

# **Assembly and Operating Instructions**



PxG® Series Servo Gear Units

Edition 05/2020 26639548/EN





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### 1 General information

#### 1.1 About this documentation

#### The documentation at hand is the original.

This documentation is an integral part of the product. The documentation is intended for all employees who perform work on the product.

Make sure this documentation is accessible and legible. Ensure that persons responsible for the systems and their operation as well as persons who work on the product independently have read through the documentation carefully and understood it. If you are unclear about any of the information in this documentation or if you require further information, contact SEW-EURODRIVE.

## 1.2 Structure of the safety notes

#### 1.2.1 Meaning of signal words

The following table shows the grading and meaning of the signal words for safety notes.

Signal word	Meaning	Consequences if disregarded			
▲ DANGER	Imminent hazard	Severe or fatal injuries			
<b>▲</b> WARNING	Possible dangerous situation	Severe or fatal injuries			
<b>▲</b> CAUTION	Possible dangerous situation	Minor injuries			
NOTICE	Possible damage to property	Damage to the product or its envi- ronment			
INFORMATION	Useful information or tip: Simplifies handling of the product.				

#### 1.2.2 Structure of section-related safety notes

Section-related safety notes do not apply to a specific action but to several actions pertaining to one subject. The hazard symbols used either indicate a general hazard or a specific hazard.

This is the formal structure of a safety note for a specific section:



#### SIGNAL WORD

Type and source of hazard.

Possible consequence(s) if disregarded.

Measure(s) to prevent the hazard.

#### Meaning of the hazard symbols

The hazard symbols in the safety notes have the following meaning:

Hazard symbol	Meaning
	General hazard



Hazard symbol	Meaning
	Warning of hot surfaces
-B M B-	Warning of risk of crushing
	Warning of automatic restart

#### 1.2.3 Structure of embedded safety notes

Embedded safety notes are directly integrated into the instructions just before the description of the dangerous action.

This is the formal structure of an embedded safety note:

▲ SIGNAL WORD! Type and source of hazard. Possible consequence(s) if disregarded. Measure(s) to prevent the hazard.

## 1.3 Decimal separator in numerical values

In this document, a period is used to indicate the decimal separator.

Example: 30.5 kg

## 1.4 Rights to claim under limited warranty

Read the information in this documentation. This is essential for fault-free operation and fulfillment of any rights to claim under limited warranty. Read the documentation before you start working with the product.

#### 1.5 Product names and trademarks

The brands and product names in this documentation are trademarks or registered trademarks of their respective titleholders.

#### 1.6 Copyright notice

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## 2 Safety notes

## 2.1 Preliminary information

The following general safety notes serve the purpose of preventing injury to persons and damage to property. They primarily apply to the use of products described in this documentation. If you use additional components, also observe the relevant warning and safety notes.

#### 2.2 Duties of the user

As the user, you must ensure that the basic safety notes are observed and complied with. Make sure that persons responsible for the machinery and its operation as well as persons who work on the device independently have read through the documentation carefully and understood it.

As the user, you must ensure that all of the work listed in the following is carried out only by qualified specialists:

- Setup and installation
- · Installation and connection
- Startup
- Maintenance and repairs
- Shutdown
- Disassembly

Ensure that the persons who work on the product pay attention to the following regulations, conditions, documentation, and information:

- National and regional safety and accident prevention regulations
- Warning and safety signs on the product
- All other relevant project planning documents, installation and startup instructions, and wiring diagrams
- Do not assemble, install or operate damaged products
- · All system-specific specifications and conditions

Ensure that systems in which the product is installed are equipped with additional monitoring and protection devices. Observe the applicable safety regulations and legislation governing technical work equipment and accident prevention regulations.

## 2.3 Target group

Specialist for mechanical work Any mechanical work may be performed only by adequately qualified specialists. Specialists in the context of this documentation are persons who are familiar with the design, mechanical installation, troubleshooting, and maintenance of the product who possess the following qualifications:

- Qualifications in the field of mechanics in accordance with the national regulations
- · Familiarity with this documentation



Specialist for electrotechnical work Any electrotechnical work may be performed only by electrically skilled persons with a suitable education. Electrically skilled persons in the context of this documentation are persons who are familiar with electrical installation, startup, troubleshooting, and maintenance of the product who possess the following qualifications:

- Qualifications in the field of electrical engineering in accordance with the national regulations
- Familiarity with this documentation

Additional qualifications

In addition to that, these persons must be familiar with the valid safety regulations and laws, as well as with the requirements of the standards, directives, and laws specified in this documentation.

The persons must have the express authorization of the company to operate, program, parameterize, label, and ground devices, systems, and circuits in accordance with the standards of safety technology.

Instructed persons

All work in the areas of transportation, storage, operation and waste disposal must be carried out by persons who are trained appropriately. The purpose of the training is to give persons the ability to perform the required tasks and work steps in a safe and correct manner.

#### 2.4 Designated use

The gear units are a means of torque and speed transmission. Gear units and gearmotors of this gear unit series are designated to be installed in electrical systems or machines.

The product is intended for use in industrial and commercial systems.

In case of installation in electrical systems or machines, startup of the product is prohibited until it is determined that the machine meets the requirements stipulated in the local laws and directives. For Europe, Machinery Directive 2006/42/EC as well as the EMC Directive 2014/30/EU apply.

Using these products in potentially explosive atmospheres is prohibited, unless specifically designated otherwise.

Unintended or improper use of the product may result in severe injury to persons and damage to property.

