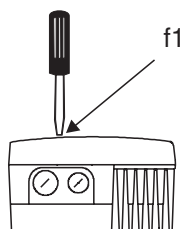
- Disconnect the inverter from the power. Observe the minimum switch-off time after disconnection from the supply system:

– **1 minute**

1. Remove the MOVIMOT® inverter from the connection box.
2. Check whether the MOVIMOT® drive is installed correctly both mechanically and electrically.
⇒ Refer to chapters "Mechanical Installation" and "Electrical Installation".
3. Make sure that the DIP switches S1/1 – S1/4 are set to "OFF" (=address 0). This means that MOVIMOT® is controlled via the terminals using binary signals.



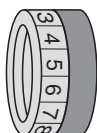
4. Set the first speed at setpoint potentiometer f1 (active when terminals f1/f2 X6:7,8 = "0"), factory setting: about 50 Hz (1500 min⁻¹).



[1] Potentiometer setting

5. **NOTICE!** Loss of the specified degree of protection if the screw plugs on the f1 setpoint potentiometer and the X50 diagnostic interface are not installed or not installed correctly. Damage to the MOVIMOT® inverter.
Reinstall the screw plug of the setpoint potentiometer with the seal.

6. Set the second speed at switch f2 (active when terminals f1/f2 X6,7,8 = "1").



f2 switch:

Detent position	0	1	2	3	4	5	6	7	8	9	10
Setpoint f2 [Hz]	5	7	10	15	20	25	35	50	60	70	100

INFORMATION



During operation, the 1st speed can be continuously adjusted using the externally accessible setpoint potentiometer f1.

The speeds f1 and f2 can be set independently of each other.

7. Set the ramp time using switch t1.

⇒ The ramp time is based on a setpoint step change of 1500 min⁻¹ (50 Hz).



t1 switch:

Detent position	0	1	2	3	4	5	6	7	8	9	10
Setpoint f2 [Hz]	0.1	0.2	0.3	0.5	0.7	1	2	3	5	7	10

8. Place the MOVIMOT® inverter onto the connection box and screw it in place.

9. Switch on the DC 24 V control voltage and the line voltage.

Inverter behavior depending on terminal signal level

The following table shows the behavior of the MOVIMOT® inverter depending on the signal level at the control terminals:

Inverter behavior	Terminal signal level					Status LED
	Supply system	24V	f1/f2	CW/stop	CCW/stop	
	X1:L1 – L3	X6:1,2,3	X6:7,8	X6:11,12	X6:9,10	
Inverter off	0	0	X	X	X	Off
Inverter off	1	0	X	X	X	Off
Stop, supply missing	0	1	X	X	X	Flashes yellow
Stop	1	1	X	0	0	Yellow
CW rotation at f1	1	1	0	1	0	Green
CCW rotation at f1	1	1	0	0	1	Green
CW rotation at f2	1	1	1	1	0	Green
CCW rotation at f2	1	1	1	0	1	Green
Stop	1	1	x	1	1	Yellow

Key:

0 = No voltage

1 = Voltage

X = Any

6.3.6 Additional information for installation close to the motor

When the MOVIMOT® inverter is installed close to the motor, observe the following notes:

Checking the connection type for the connected motor

Make sure that the selected connection type of the MOVIMOT® inverter corresponds to that of the connected motor according to the figure below.



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For brakemotors, no brake rectifier must be installed in the motor terminal box!

Motor with Option /MI

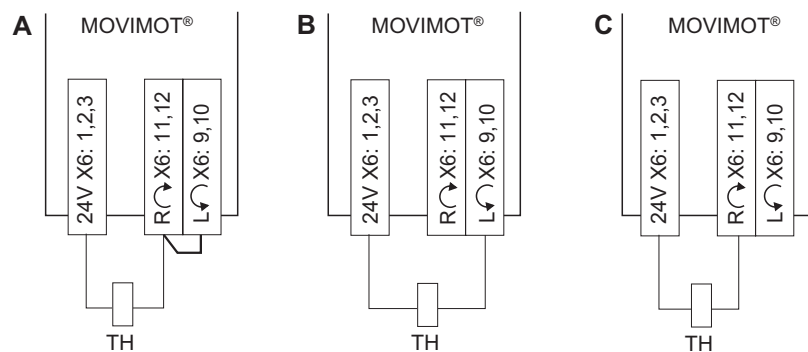
Make sure a drive ID module suitable to the energy efficiency class of the motor is plugged into the MOVIMOT® inverter.

When a motor/brakemotor (without MOVIMOT® inverter) is ordered with the option /MI, the drive ID module can be found in the terminal box of the motor.

Motor protection and direction of rotation enable

The connected motor must be equipped with a TH.

- For control via RS485, the TH must be wired as follows:

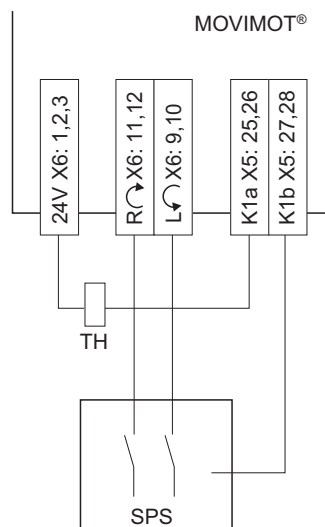


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- [A] Both directions of rotation are enabled.
- [B] Only **CCW** direction of rotation is enabled.
- [C] Only **CW** direction of rotation is enabled.

- For control via binary signals, SEW-EURODRIVE recommends that you connect the TH in series with the "Ready signal" relay (see the following figure).
 - The ready signal must be monitored by an external controller.

- As soon as the ready signal is no longer present, the drive must be switched off (terminals R ↻ X6:11,12 and L ↻ X6:9,10 = "0").



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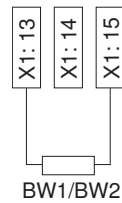
DIP switch

When the MOVIMOT® inverter is installed close to the motor, the DIP switch S1/5 must be set to "ON" instead of the factory setting:

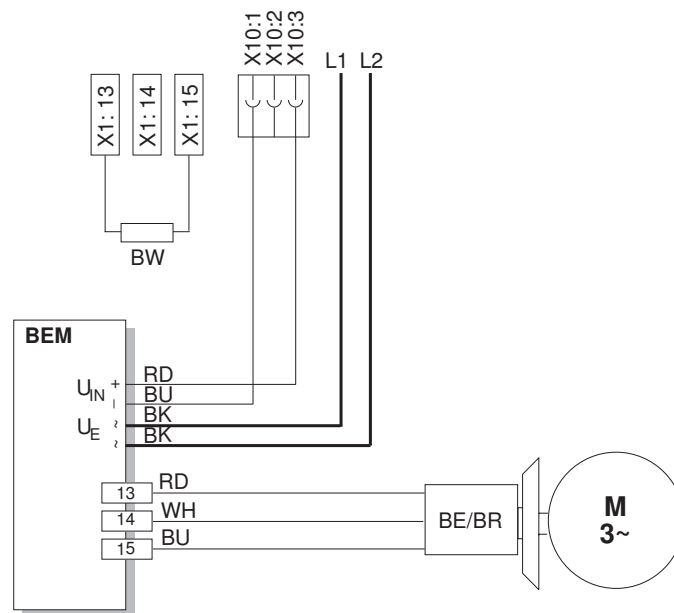
S1	1	2	3	4	5	6	7	8
Meaning	Binary coding RS485 unit address				Motor pro- tection	Motor power rating	PWM frequency	No-load damping
	2 ⁰	2 ¹	2 ²	2 ³				
ON	1	1	1	1	Off	Motor one stage smaller	Variable (16, 8, 4 kHz)	On
OFF	0	0	0	0	On	Adapted	4 kHz	Off

Braking resistor

- For **motors without brake**, a braking resistor must be connected in the MOVIMOT® connection box.



- For **brake motors without BEM option**, a braking resistor must not be connected to the MOVIMOT®.
- For **brakemotors with BEM option** and external braking resistor, the external braking resistor BW and the brake must be connected as follows.



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6.4 "Easy" startup with RS485 interface

6.4.1 Requirements

The following prerequisites are required for startup:

- The MOVIMOT® drive must be installed correctly both mechanically and electrically.
- Appropriate safety measures prevent the drives from starting up unintentionally.
- Appropriate safety measures must be taken to prevent risk of injury or damage to the machine.

6.4.2 Startup procedure



⚠ WARNING

Electric shock caused by dangerous voltages in the connection box. Dangerous voltages may still be present for up to 1 minute after disconnection from the power supply.

Severe or fatal injuries.

- De-energize the unit using a suitable disconnection device.
- Protect it against unintentional reconnection to the voltage supply.
- Wait for at least 1 minute before disassembling the device.

1. Remove the MOVIMOT® inverter from the connection box.
2. Check whether the MOVIMOT® drive is installed correctly both mechanically and electrically.
 - ⇒ Refer to chapters "Mechanical Installation" and "Electrical Installation".
3. Set the correct RS485 address of the drive at DIP switches S1/1 – S1/4.
 - ⇒ In conjunction with fieldbus interfaces MF../MQ., always set address "1".

Decimal address	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
S1/1	–	X	–	X	–	X	–	X	–	X	–	X	–	X	–	X
S1/2	–	–	X	X	–	–	X	X	–	–	X	X	–	–	X	X
S1/3	–	–	–	–	X	X	X	X	–	–	–	–	X	X	X	X
S1/4	–	–	–	–	–	–	–	–	X	X	X	X	X	X	X	X

☒ = ON

☐ = OFF

4. Set the minimum frequency $f_{\min}$ using the switch f2.



f2 switch:											
Detent position	0	1	2	3	4	5	6	7	8	9	10
Minimum frequency $f_{\min}$ [Hz]	2	5	7	10	12	15	20	25	30	35	40

5. If the ramp time is not specified via the fieldbus, set the ramp time at switch t1.

⇒ The ramp time is based on a setpoint step change of 1500 min^{-1} (50 Hz).



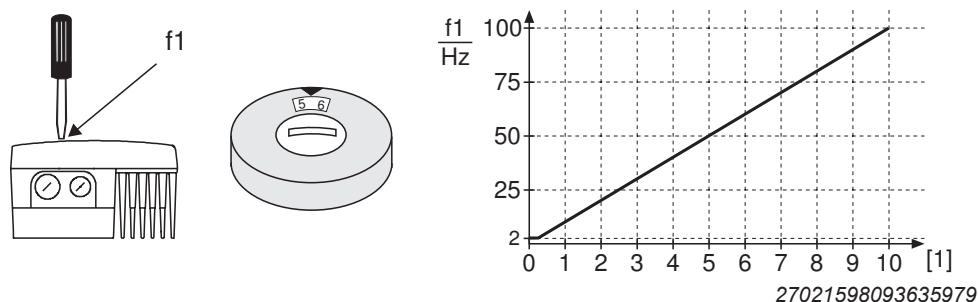
t1 switch:											
Detent position	0	1	2	3	4	5	6	7	8	9	10
Ramp time t1 [s]	0.1	0.2	0.3	0.5	0.7	1	2	3	5	7	10

6. Check to see if the required direction of rotation has been enabled.

CW/stop	CCW/stop	Meaning
Activated	Activated	Both directions of rotation are enabled.
Activated	Not activated	- Only CW rotation is enabled. - Setpoint input for CCW rotation will stop the drive.
Not activated	Activated	- Only CCW rotation is enabled. - Setpoint input for CW rotation will stop the drive.
Not activated	Not activated	The device is inhibited or the drive is stopped.

7. Place the MOVIMOT® inverter onto the connection box and screw it in place.

8. Set the maximum speed required using setpoint potentiometer f1.



[1] Potentiometer setting

9. **NOTICE!** Loss of the specified degree of protection if the screw plugs on the f1 setpoint potentiometer and the X50 diagnostic interface are not installed or not installed correctly. Damage to the MOVIMOT® inverter.
Make sure the screw plug of the setpoint potentiometer has a seal and screw it in.

10. Switch on the DC 24 V control voltage and the line voltage.

For further information on the function in conjunction with the RS485 master, refer to chapter "Function with RS-485 master".

For information on the function in connection with fieldbus interfaces, refer to the corresponding fieldbus manuals.

6.5 Expert startup with parameter function

INFORMATION



Startup in Expert mode is only required if you want to set parameters during startup.

Startup in Expert mode is only possible if:

- No additional function is activated (DIP switch S2/5 - S2/8 is set to "OFF")
- The Drive ID module is plugged in
- And parameter *P805 Startup mode* is set to "Expert mode".

6.5.1 Requirements

The following prerequisites are required for startup:

- The MOVIMOT® drive must be installed correctly both mechanically and electrically.
- Appropriate safety measures prevent the drives from starting up unintentionally.
- Appropriate safety measures must be taken to prevent risk of injury or damage to the machine.

The following hardware must be present for startup:

- PC or laptop, see chapter "PC/laptop connection" (→ 42)

The following software must be installed on the PC or laptop for startup:

- MOVITOOLS® MotionStudio

6.5.2 MOVITOOLS® MotionStudio

The "MOVITOOLS® MotionStudio" software package is the SEW-EURODRIVE engineering tool that you can use to access all SEW-EURODRIVE drive units. For the MOVIMOT® inverter, you can use MOVITOOLS® MotionStudio to perform diagnostics with simple applications. For more demanding applications, you can use the simple wizards available to startup and configure the MOVIMOT® inverter. The scope function in MOVITOOLS® MotionStudio can be used for visualizing process values.

Install the latest software version of MOVITOOLS® MotionStudio on your PC/laptop.

MOVITOOLS® MotionStudio can communicate with the drive units using different communication and fieldbus systems.

The following section describes the most straightforward application, a connection between a PC/laptop and a MOVIMOT® inverter via the diagnostics interface X50 (point-to-point connection).

Integrating MOVIMOT® into MOVITOOLS® MotionStudio

INFORMATION



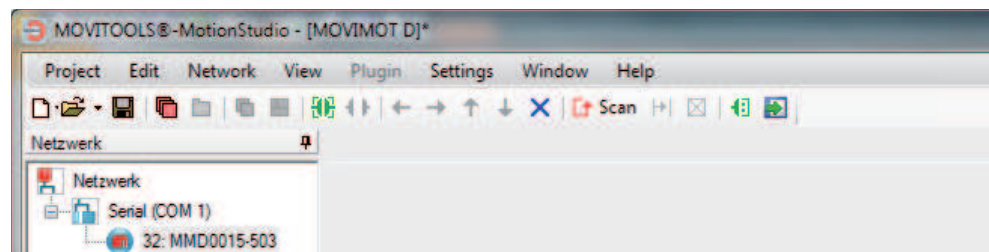
For a detailed description of the following steps please refer to the comprehensive online help in MOVITOOLS® MotionStudio.

1. Start MOVITOOLS® MotionStudio.
2. Create a project and a network.
3. Configure the communication channel on the PC/laptop.
4. Make sure that the 24 V supply of the MOVIMOT® inverter is connected.
5. Perform an online scan.
 - ⇒ Check the set scanning range in MOVITOOLS® MotionStudio.

INFORMATION



- The diagnostic interface has fixed **address 32**. Adapt the scanning range in MOVITOOLS® MotionStudio so that address 32 is also scanned.
 - The baud rate is 9.6 kBaud.
 - The online scan may take a longer time.
6. MOVIMOT® is displayed in MOVITOOLS® MotionStudio as shown in the example below:



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7. By right-clicking "32: MMD0015-503", tools for startup and diagnostics of MOVIMOT® are available in the context menu.

6.5.3 Startup and function expansion with individual parameters

The basic functionality of the MOVIMOT® drive can be expanded by using individual parameters.