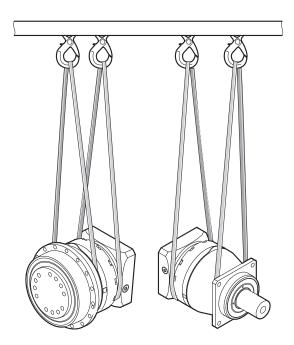
For the technical data, refer to the nameplate and chapter "Technical data" in the documentation. Always comply with the data and conditions.



## 2.5 Transportation/storage

Observe the following notes when transporting the device:

- Inspect the shipment for damage as soon as you receive the delivery. Inform the shipping company immediately about any damage. If the product is damaged, it must not be assembled, installed or started up.
- In case the product is not installed right away, store it horizontally, dry, dust-free and indoors at a storage temperature between -10 °C and +40 °C. The product can be stored for up to 24 months without requiring any special measures before startup. In case of storage period longer than 24 months, contact SEW-EURODRIVE.
- Note that retaining straps attached to the products might be under tension. To avoid cutting injuries, remove the retaining straps carefully from the product and wear suitable protective clothing, if necessary.
- If the product weighs more than 40 kg, use lifting equipment for transporting, e.g. straps. You can find the product weight on the nameplate of the product or in the order data sheet.



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- Note the hazard from suspended loads. Do not stand under suspended loads. Secure the area where suspended loads can fall down. Secure loads using suitable holding fixtures (e.g. belts) before lifting them.
- Sudden impacts, e.g. due to falling or sudden lowering of the product can cause damages to the product. Only use lifting equipment and load handling devices with a sufficient load capacity. Adhere to the permitted load of the lifting equipment. Lower the product carefully.

## 2.6 Installation/assembly

Protect the product from strong mechanical strain. The product and its mounting parts must never protrude into the path of persons or vehicles. Ensure that components are not deformed, particularly during transportation and handling. Electrical components must not be mechanically damaged or destroyed.





## 2.7 Carrying out electrical work safely

Observe the following information to carry out electrical work safely during installation and maintenance:

- Electrical work may only be carried out by electrically skilled persons.
- Always adhere to the 5 safety rules for working on electrical components:
  - Disconnect
  - Secure the drive against restart
  - Check that no voltage is applied
  - Ground and short-circuit it
  - Cover or safeguard neighboring live parts
- When the device is switched on, dangerous voltages are present at all power connections as well as at any connected cables and terminals. This also applies even when the product is inhibited and the motor is at standstill.

### 2.8 Startup/operation

Do not deactivate monitoring and protection devices even for a test run.

In the event of deviations from normal operation, switch the product off. Possible deviations are increased temperatures, noise, or vibration, for example. Determine the cause. Contact SEW-EURODRIVE if necessary.

Risk of burns: The surface temperature of the product can exceed 60 °C during operation. Do not touch the product during operation. Let the product cool down before touching it.

#### 2.9 Cleaning

During cleaning work, protect the bearing and the sealing rings against contact with solvents. Solvents can damage the bearing and the sealing rings.

Only use commercial cleaning agents that are grease-dissolving but non-aggressive to prevent corrosion.

Do not use compressed air for cleaning the unit, but use a vacuum cleaner. Using compressed air can damage the product or lead to premature wear as particles are blown into the guides and bearings.

Only clean the gear unit in idle state. The pumping effect of a running gear unit can suck cleaning agent into the gear unit.



## 3 Gear unit structure

## 3.1 Basic structure

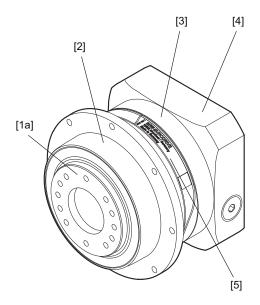
The gear units of the  $PxG^{\$}$  series are single- or multi-stage gear units with low backlash. They can be used in all mounting positions. The gear units are lubricated for life and so require little maintenance.

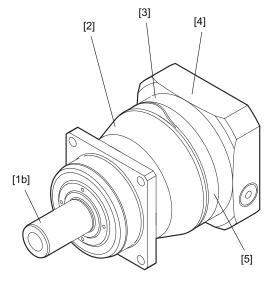
#### **INFORMATION**



The following illustrations serve as examples. Deviations are possible, depending on the design type and size.

The following figure shows an overview of the gear unit components.





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- [1a] Flange block shaft
- [1b] Output shaft
- [2] Gear unit housing

- [3] Adapter housing
- [4] Adapter flange
- [5] Nameplate

## 3.2 Output designs

## **INFORMATION**



The dots in product designations are placeholders for letters and/or numbers. One dot represents one letter or one number, two dots represent two or more letters or numbers.

The output design is a characteristic feature of the gear units.

The following output designs are available:

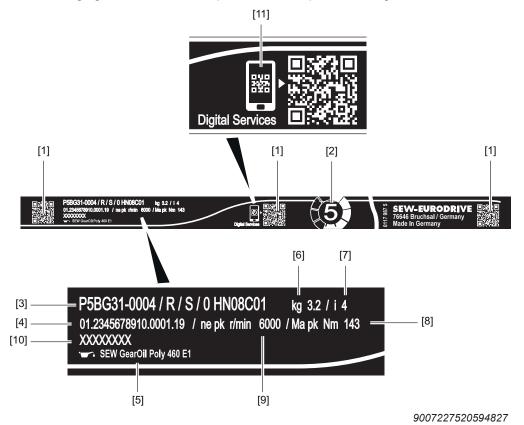
- · Flange block shaft
  - Flange block (P.BG..)
  - Flange block with index bore (P.CG..)
- · Output shaft
  - Smooth solid shaft (P.NG..)
  - Solid shaft with keyway (P.KG..)
  - Splined solid shaft (P.VG..)