INFORMATION



Startup in "Expert" mode is only possible if:

- No additional function is activated (DIP switch S2/5 - S2/8 is set to "OFF")
- The Drive ID module is plugged in
- And parameter *P805 Startup mode* = "Expert mode" is set.

1. Perform startup in "Easy" mode.
 - ⇒ See chapter "Easy startup" (→ 45)
2. Connect the PC/laptop or the DBG keypad to the MOVIMOT® inverter.
 - ⇒ See chapter "PC/laptop connection" (→ 42) or chapter "DBG keypad connection".
3. Connect the 24 V supply of the MOVIMOT® inverter.
4. When using a PC/laptop, start MOVITOOLS® MotionStudio and integrate the MOVIMOT® inverter.
 - ⇒ See chapter "Integrating MOVIMOT® into MOVITOOLS® MotionStudio" (→ 66)
5. Set parameter *P805 Startup mode* to "Expert".
6. Specify the parameters which you want to change.
7. Check whether these parameters depend on the mechanical control elements.
 - ⇒ See chapter "Integrating MOVIMOT® into MOVITOOLS® MotionStudio" (→ 66)
8. Deactivate the respective control elements by adjusting the bit-coded selection box of parameter *P102*.
 - ⇒ See chapter "Parameter 102"
9. Change the set parameters.
 - ⇒ For information on parameter setting with the DBG keypad, refer to chapter "Parameter mode".
10. Check the functionality of the MOVIMOT® drive.
 - Optimize the parameters if necessary.
11. Disconnect the PC/laptop or the DBG keypad from the MOVIMOT® inverter.
12. **NOTICE!** Loss of the specified degree of protection if the screw plugs on the f1 setpoint potentiometer and the X50 diagnostic interface are not installed or not installed correctly. Damage to the MOVIMOT® inverter.
Reinstall the screw plug of the setpoint potentiometer with the seal.

6.5.4 Startup by transferring the parameter set

You can startup several MOVIMOT® drives with the same parameter set.

Parameters can only be transferred between two identical MOVIMOT® drives (same inverter and same motor).

INFORMATION



The parameter set can only be transferred if:

- No additional function is activated (DIP switch S2/5 - S2/8 is set to "OFF")
- The Drive ID module is plugged in
- The parameter set of one MOVIMOT® reference unit already exists.

Transferring the parameter set using MOVITOOLS® or the DBG keypad

1. Remove the MOVIMOT® inverter from the connection box.
2. Check the connection of the MOVIMOT® inverter.
 - ⇒ See chapter "Electrical installation".
3. Set all mechanical control elements identical to the reference device.
4. Place the MOVIMOT® inverter onto the connection box and screw it in place.
5. Connect the PC/laptop or the DBG keypad to the MOVIMOT® inverter.
 - ⇒ See chapter "PC/laptop connection" (→ 42) or chapter "Connection of DBG keypad (in preparation)".
6. Connect the 24 V supply of the MOVIMOT® inverter.
7. When using a PC/laptop, start MOVITOOLS® MotionStudio and integrate the MOVIMOT® inverter in MOVITOOLS®.
 - ⇒ See chapter "Integrating MOVIMOT® into MOVITOOLS® MotionStudio" (→ 66).
8. Transfer the entire parameter set of the MOVIMOT® reference unit to the MOVIMOT® inverter.
 - ⇒ For information on transferring the parameter set with the DBG keypad, refer to chapter "Copy function of the DBG keypad".
9. Check the functionality of the MOVIMOT® drive.
10. Disconnect the PC/laptop or the DBG keypad from the MOVIMOT® inverter.
11. **NOTICE!** Loss of the specified degree of protection if the screw plugs on the f1 setpoint potentiometer and the X50 diagnostic interface are not installed or not installed correctly. Damage to the MOVIMOT® inverter.
Make sure the screw plug of the setpoint potentiometer has a seal and screw it in.

7 Operation

7.1 Operating notes



⚠ WARNING

Electric shock due to dangerous voltages at connections, cables, and motor terminals.

When the device is switched on, dangerous voltages are present at the connections as well as at any connected cables and motor terminals. This even applies when the device is inhibited and the motor is in an idle state.

Severe or fatal injuries.

- Avoid switching under load.
- Before performing any work on the device, disconnect it from the voltage supply. Note that dangerous voltages can be present at the terminals and connections for up to 1 minute after the controller is switched off.
- Block the output stage of the inverter before switching at the output of the device.



⚠ WARNING

Electric shock from capacitors that have not been fully discharged.

Severe or fatal injuries.

- Disconnect the inverter from the power. Observe the minimum switch-off time after disconnection from the supply system:
 - **1 minute**



⚠ WARNING

Danger if the motor starts up unintentionally

Severe or fatal injuries.

- Observe the startup instructions.
- Deactivate all control signals.



⚠ WARNING

Danger of burns due to hot surfaces of the device (e.g. the heat sink).

Severe injuries.

- Do not touch the device until it has cooled down sufficiently.



INFORMATION

- The maximum output frequency in any operating mode is 120 Hz.
- If the maximum output frequency is exceeded, the status LED of the MOVIMOT® inverter flashes slowly red (fault 08 "speed monitoring").

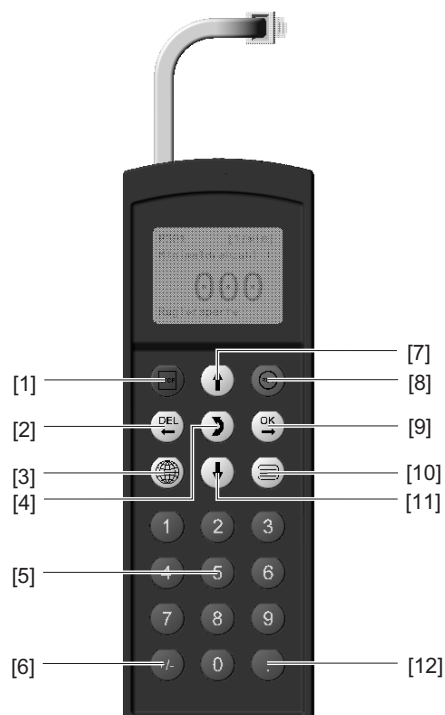
7.2 DBG keypad

7.2.1 Function

You can use the DBG keypad for parameterization and manual operation of MOVIMOT® drives. In addition to that, the keypad displays important information about the state of the MOVIMOT® drive.

7.2.2 Key assignment DBG

The following figure shows the key assignment of the DBG keypad:



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[1]	Key		Stop
[2]	Key		Delete previous entry
[3]	Key		Select the required language
[4]	Key		Change the menu
[5]	Key	<0> – <9>	Digits 0 – 9
[6]	Key		Changes signs
[7]	Key		Up arrow, moves up to the next menu item
[8]	Key		Start
[9]	Key		OK, confirms the entry
[10]	Key		Calls up the context menu
[11]	Key		Down arrow, moves down to the next menu item
[12]	Key		Decimal point

7.2.3 Activation



▲ WARNING

Risk of crushing if the drive starts up unintentionally.

When deactivating the manual mode, the binary signals (binary control) or the process data of the master (control via RS485) become active. If the enable signal is present via the binary signals or process data, the MOVIMOT® drive can start up unintentionally when deactivating manual operation.

- Before deactivating the manual mode, set the binary signals or the process data in such way that the MOVIMOT® drive is not enabled.
- The binary signals or process data must only be changed again after deactivating manual operation.

To switch to manual mode, proceed as follows:

1. Use the  key to switch to the context menu.
2. Use the  or  key to select "MANUAL MODE".
⇒ Press the  key to confirm your selection.

The keypad is now in manual mode.