## 3.3 Nameplate/type designation

#### 3.3.1 Example nameplate

The following figure shows an example of the nameplate for the gear unit:



	Inf	formation regarding the following:
[1]	•	Data matrix code
[2]	•	Performance class
[3]	•	Type designation
[4]	•	Serial number
[5]	•	Lubricant
[6]	•	Weight
[7]	•	Gear unit ratio
[8]	•	Peak torque, output end
[9]	•	Peak speed, input end
[10]	•	Customer-specific designation (optional)
[11]	•	Digital Services

#### 3.3.2 Sample type designation

P5BG31-0	P5BG31-0004/R/S/0 HN08C01							
Р	Gear unit type	Servo gear unit						
5	Performance class	Dynamics						
W	Output design	Flange block (without index hole)						
G	Gear unit design	Planetary gear unit						
3	Size	Size 3						
1	No. of stages	Single-stage						
0004	Gear ratio	i = 4						
R	Rotational clearance	R: Reduced						
S	Lubricant	Standard lubricant – oil						
0	Design	0: Standard						
H.	Adapter type	Smooth shaft						
.N	Adapter design	Rigid shaft, clamp-force-optimized						
08C01	Adapter code	08: Size 8 adapter shaft						
		C: With coupling sleeve C						
		01: Flange code number						

#### 4 Mechanical installation

#### 4.1 Prerequisites for installation

## **▲** CAUTION



The surfaces on the drive can become very hot during operation.

Risk of burns.

- Make sure that hot surfaces cannot be touched unintentionally or during normal operation. Install covers or warning signs according to regulations.
- · Let the motor cool down sufficiently before you start working on it.

#### **A CAUTION**



Risk of injury and malfunctions due to burrs at the cut edges.

Cut injuries and malfunctions.

- · Deburr all edges of the used components carefully.
- · Use work gloves.

Ensure that the following requirements have been met:

- The drive has not been damaged during transportation or storage.
- The data on the nameplate of the gear unit matches the requirements.
- Unless the gear unit was designed specifically for liquids, dust, aggressive oils, acids, gases, vapors, or radiation, no contact with these substances is permitted.
- Ensure that no foreign objects (e.g. falling objects or coverings) affect the operation of the gear unit.
- Thoroughly clean the output shafts and the flange surfaces, so that they are free
  from anti-corrosion agents, dirt, or the like. Do not use compressed air. Use a mild
  commercially available solvent. Do not expose the sealing lips of the oil seals to
  the solvent.
- In the case of operation outdoors, the drives must not be exposed to direct sunlight. Install an appropriate protection device, e.g. a cover or a canopy. The protection device must not cause heat build-up.
- Protect the gear unit against icing, because otherwise the seals may suffer damage.
- When the drive is installed in abrasive ambient conditions, protect the output end oil seals against wear.
- Protect the gear unit from cold air flows. Condensed water in the gear unit can cause damage.
- Mount the drive in such a way that sufficient ventilation is guaranteed after installation.
- Make sure that the nameplate is legible after assembly.

### 4.2 Required tools and resources

- · Set of wrenches
- Torque wrench
- Mounting device (recommended)
- · Compensation elements (e.g. shims, spacer rings, etc.), if necessary
- · Fixing devices for input and output elements
- · Set of Allen keys
- Sealant (e.g. LOCTITE<sup>®</sup> 573 or 574)
- Thread locking compound (e.g. LOCTITE® 243)

#### 4.2.1 Installation tolerances

For the tolerances, refer to the dimension sheet included in the product delivery. Contact SEW-EURODRIVE, if necessary.

## 4.3 Mounting the motor to the gear unit

#### **INFORMATION**

i

Observe the operating instructions of the motor.

#### **INFORMATION**

i

Observe the safety and processing instructions of the used thread locking adhesive.

#### 4.3.1 Motor mounting using an H. adapter

#### NOTICE



Damage to the adapter due to penetration of moisture or dirt (e.g. dust) during the attachment of a motor or an input component.

Damage to the adapter.

 If the motor being attached or the input component has openings or holes with access to the interior of the adapter, seal them so that they are dustproof and liguidproof.

#### **NOTICE**

Affected friction coefficient due to cleaning agent sprayed on the clamping hub. Malfunctions.

Spray the cleaning agent onto a cloth to clean the clamping hub.

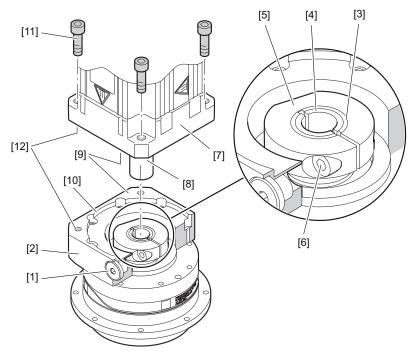


#### **INFORMATION**



In case of gear units with grease lubrication, small amounts of lubricant may escape (sweat out). SEW-EURODRIVE recommends sealing the surfaces between adapter flange and adapter housing, as well as between adapter flange and motor using a suitable sealing compound (e.g. LOCTITE® 573 or 574).

The following figure shows an example for mounting a motor to adapter H.:



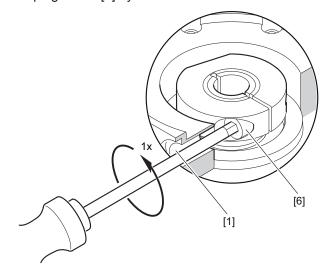
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- [1] Mounting bore with screw plug
- [2] Adapter flange
- [3] Adapter shaft
- [4] Coupling sleeve (if available)
- [5] Clamping ring
- [6] Clamping screw

- [7] Motor flange
- [8] Motor shaft
- [9] Flange contact surface
- [10] Flange centering
- [11] Connection screws
- [12] Connection bores
- ✓ Important information Mount the motor in a vertical position if possible. The drive component with the lighter weight (either motor or gear unit) must be mounted in the top position. You can perform the assembly in a different location only if the application or space circumstances do not permit the standard position.
- ✓ Important information regarding corrosion-resistant gear units Check that the sealing surfaces are aligned prior to mounting the motor. Use a sealant (such as Loctite® 573) to prevent leakage. SEW-EURODRIVE offers a suitable sealing plate to cover the screws as an option.
- ✓ To avoid tensions due to misalignments, you must support the motor and align the
  motor shaft.
- √ The motor must demonstrate at least true-running, face runout, and coaxiality accuracy level "N" to DIN 42955.



- 1. A WARNING! Risk of injury if the drive starts up unintentionally. Severe or fatal injuries. Disconnect the drive from the power supply before you start work. Prevent the drive from starting up unintentionally, for example by locking the key switch or removing the fuses from the current supply. Set up a caution sign to warn that it is forbidden to switch the drive on.
- 2. Check the flange surfaces [9] of the motor and adapter for possible scoring and smoothen them if necessary.
- 3. Clean, degrease and dry the following drive components. Use a grease-dissolving, non-aggressive cleaning agent:
  - ⇒ The hollow shaft bore of the adapter shaft [3]
  - ⇒ The coupling sleeve [4] (if available)
  - ⇒ The motor shaft [8]
  - ⇒ The flange contact surfaces of motor and adapter [9]
  - ⇒ The flange centering of motor and adapter [10]
- 4. Remove the screw plug from the mounting bore [1] at the adapter flange [2].
- 5. Turn the adapter shaft [3] with clamping ring [5] until the screw head of the clamping screw [6] can be accessed via the mounting bore [1] in the adapter housing.
- 6. Loosen the clamping screw [6] by 1 turn.

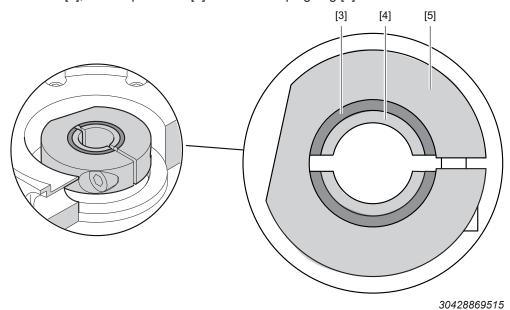


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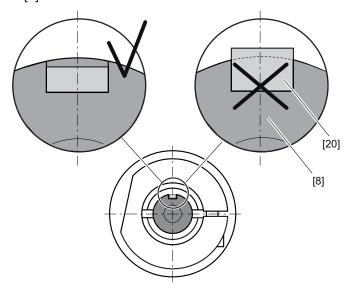
- [1] Mounting bore
- [6] Clamping screw



7. When using coupling sleeves [4], make sure to align the slots in the coupling sleeve [4], the adapter shaft [3] and the clamping ring [5].



- [3] Adapter shaft
- [4] Coupling sleeve (if available)
- [5] Clamping ring
- 8. For motors with a keyway: SEW-EURODRIVE recommends to insert a half key into the keyway to compensate imbalance. The key half must not protrude out of the groove in the motor shaft extension. Turn the keyway by 90° to the slots in the adapter shaft [3].

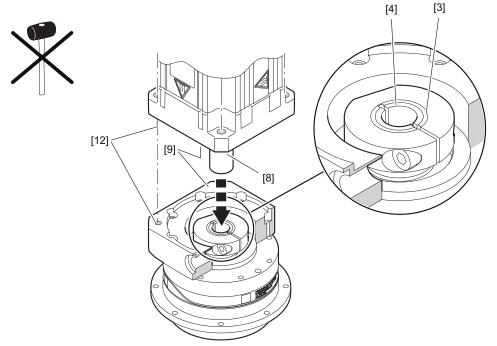


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[8] Motor shaft [20] Half key

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9. Carefully and without using force insert the motor shaft [8] into the hollow shaft bore of the adapter shaft [3] until the flange contact surfaces [9] of motor and adapter touch. The connection bores [12] must be positioned above each other.

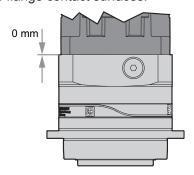


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- [3] Adapter shaft
- [4] Coupling sleeve (if available)
- [8] Motor shaft

- [9] Flange contact surfaces
- [12] Connection bores

⇒ No gap between the flange contact surfaces:



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- 10. Coat the 4 connection screws [11] for motor mounting with a threadlocker (e.g. LOCTITE® 243). Select the screws according to the specifications of the motor manufacturer. Observe the minimum screw-in depth according to the strength class (see chapter "Minimum screw-in depth for motor mounting" (→ ≜ 21)).
- 11. Insert the connecting screws [11] into the tapped holes of the adapter flange [2] via the through bores of the motor flange. Evenly tighten the connection screws in diametrically opposite sequence with increasing torque, as specified by the motor manufacturer.