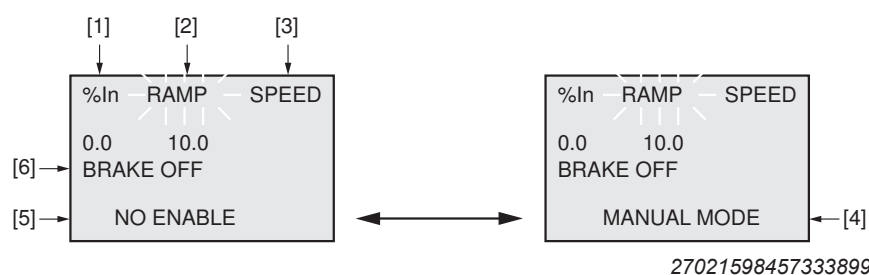
INFORMATION



If the drive is enabled or the brake is released, you cannot switch to manual mode.

The display shows the message "NOTE 17: INV. ENABLED" for 2 seconds. The operator terminal switches to the context menu.

Display in manual mode



Display alternates every 2 s

- [1] Output current in % of I_N
- [2] Acceleration (speed ramps in [s] in relation to setpoint step change of 50 Hz)
- [3] Speed in min^{-1}
- [4] Display in manual mode
- [5] Inverter status
- [6] Brake status

7.2.4 Operation

The following MOVIMOT® function can be executed in the "MANUAL MODE" menu:

Setting the ramp time.

Press the  key.

Use the  or  key to set the required ramp time.

Press the  key to confirm your entry.

Changing parameters.

Use the  key to switch between parameters "RAMP", "SPEED" and "BRAKE".

Switch to the "SPEED" parameter.

The keypad flashes the currently set parameter "SPEED".

Enter speed.

Use the digit keys <0> – <9> to enter the desired speed for manual mode.

The sign determines the direction of rotation of the drive.

Press the  key to confirm your entry.

Starting the drive.

Use the  key to start the MOVIMOT® drive.

During operation, the operator terminal displays the current motor current in [%] of the rated motor current I_N .

Stop drive.

Use the  key to stop the MOVIMOT® drive.

Release brake without drive enable.

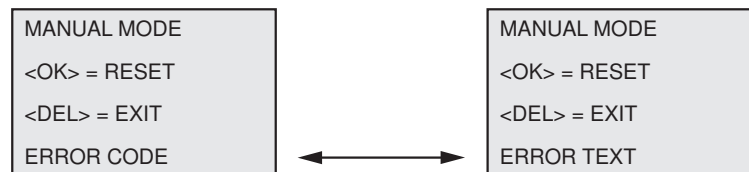
Press the  key to switch to the "BRAKE" menu item.

Use the  key or the  key to release or engage the brake without drive enable.

Press the  key to confirm your selection.

Reset the fault.

If an error occurs in manual mode, the display shows the following message:



Display alternates every 2 s

Press the  key to have the DBG operator terminal reset the error.

During the error reset, the following message is displayed:

MANUAL MODE
PLEASE WAIT...

After the error is reset, manual mode remains active.

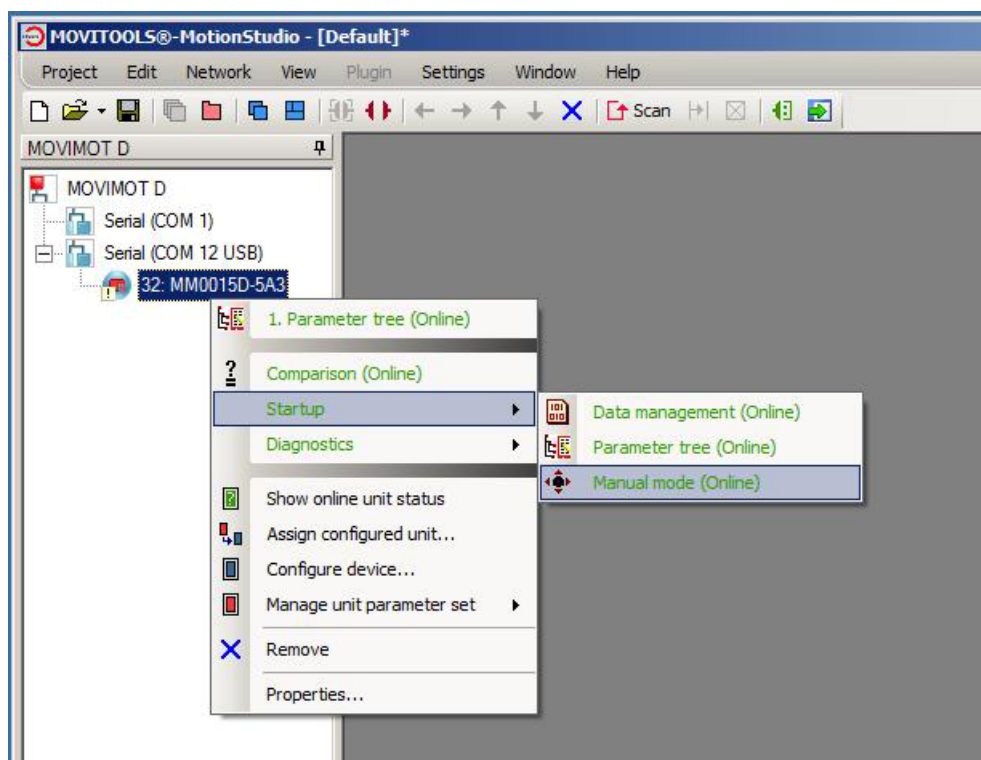
The display shows manual mode again.

7.3 MOVIMOT® manual mode with MOVITOOLS® MotionStudio

MOVIMOT® drives are equipped with an X50 diagnostics interface for startup and service. This enables diagnostics, manual mode and parameterization.

For manual operation of the MOVIMOT® drive, you can use the manual mode function of the MOVITOOLS® MotionStudio software.

1. Firstly connect the PC/laptop to the MOVIMOT® inverter.
 - ⇒ See chapter "PC/laptop connection" (→ 42).
2. Start the software MOVITOOLS® MotionStudio and integrate the MOVIMOT® inverter in MOVITOOLS® MotionStudio.
 - ⇒ See chapter "MOVITOOLS® MotionStudio" (→ 66).
3. Once the MOVIMOT® inverter is successfully integrated, open the context menu by clicking on the right mouse button and select the menu item "Startup" > "Manual mode".



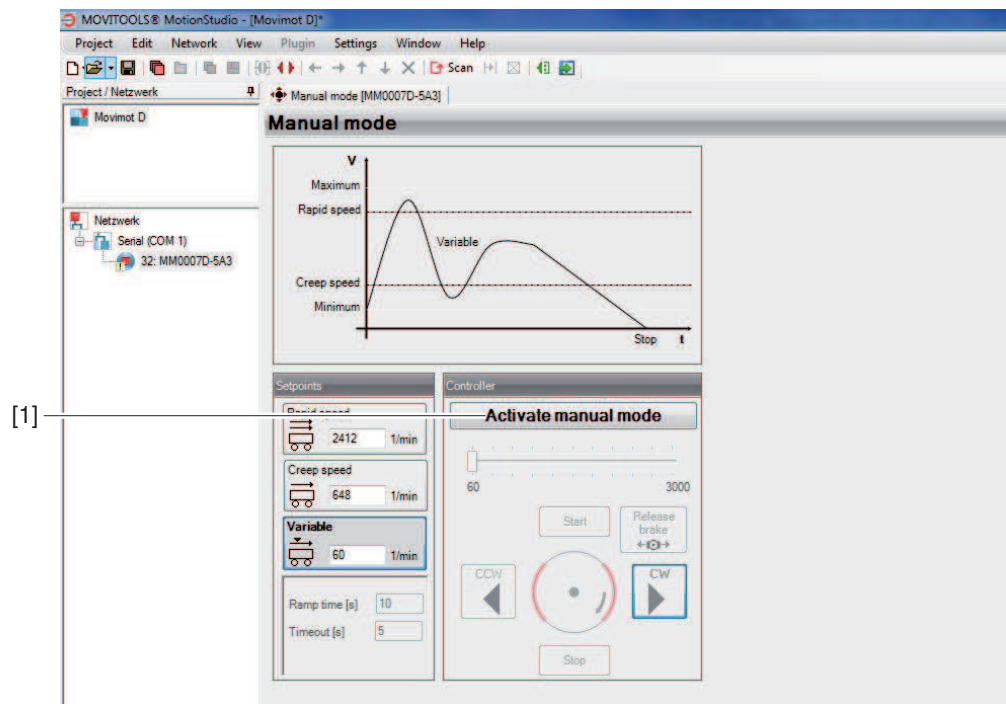
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7.3.1 Activation

Manual mode can only be activated if the MOVIMOT® drive is inhibited.