- 12. Tighten the clamping screw [6] to the specified tightening torque using a suitable torque wrench¹¹. For the required tightening torque, refer to the table "Tightening torques for clamping screws" (→ 

  21) or to the clamping ring.
- 13. Close the assembly bore [1] again with the relevant screw plug. You can find the required torque in chapter "Tightening torques for the screw plug" ( $\rightarrow \mathbb{B}$  21).

#### 4.3.2 Minimum screw-in depth for motor mounting

	Strength class of the screws <sup>1)</sup>						
	8.8	10.9					
Minimum screw-in depth	1.5 × screw Ø	1.8 × screw Ø					

<sup>1)</sup> Strength class according to the specifications of the motor manufacturer

For the maximum screw-in depth in the adapter flange, and for the screw diameter, refer to the respective dimension sheet.

#### 4.3.3 Tightening torques for clamping screws

	Clamping screw wrench size in mm								
	3	4	5	6	8	10	14		
Tightening torque <sup>1)</sup> in Nm	4.2	8.3	14	35	68	117	285		

<sup>1)</sup> Refer to the clamping ring for the tightening torque.

All values are calculated to VDI 2230, based on the following conditions:

The friction coefficient for threads in strength class 8.8 is  $\mu$  = 0.14, and in strength classes 10.9 and 12.9 it is  $\mu$  = 0.09 (to VDI 235-101). The level of utilization is 90% of the elastic limit, and signal-generating torque wrenches or motor torque wrenches with dynamic torque measurement are used as tools.

#### 4.3.4 Tightening torques for the screw plug

			Screw thread								
	Unit	M8 × 1	M10 × 1	M12 × 1.5	M16 × 1.5	M22 × 1.5	M26 × 1.5				
Wrench size	mm	4	5	6	6	10	12				
Tightening torque	Nm	8	12	15	40	60	80				

## 4.4 Mounting the gear unit to a machine

Customer construction

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The customer construction must have the following characteristics:

- Level
- · Vibration damping
- · Torsionally rigid

The maximum permitted flatness error applies to flange mounting (guide values with reference to DIN ISO 1101):

Gear unit sizes P..G21 – 72: max. 0.2 mm



<sup>1)</sup> Signal-generating torque wrenches or motorized torque wrenches with dynamic torque detection

## 4

#### **Mechanical installation**

Mounting the gear unit to a machine

Corrosion protection

Electrochemical corrosion occurs between various metals, for example, cast iron and stainless steel. Use plastic inserts (2 - 3 mm thick) if there is a risk of electrochemical corrosion between the gear unit and the driven machine. The material used must have an electrical leakage resistance <  $10^{9}\,\Omega$ . If necessary, insert the install the screws with plastic washers. Use the grounding screws on the motor housing to ground the motor.

Thread locking compound

Coat the retaining screws with a threadlocker e.g. LOCTITE® 243. Observe the safety and processing notes of the used thread locking compound.

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#### 4.4.1 Mounting on the output end

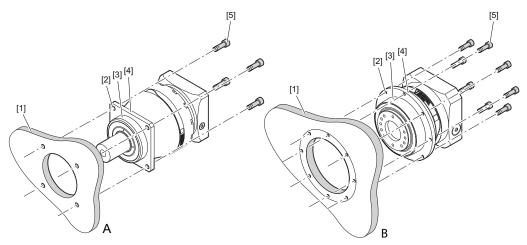
#### **A CAUTION**

Gear unit overload due to insufficient centering in the machine bed.

Destruction of the gear unit.

 Center the gear unit with as little play as possible in the machine bed using the centering collar.

The figures illustrate the basic procedure for mounting the gear unit at the output end.



- A Output design: solid shaftW Output design: Flange block
- [1] Machine bed with tapped holes or through bores
- [2] Mounting bores
- [3] Output-end centering collar
- [4] Gear unit housing
- [5] Retaining screws

#### ✓ ▲ WARNING!

Risk of injury if the drive starts up unintentionally. Severe or fatal injuries. Disconnect the drive from the power supply before you start work. Prevent the drive from starting up unintentionally, for example by locking the key switch or removing the fuses from the current supply. Set up a sign to warn that it is forbidden to switch the drive on.

- ✓ Observe the notes in chapter "Prerequisites for installation" ( $\rightarrow$  15).
- 1. Center the gear unit with as little play as possible in the machine bed.
- 2. Coat the retaining screws with a threadlocker e.g. LOCTITE® 243.
- 3. Mount the gear unit to the machine bed via the mounting bores. Using through bores and nuts is also permitted as an alternative to direct screw connections with threaded holes.
- 4. Tighten the screws evenly, in several stages, and with increasing torque using a suitable tool.¹) For the suitable screw sizes and tightening torques, refer to chapter "Screw sizes for the gear units" (→ 🖹 24).



<sup>1)</sup> Signal-generating torque wrench or a motor torque wrench with dynamic torque measurement.

#### Screw sizes for the gear units

The following table shows the tightening torques of the gear unit retaining screws. The information refers to design 0 (standard), refer to chapter "Sample type designation" ( $\rightarrow$  14). For deviating designs, refer to the information in the order documents or on the dimension sheet.

Type designation <sup>1)</sup>	Size	Mounting bore Number of screws × Ø	Screw size <sup>2)</sup>	Tightening torque <sup>2)</sup>		
		mm		Nm		
	2	4 × 5.5	M5	8.3		
	3	4 × 6.6	M6	14		
P5NG, P6NG, P5KG, P6KG,	4	4 × 9	M8	35		
P5VG, P6VG	5	4 × 11	M10	68		
	6	4 × 13.5	M12	117		
	7	4 × 17	M16	285		
	2	8 × 4.5	M4	4.2		
	3	8 × 5.5	M5	8.3		
P5BG, P6BG,	4	8 × 5.5	M5	8.3		
P5CG, P6CG	5	12 × 6.6	M6	14		
	6	12 × 9	M8	35		
	7	16 × 13.5	M12	117		
	2	16 × 4.5	M4	4.2		
	3	16 × 5.5	M5	8.3		
P7BG	4	16 × 5.5	M5	8.3		
r / bG	5	24 × 6.6	M6	14		
	6	24 × 9	M8	35		
	7	32 × 13.5	M12	117		

- 1) See chapter "Output designs" ( $\rightarrow \mathbb{B}$  12).
- 2) Strength class 12.9.

All values are calculated to VDI 2230, based on the following conditions:

The friction coefficient for threads in strength class 8.8 is  $\mu$  = 0.14, and in strength classes 10.9 and 12.9 it is  $\mu$  = 0.09 (to VDI 235-101). The level of utilization is 90% of the elastic limit, and signal-generating torque wrenches or motor torque wrenches with dynamic torque measurement are used as tools.

#### 4.4.2 Mounting to the gear unit backside

#### **A** CAUTION

Gear unit overload due to insufficient centering in the machine bed.

Destruction of the gear unit.

 Center the gear unit with as little play as possible in the machine bed using the centering collar.



#### **A CAUTION**

Damage to the gear unit caused by removing the adapter housing.

Gear unit damage.

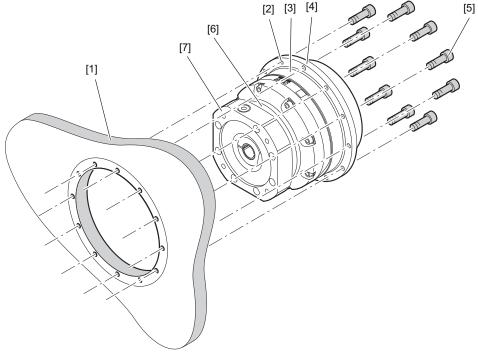
 Do not remove the adapter housing. It may be necessary to contact SEW-EURODRIVE. Disassembly renders any rights to claim under limited warranty null and void. Only the adapter flange may be disassembled to allow for rear attachment or replacement.

Mounting the gear unit backside to a machine is only possible in flange block design. In addition, the largest diameter of the adapter housing must be smaller than the centering collar on the backside of the gear unit housing. For the specified dimensions, refer to the dimension sheets.

The adapter housing must not be removed. Otherwise, the rights to claim under limited warranty become void.

Observe the notes in chapter "Prerequisites for installation" ( $\rightarrow \mathbb{B}$  15).

The following figure shows the basic procedure for mounting the gear unit backside to a machine. For this procedure, the diameter of the adapter flange needs to be smaller that the diameter of the centering collar on the backside of the gear unit housing. For the specified dimensions, refer to the dimension sheet.



9007227482502667

- [1] Machine bed with tapped holes or through bores
- [2] Mounting bores
- [3] Backside centering collar
- [4] Gear unit housing
- [5] Retaining screws
- [6] Adapter housing
- [7] Adapter flange



#### ✓ ▲ WARNING!

Risk of injury if the drive starts up unintentionally. Severe or fatal injuries. Disconnect the drive from the power supply before you start work. Prevent the drive from starting up unintentionally, for example by locking the key switch or removing the fuses from the current supply. Set up a sign to warn that it is forbidden to switch the drive on.

- 1. Center the gear unit with as little play as possible in the machine bed [1].
- 2. Coat the retaining screws [5] with a threadlocker e.g. LOCTITE® 243.
- 3. Mount the gear unit to the machine bed via the mounting bores. Using through bores and nuts is also permitted as an alternative to direct screw connections with threaded holes.
- 4. Tighten the screws evenly, in several stages, and with increasing torque using a suitable tool.¹¹ For the suitable screw sizes and tightening torques, refer to chapter "Screw sizes for the gear units" (→ 24).
- 1) Signal-generating torque wrench or a motor torque wrench with dynamic torque measurement.

#### Removal/installation of the adapter flange

#### **A CAUTION**

Damage to the gear unit, if the gear unit is operated without an adapter flange. Gear unit damage.

Operation without an adapter flange is not permitted. Ideal operation is guaranteed only with the SEW adapter flange.

#### INFORMATION



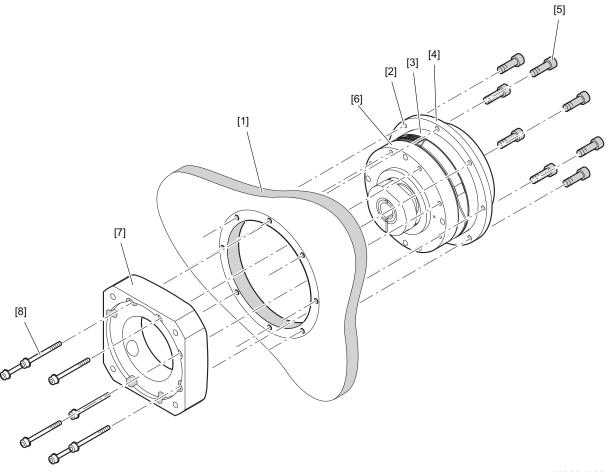
In case of gear units with grease lubrication, small amounts of lubricant may escape (sweat out). SEW-EURODRIVE recommends sealing the surfaces between adapter flange and adapter housing, as well as between adapter flange and motor using a suitable sealing compound (e.g. LOCTITE® 573 or 574).