Activation is **not** possible

- If the brake is released without drive enable
- or if the inverter output stage is enabled to supply a standstill current.



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To activate manual mode, click the [Activate manual mode] button [1].

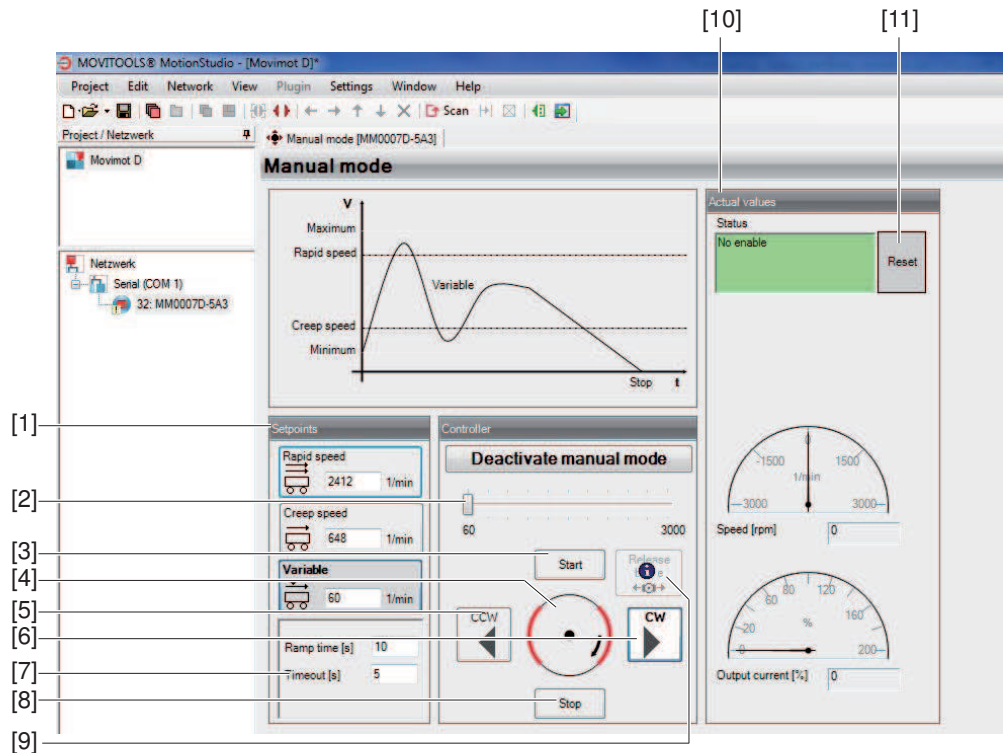
Parameter *P097 PI 1 Actual value (display value)* signals the higher-level controller that manual mode is active.

Manual mode remains active even after an error reset or after the 24 V supply has been switched off.

Deactivate manual operation before you disconnect the PC/laptop from the MOVIMOT® inverter.

7.3.2 Control in manual mode

Once manual mode has been successfully activated, you can control the MOVIMOT® drive using the controls in the "Manual mode" window of MOVITOOLS® MotionStudio.



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1. Use the slider [2] in the "Control" group to set the variable setpoint speed.
2. Use the buttons [clockwise] [6] or [counterclockwise] [5] to specify the direction of rotation..
3. Click on the [Start] button [3] to enable the MOVIMOT® drive.
 - ⇒ The motor axis [4] shown in the "Control" group symbolizes the direction of rotation and the speed of the motor.
4. Use the [Stop] [8] button to stop the drive.

Alternatively, you can enter the setpoints for rapid speed, creep speed or variable speed setpoint directly in the "Setpoints" group [1].

The direction of rotation is defined by the sign (positive = clockwise rotation, negative = counterclockwise rotation).

First enter the setpoint. Press <ENTER> and click on the button that contains the setpoint input field to enable the MOVIMOT® drive.

The group "Actual values" [10] displays the following actual values of the MOVIMOT® drive:

- MOVIMOT® inverter status
- Motor speed in min^{-1}
- Output current of the MOVIMOT® inverter in [%] of I_N

On MOVIMOT® drives with a brake, you can release the brake even without drive enable by activating the "Brake release" check box [9].

INFORMATION



The brake can only be released without drive enable if:

- DIP switch S2/2 = ON
- Or this function is enabled via parameter *P738*

7.4 IT security

7.4.1 Hardening measures



Perform the following hardening measures:

- Report incidents regarding cybersecurity by e-mail to cert@sew-eurodrive.com or via the contact form on the Product Security Management website (<http://go.sew/psm>).
- Regularly check which security advisories are available in the Online Support of SEW-EURODRIVE.
- Evaluate the fault memories and diagnostics information of your products regularly and check whether there are entries that affect IT security.

7.4.2 Guidelines for secure operation



The engineering protocol from SEW-EURODRIVE allows to activate various interfaces on the device. No authentication takes place and no user account management guidelines are applied that are used to protect against changes or to prevent attacks on IT security.

To prevent misuse of the interfaces, access must be restricted using state-of-the-art technology. For more information, refer to section "IT security of the environment" (→ 8).

7.4.3 Guidelines for user account management

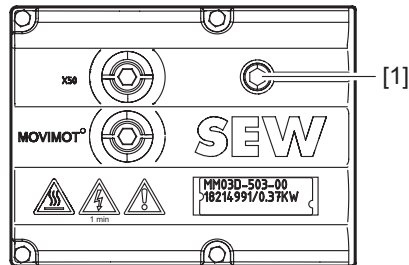


The device has no user accounts.

8 Service

8.1 Status and error display

The status LED is located on the top of the MOVIMOT® inverter.



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[1] MOVIMOT® status LED

8.1.1 Meaning of the status LED

The 3-color status LED indicates the operating and error states of the MOVIMOT® inverter.

LED Color Status	MeaningOperating state error code	Possible cause
Off	Not ready for operation	No 24 V voltage supply.
Yellow Flashing steadily	Not ready for operation	Self-test phase active or 24 V power supply present but line voltage is not OK.
Yellow Flashing steadily fast	Ready	Releasing the brake without drive enable active (only with S2/2 = "ON").
Yellow steady light	Ready but unit inhibited	24 V power supply and line voltage is OK, but no enable signal. If the drive does not run when enable signal is present, check startup.
Yellow 2x flashing, pause	Ready, but manual mode without unit enable	24 V power supply and line voltage OK. Stop manual mode to activate automatic mode.
	Ready, Prioritized fixed setpoint control	Terminals R ↻ and L ↻ are supplied with 24 V. To activate RS485 operation, remove the bridges installed in the factory. See chapter "Electrical installation".
Yellow/green Flashing with alternating colors	Ready, but timeout	Communication is interrupted during cyclical data exchange.
Green Steady light	Device enabled	Motor is in operation.

LED Color Status	MeaningOperating state error code	Possible cause
Green Flashing steadily fast	Current limit active	Drive is at the current limit.
Green Flashing steadily	Ready	Idle state current function active.
Green 2x flashing, pause	Device enabled	MOVIMOT® drive is in operation. Prioritized fixed setpoint control is active. See chapter "Parameter description" > "Parameter 600".
Green/Red/Green Flashing with alternating colors, pause	Localization function active	Localization function was activated. See parameter 590.
Red 2x flashing, pause	Fault 07	DC link voltage too high.
Red Flashing slowly	Fault 08	Speed monitoring error (only when S2/4 = "ON") or additional function 13 is active.
	Fault 09	Startup fault Additional functions 4, 5, 12 (DIP switches S2/5 – S2/8) are not permitted.
		Firmware does not support MLK..A option (only with MOVIMOT® with AS-Interface).
	Fault 15	24 V supply error
	Error 17 – 24, 37	CPU fault
	Error 25, 94	EEPROM fault
	Error 38, 45	Device and motor data error
	Fault 44	The current limit was exceeded for more than 500 ms. (only with additional function 2)
Red 3x flashing, pause	Fault 90	Incorrect motor/inverter assignment.
	Fault 97	Error while transmitting a parameter set
Red 4x flashing, pause	Fault 01	Overcurrent in output stage
	Fault 11	Overtemperature in output stage
Red 5x flashing, pause	Fault 84	Motor overload
Red 5x flashing, pause	Fault 4	Brake chopper fault
	Fault 89	Overtemperature of the brake Incorrect motor – frequency inverter assignment. At terminals X1:13– X1:15, both brake and braking resistor are connected. This is not permitted.

LED Color Status	Meaning Operating state error code	Possible cause
Red 6x flashing, pause	Fault 06	Line phase failure
	Fault 81	Start condition
	Fault 82	Output phases are interrupted.
Red steady light	Not ready for operation	Check 24 V supply. A smoothed DC voltage with a maximum residual ripple of 13% must be present.

Flashing codes of the status LED

Flashing steadily:	LED 600 ms on, 600 ms off
Flashing steadily, fast:	LED 100 ms on, 300 ms off
Flashing with alternating colors:	LED 600 ms green, 600 ms yellow
Flashing with alternating colors, pause:	LED 100 ms green, 100 ms red, 100 ms green, 300 ms pause
N x flashing, pause:	LED N x (600 ms red, 300 ms off), then LED off for 1 s

8.2 Fault description

The following table helps you with troubleshooting:

Code	Error	Possible cause	Measure
–	Communication timeout (Motor stops, without error code)	Missing connection $\perp$, RS+, RS- between MOVIMOT® and RS485 master	Check and establish the connection, especially ground.
		EMC influence	Check the shielding of signal cables and improve, if necessary.
		Incorrect type (cyclical) for acyclical data traffic, the protocol period between the individual telegrams is longer than the set timeout interval.	Check the number of MOVIMOT® drives connected to the master. If the timeout interval is 1 s, for example, you can connect a maximum of 8 MOVIMOT® drives as slaves for cyclical communication. Reduce message cycle, increase timeout interval, or select message type "acyclic".
–	Supply voltage not present (Motor stops, without error code)	DC link voltage too low, Power off has been detected.	Check supply system cables and line voltage for interruption.

Code	Error	Possible cause	Measure
–	24 V supply not present (Motor stops, without error code)	24 V supply voltage not present.	Check 24 V supply voltage for interruption. Check the value of the 24 V supply voltage. Permitted voltage: DC 24 V ± 25%, EN 61131-2, residual ripple max. 13% Motor restarts automatically as soon as the voltage reaches normal values.
		AUX power supply voltage not available. (only for MOVIMOT® with AS-Interface)	Check AUX power supply voltage for interruption. Check the value of the AUX power supply voltage. Permitted voltage: DC 24 V ± 25%, EN 61131-2, residual ripple max. 13% Motor restarts automatically as soon as the voltage reaches normal values.
01	Overcurrent in output stage	Short circuit of inverter output	Check the connection between the inverter output and the motor as well as the motor winding for short circuits. Reset the error. ¹⁾
04	Brake chopper	Overcurrent in brake output, resistor damaged, resistance too low	Check the connection of the resistor/replace it.
		Short circuit in brake coil	Replace brake.
06	Phase failure (The error can only be detected when the drive is under load)	Phase failure	Check the supply system cables for phase failure. Reset the error ¹⁾
07	DC link voltage too high	Ramp time too short.	Extend the ramp time. Reset the error ¹⁾
		Faulty brake coil/braking resistor connection	Check the braking resistor/brake coil connection. Correct, if necessary. Reset the error ¹⁾
		Incorrect internal resistance of brake coil/braking resistor	Check internal resistance of brake coil/braking resistor (see operating instructions, chapter "Technical data"). Reset the error ¹⁾
		Thermal overload in braking resistor, wrong size of braking resistor selected	Dimension the braking resistor correctly. Reset the error ¹⁾
		Invalid voltage range of line input voltage	Check the line input voltage for permissible voltage range. Reset the error ¹⁾
08	Speed monitoring	Rotational speed deviation due to operation at the current limit	Reduce the drive load. Reset the error ¹⁾

Code	Error	Possible cause	Measure
09	Startup	Improper drive ID module for MOVIMOT® with 230 V supply	For MOVIMOT® with 230 V supply, not all drive ID modules are permitted (see operating instructions, chapter "Assignment of the drive ID module"). Check/correct the drive ID module.
		The additional functions 4, 5, 12 are not permitted for MOVIMOT® MM..D with AS-Interface.	Correct the setting of DIP switches S2/5 to S2/8.
		Firmware does not support MLK..A option (only with MOVIMOT® with AS-Interface).	Contact SEW-EURODRIVE Service.
11	Thermal overload of the output stage or internal unit error	Heat sink is dirty.	Clean the heat sink. Reset the error ¹⁾
		Ambient temperature too high.	Lower the ambient temperature. Reset the error ¹⁾
		Heat build-up at MOVIMOT® drive.	Prevent heat build-up. Reset the error ¹⁾
		Drive load too high.	Reduce the drive load. Reset the error ¹⁾
15	24 V monitoring	Voltage dip in the 24 V supply	Check the 24 V supply. Reset the error ¹⁾
17 - 24 37	CPU error	CPU error	Reset the error ¹⁾ If the error reoccurs, contact SEW-EURODRIVE Service.
25	EEPROM error	Error when accessing EEPROM	Set parameter <i>P802</i> to "Delivery state". Reset the error ¹⁾ Re-parameterize MOVIMOT® inverter. If the error reoccurs, contact SEW-EURODRIVE Service.
26	External terminal	External signal at terminal X6: 9.10 not present.	Correct/reset external error.
38	System software error	Internal error	Contact SEW-EURODRIVE Service.

Code	Error	Possible cause	Measure
43	Communication timeout	Communication timeout during cyclical communication via RS485. If this error occurs, the drive is decelerated and stopped along the set ramp.	Check/re-establish the communication link between the RS485 master and the MOVIMOT® inverter. NOTICE! When communication is restored, the drive will be enabled again.
			Check the number of slaves connected to the RS485 master. If the timeout interval of the MOVIMOT® inverter is set to 1 s, you can connect a maximum of 8 MOVIMOT® inverters (slaves) to the RS485 master for cyclical communication.
		Internal communication error (at MOVIMOT® MM..D with AS-Interface)	Contact SEW-EURODRIVE Service.
44	Current limit exceeded	The set current limit was exceeded for more than 500 ms. This error is only active with additional function 2. The status LED flashes red.	Reduce load or increase current limit at switch f2 (only with additional function 2).
45	Device/motor data error during initialization	Device/motor data error A non-IT-compatible device is connected to the IT system. MOVIMOT® hardware defect	Restore the delivery state (P802). Use an IT system device. Contact SEW-EURODRIVE Service.
81	Start condition error	The inverter could not be supplied with the correct amount of current during the premagnetization time. Rated motor power too small in relation to rated inverter power.	Check connection between MOVIMOT® inverter and motor.
82	Output open error	Two or all output phases are interrupted.	Check connection between MOVIMOT® inverter and motor.
		Rated motor power too small in relation to rated inverter power.	Check the combination of motor and MOVIMOT® inverter.