In case the diameter of the adapter flange is larger than the diameter of the backside centering collar, the adapter flange must be removed before the gear unit backside can be mounted to the machine. For the specified dimensions, refer to the dimension sheets.

The adapter housing must not be removed! Otherwise, the rights to claim under limited warranty become void.



The following figure shows the basic procedure for mounting the gear unit backside to a machine. For this procedure, the diameter of the adapter flange is larger that the diameter of the centering collar on the backside of the gear unit housing. For the specified dimensions, refer to the dimension sheets.



28228132875

- [1] Machine bed with tapped holes or through bores
- [2] Mounting bores
- [3] Backside centering collar
- [4] Gear unit housing
- [5] Retaining screws
- [6] Adapter housing
- [7] Adapter flange
- [8] Adapter flange retaining screws
  - ✓ Make sure that the adapter flange is mounted in the same position as before it has been removed.
  - 1. Loosen the screws [8] of the adapter flange [7]. Memorize the position of each screw in the adapter flange.
  - 2. Clean the screws or use new, suitable screws. Contact SEW-EURODRIVE, if required.
  - 3. Carefully remove the adapter flange.
  - 4. Guide the gear unit through the centering in the machine bed [1] with the backside first.
  - 5. Coat the retaining screws [5] with a threadlocker e.g. LOCTITE® 243.



- 6. Evenly tighten the screws in several turns with increasing torque using a suitable tool¹). For the suitable screw sizes and tightening torques, refer to chapter "Screw sizes for the gear units" (→ 🖺 24).
- 7. Mount the adapter flange in it's initial position (before removal).
- 8. Coat the adapter flange screws with a threadlocker (e.g. LOCTITE® 243). Insert the screws into their initial fastening bores of the adapter flange.
- 9. Evenly tighten the screws (of strength class 10.9) in several turns with increasing torque using a suitable tool<sup>1)</sup>. For the suitable tightening torques depending on the screw size, refer to chapter "Standard tightening torques" (→ 28).
- 1) Signal-generating torque wrenches or motorized torque wrenches with dynamic torque detection

#### Standard tightening torques

The following table lists the tightening torques for common thread sizes of shank screws and nuts (as used in general mechanical engineering).

Strength class of screw/nut	М3	M4	M5	М6	M8	M10	M12	M16	M20	M24
8.8/8	1.5	3.4	6.7	12	28	56	96	235	460	795
10.9/10	1.5	3.5	6.9	12	29	57	98	235	465	800
12.9/12	1.8	4.2	8.3	14	35	68	117	285	557	960

All values are calculated to VDI 2230, based on the following conditions:

The friction coefficient for threads in strength class 8.8 is  $\mu$  = 0.14, and in strength classes 10.9 and 12.9 it is  $\mu$  = 0.09 (to VDI 235-101). The level of utilization is 90% of the elastic limit, and signal-generating torque wrenches or motor torque wrenches with dynamic torque measurement are used as tools.

## 4.5 Mounting the output elements to the output shaft

#### **▲ WARNING**



Risk of injury if the drive starts up unintentionally.

Severe or fatal injuries.

- Disconnect the drive from the power supply before you start work.
- Prevent the drive from starting up unintentionally, for example by locking the key switch or removing the fuses from the current supply, and set up a prohibition sign to prevent a restart.

#### **A** CAUTION



Risk of injury due to moving drive and output elements such as belt pulleys or couplings.

Risk of jamming and crushing.

· Cover the moving drive and output elements with a touch guard.



#### 4.5.1 Mounting output elements onto solid shafts



#### **A CAUTION**

The bearing, housing, or shaft may be damaged due to improper assembly. Possible damage to property.

- Use a mounting device for installing input and output elements if possible. Use the centering bore and the thread on the shaft end for positioning.
- Push all mount-on components (belt pulleys, couplings, pinions etc.) onto the shaft end without force.
- When installing the belt pulleys, make sure the belt is tensioned correctly in accordance with the manufacturer's instructions.
- Make sure the mounted transmission elements are balanced to prevent impermissible radial or axial forces.

#### Maximum permitted static axial forces at the output shaft

The following table lists the maximum permitted static axial forces  $F_{A\_stat\_max}$  (axial forces at standstill), that may not be exceeded when a mount-on component is pushed or shrunk onto the output shaft. The values apply to a shaft unaffected by any radial loads ( $F_R = 0$ ).

For the applicable bearing type, refer to the oder documents.

Type designation <sup>1)</sup>	Size	F <sub>A_stat_max</sub> in N		
		Bearing type 1	Bearing type 2	
	3	12000	2000	
P.NG, P.KG, P.VG	4	20250	3550	
	5	34500	6250	

1) See chapter "Output designs" ( $\rightarrow \mathbb{B}$  12).



#### Mounting the gear unit - Solid shaft design with smooth output shaft

#### **A CAUTION**

Insufficient shaft-hub connection with the use of clamping sets on a smooth shaft end due to greasy or dirty shaft.

Malfunction.

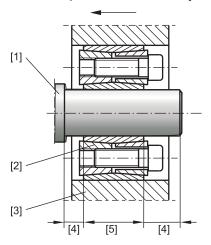
• Make sure the clamping area [5] is free of dirt and grease. Otherwise the shafthub connection may not function properly.

#### **INFORMATION**



The shaft collar [1] can be used as defined stop for mounting output elements onto the solid shaft.

The following figures shows an example of shaft assembly with inner clamping set:



1839232907

- [1] Shaft shoulder
- [2] Clamping set
- [3] Output element, e. g. gear or sprocket
- [4] Greased shaft areas
- [5] Ungreased clamping area

Grease accessible areas [4] of the shaft after mounting.