Code	Error	Possible cause	Measure
84	Thermal overload of the motor	If the MOVIMOT® inverter is mounted close to the motor, the motor protection is active.	Set DIP switch S1/5 to "ON". Reset the error ¹⁾
		The performance level is set incorrectly for the combination of MOVIMOT® inverter and motor.	Check the setting of DIP switch S1/6. Reset the error ¹⁾
		Ambient temperature too high.	Lower the ambient temperature. Reset the error ¹⁾
		Heat build-up at MOVIMOT® drive.	Prevent heat build-up. Reset the error ¹⁾
		Motor load too high.	Reduce the load on the motor. Reset the error ¹⁾
		Speed too low.	Increase the speed. Reset the error ¹⁾
		If the error is signaled just after the first enable signal.	Check the combination of motor and MOVIMOT® inverter. Reset the error ¹⁾
		The temperature monitoring in the motor (TH winding thermostat) has tripped when using a MOVIMOT® inverter with the selected extra function 5.	Reduce the load on the motor. Reset the error ¹⁾
89	Overtemperature of the brake	Thermal overload of brake coil	Extend the ramp time. Reset the error ¹⁾
		Brake coil is defective.	Contact SEW-EURODRIVE Service.
		Brake coil and braking resistor connected.	Connect either brake or braking resistor to drive.
		Brake coil incorrectly connected	See chapters "Connection of MOVIMOT® drive" (→ 34) and "Connecting without connector" (→ 36).
		Inverter does not match the motor. (only if error occurs after first enable)	Check the combination of motor (brake coil) and MOVIMOT® inverter. Check/correct the settings of DIP switches S1/6 and S2/1. Reset the error ¹⁾

Code	Error	Possible cause	Measure
90	Output stage detection	The inverter/motor combination is not permitted.	Check/correct the settings of DIP switches S1/6 and S2/1.
			Check/correct the connection type of the motor.
			Check whether the drive ID module fits the motor and is plugged in correctly.
			Use a MOVIMOT® inverter or a motor with another power rating.
91	Communication timeout bus module – MOVIMOT®	Timeout between the fieldbus interface and the MOVIMOT® inverter.	Check/re-establish the communication link between the fieldbus interface and the MOVIMOT® inverter. The fieldbus interface reports the error only to the higher-level controller.
94	EEPROM checksum error	EEPROM defective.	Contact SEW-EURODRIVE Service.
97	Copy error	DBG keypad or PC/laptop disconnected during the copy process.	Before acknowledging the error, load the factory setting or the complete data set from the DBG keypad or the MOVITOOLS® MotionStudio software.
		Switching the 24 V voltage supply off and on during the copying process.	Before acknowledging the error, load the factory setting or the complete data set from the DBG keypad or the MOVITOOLS® MotionStudio software.

1) With standard MOVIMOT® units, reset the error by switching off the 24 V supply voltage or by performing an error reset. With MOVIMOT® with AS-Interface, reset the error via the AS-Interface signals or by error reset via the diagnostics socket.

8.3 Unit replacement



⚠ WARNING

Electric shock from capacitors that have not been fully discharged.

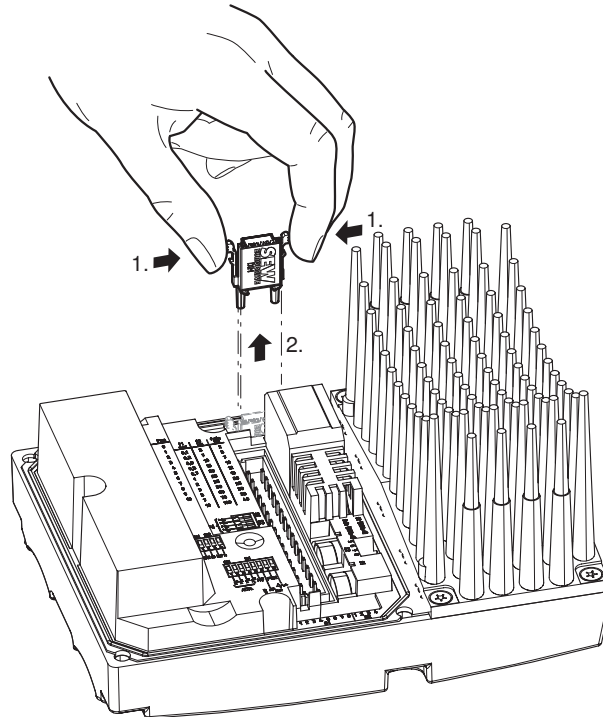
Severe or fatal injuries.

- Disconnect the inverter from the power. Observe the minimum switch-off time after disconnection from the supply system:

– **1 minute**

1. Remove the screws and take off the MOVIMOT® inverter from the connection box.
2. Compare the data on the nameplate of the previous MOVIMOT® inverter with the data on the nameplate of the new MOVIMOT® inverter.
 - ⇒ The MOVIMOT® inverter must only be replaced with a MOVIMOT® inverter with the same part number.
3. Set the following control elements on the new MOVIMOT® inverter according to the control elements of the previous MOVIMOT® inverter:
 - ⇒ DIP switch S1
 - ⇒ DIP switch S2

- ⇒ Setpoint potentiometer f1
 - ⇒ Switch f2
 - ⇒ Switch t1
4. Unlock the drive ID module of the new MOVIMOT® inverter and pull it out carefully.



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5. Unlock the drive ID module of the previous MOVIMOT® inverter as well and pull it out carefully.
6. Insert this drive ID module into the new MOVIMOT® inverter.
- ⇒ Make sure that the drive ID module snaps into place.
7. Place the new MOVIMOT® inverter onto the connection box and screw it in place.
8. Supply voltage to the MOVIMOT® inverter.
- ⇒ When switching on the new inverter the first time after a unit replacement, the 24 V supply must be connected for at least 10 seconds without interruptions.
 - ⇒ After the unit replacement, it can take up to 6 s before the MOVIMOT® inverter signals the ready signal.
9. Check whether the new MOVIMOT® inverter is functioning properly.

8.4 Shutdown

To shut down the MOVIMOT® drive, de-energize the drive using appropriate measures.



⚠ WARNING

Electric shock from capacitors that have not been fully discharged.

Severe or fatal injuries.

- Disconnect the inverter from the power. Observe the minimum switch-off time after disconnection from the supply system:
 - **1 minute**

8.5 IT security guidelines for secure disposal

8.5.1 Removing the product from its intended environment



If you consider the data stored on the product relevant to IT security, remove the data in accordance with the section "Secure removal of data stored in the product." (→ 86)

Although this product does not independently transmit data to devices in its environment, other devices in the environment, such as controllers, HMIs, engineering PCs, or operator panels, can read and store data from the product. This includes reference data, configuration data, log data and other data belonging to the product.

If the data stored in the environment is classified as relevant for IT security, remove this data according to the documentation of the respective devices in the environment.

For data that can be saved with the engineering software from SEW-EURODRIVE, refer to "Deleting data saved using the engineering software" (→ 87).

8.5.2 Secure removal of data stored in the product



Some of the data of the product is stored on a removable storage medium (DIM module). If the data on the removable storage medium is classified as sensitive data from the operator's point of view and is not intended for later use, reset the device to the factory settings using MOVITOOLS® MotionStudio before disposing of the data. This also deletes the storage medium content. Alternatively, remove the DIM module and disposed of it through a qualified disposal process.

The following data is deleted/reset:

- Configuration of the device
- Device name
- Device address
- Safety-relevant data

The following data is not reset during this procedure and can be modified individually if available on the described product:

- AS-Interface address
- DIP switch settings
- Potentiometer settings
- Scope recording of the device
- Fault memory

8.5.3 Deleting data saved using the engineering software



Using the MOVITOOLS® MotionStudio engineering software, you can retrieve all product data and store it locally or on remote storage locations.

If the data saved in this way is classified as relevant for IT security, delete the data when removing the product from the environment.

When data is saved by an engineering software in the environment of the product, the following data types and data volumes are created:

Software	Data type	Data volume
MOVITOOLS® MotionStudio	Proprietary SEW device format	< 1 MB

8.6 Waste disposal

Dispose of the product and all parts separately in accordance with their material structure and the national regulations. Put the product through a recycling process or contact a specialist waste disposal company. If possible, divide the product into the following categories:

- Iron, steel, or cast iron
- Stainless steel
- Magnets
- Aluminum
- Copper
- Electronic parts
- Plastics

The following materials are hazardous to health and the environment. These materials must be collected and disposed of separately:

- Oil and grease
Collect used oil and grease separately according to type. Ensure that the used oil is not mixed with solvent. Dispose of used oil and grease correctly.
- Screens
- Capacitors



Waste disposal according to WEEE Directive 2012/19/EU

This product and its accessories may fall within the scope of the country-specific application of the WEEE Directive. Dispose of the product and its accessories according to the national regulations of your country.

For further information, contact the responsible SEW-EURODRIVE branch or an authorized partner of SEW-EURODRIVE.

9 Inspection and maintenance

9.1 MOVIMOT® inverter

The MOVIMOT® inverter is maintenance-free. SEW-EURODRIVE does not prescribe any inspection or maintenance work for the MOVIMOT® inverter and the fieldbus interface.

Exception: For extended storage, refer to the instructions in chapter "Extended storage".

9.2 Motor

The motor requires regular inspection and maintenance work.

Observe the notes and instructions in chapter "Inspection/Maintenance" of the motor operating instructions.

9.3 Gear units (only for MOVIMOT® gearmotors)

The gear unit requires regular inspection and maintenance work.

Observe the notes and instructions in chapter "Inspection/Maintenance" of the gear unit operating instructions.

10 Contacting SEW-EURODRIVE

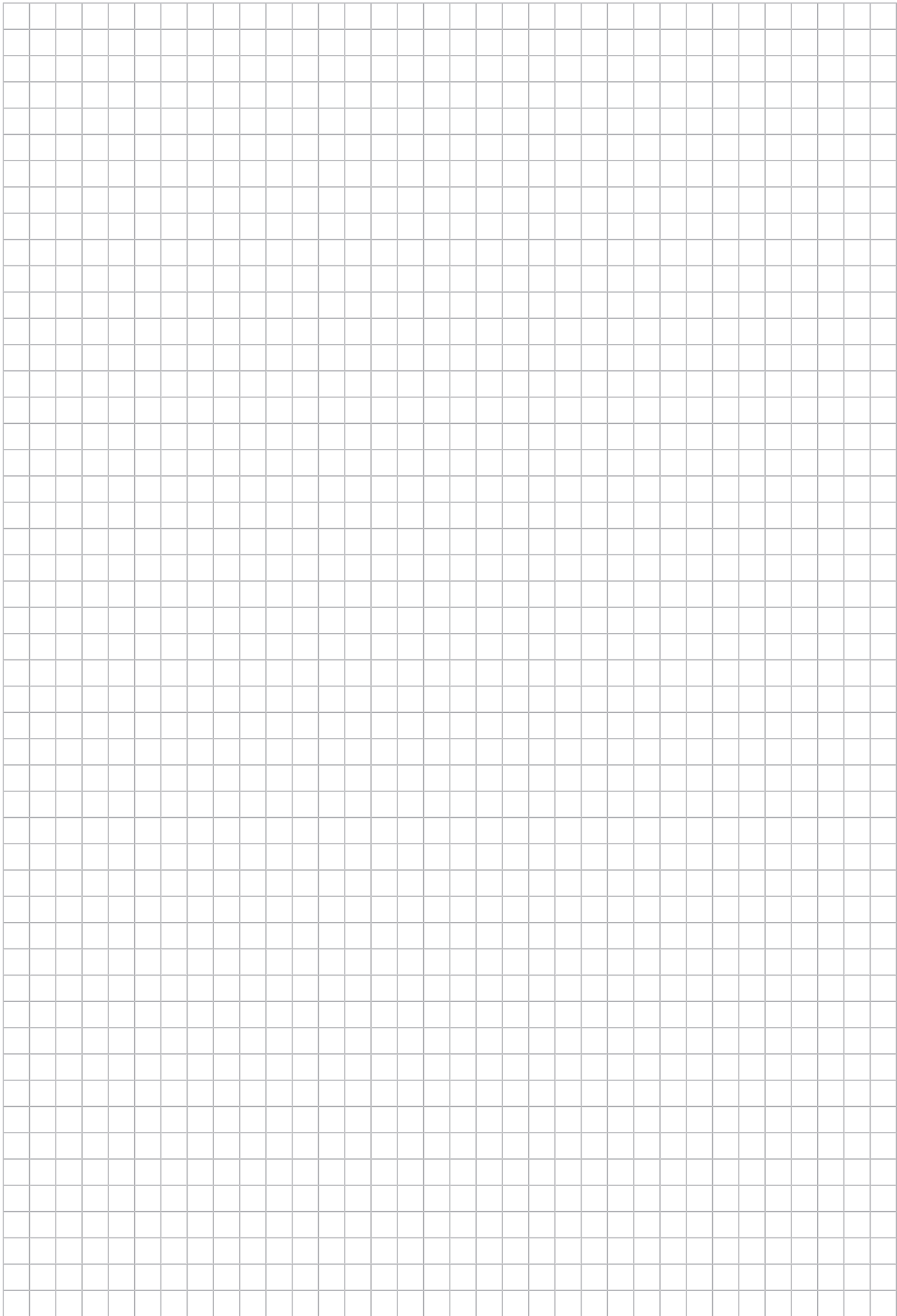
You can find the worldwide contact data and locations on the **SEW-EURODRIVE website** via the following link or the QR code shown below.

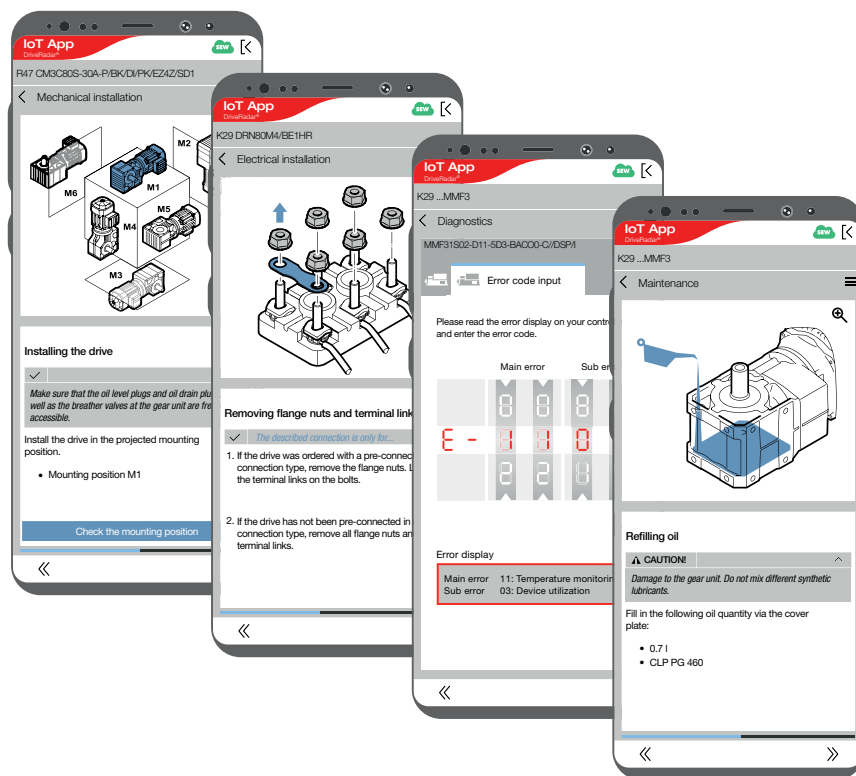
<https://www.sew-eurodrive.de/contacts-worldwide>



SEW
EURODRIVE







<https://iotapp.io>



THE GREEN SIDE OF DRIVE

Documentation and technical information on your smartphone –
paperless and always available





SEW-EURODRIVE
Driving the world

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