#### Mounting the gear unit - Solid shaft design with key or splined solid shaft design

#### INFORMATION



If you mount your gear unit in another way than described in the mounting example given in this chapter, observe the specifications on maximum permitted static axial forces in chapter "Maximum permitted static axial forces at the output shaft" ( $\rightarrow \mathbb{B}$  29).

#### **INFORMATION**



For reversing operation, also observe the notes on required output elements in the applicable project planning documents and dimension sheets.

For mounting customer output elements, SEW-EURODRIVE recommends using a smaller hub fit and/or adhesive (e.g. LOCTITE® 243) to secure the hub additionally.

#### **INFORMATION**



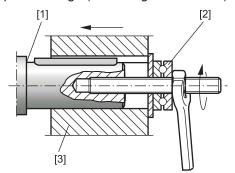
The shaft collar [1] can be used as defined stop for mounting output elements onto the solid shaft.

#### **INFORMATION**



Mounting is easier if you first apply lubricant to the output element or heat it up  $(80 - 100 \, ^{\circ}\text{C})$ .

The following figure shows the example of a mounting device used to push hubs [3] onto gear shaft ends. The axial bearing [2] on the mounting device is optional. The figure also applies to the splined design (according to DIN 5480).



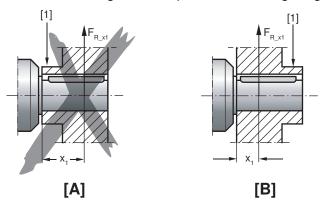
1839217419

- [1] Shaft shoulder
- [2] Thrust bearing
- [3] Hub



#### Avoiding high radial loads

To avoid high radial loads, mount gears and sprockets according to figure B.



9007199466105227

[1] Hub

[A] Incorrect assembly

 $F_{R_{-}X1}$  Radial load at position  $x_1$  [B] Correct assembly

### 4.5.2 Mounting the output elements to the flange block shaft

- 1. Clean and degrease the flange surfaces.
- 2. Tighten the screws evenly, in several stages, and with increasing torque. For the respective maximum screw-in depth and the tightening torques, refer to the following table.

The table refers to the design 0 (Standard); see chapter "Sample type designation" ( $\rightarrow$   $\bigcirc$  14). In the case of a different design, refer to the respective order documents or dimension sheet.

Type designation <sup>2)</sup>	Size N	Number of screws × screw size <sup>1)</sup>	Screw-in depth		Tightening
			Minimum	Maximum	torque <sup>1)</sup>
			mm	mm	Nm
	2	8 × M5	5	7	8.3
	3	8 × M6	6	10	14
P5BG,	4	12 × M6	6	12	14
P6BG	5	12 × M8	8	15	35
	6	12 × M10	10	20	68
	7	12 × M16	16	31	285
	2	7 × M5	5	7	8.3
	3	7 × M6	6	10	14
P5CG,	4	11 × M6	6	12	14
P6CG <sup>3)</sup>	5	11 × M8	8	15	35
	6	11 × M10	10	20	68
	7	11 × M16	16	31	285

Type designation <sup>2)</sup>	Size	Number of screws ×	Screw-in depth		Tightening
		screw size <sup>1)</sup>	Minimum	Maximum	torque <sup>1)</sup>
			mm	mm	Nm
P7BG	2	10 × M5	5	7	8.3
	3	12 × M6	6	10	14
	4	12 × M8	8	12	35
	5	12 × M10	10	15	68
	6	12 × M12	12	19	117
	7	12 × M20	20	31	557

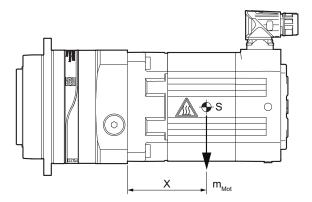
- 1) Strength class 12.9.
- 2) See chapter "Output designs" ( $\rightarrow$  12).
- 3) For the geometry of the index bore, refer to the dimension sheet.

All values are calculated to VDI 2230, based on the following conditions:

The friction coefficient for threads in strength class 8.8 is  $\mu$  = 0.14, and in strength classes 10.9 and 12.9 it is  $\mu$  = 0.09 (to VDI 235-101). The level of utilization is 90% of the elastic limit, and signal-generating torque wrenches or motor torque wrenches with dynamic torque measurement are used as tools.

#### 4.6 Maximum permitted motor weight

The following figure shows the center of mass of the motor at the example of a motor by SEW-EURODRIVE.



- [S] Center of mass of the motor
- [x] Distance from the adapter flange to the center of mass of the motor

 $m_{\mbox{\scriptsize Mot}}$  Maximum permitted motor weight referring to x for stationary applications

Strictly adhere to the specified distances and masses in the following table to prevent overload on the connection screws.

The following table shows the maximum permitted motor mass referring to the distance from the center of gravity and adapter flange at the example of a motor from SEW-EURODRIVE.

If the motor weight is increased in stationary applications, you must reduce the distance to center in linear fashion. If the motor weight is reduced, you can increase the distance to center in linear fashion.

Size	Ø of the adapter shaft <sup>1)</sup>	Example: Motor by	Distance x	Maximum permitted motor mass m <sub>Mot</sub> in relation to x		
		SEW-EUR ODRIVE		P.BG, P.CG <sup>2)</sup>	P.NG, P.KG, P.VG <sup>2)</sup>	
	mm		mm		kg	
21	11 – 14	CMP63L	144	39	56	
21	19	CM71L	165	60	85	
22	11	CMP50L	120	75	76	
22	14	CMP63L	144	70	71	
31	14 – 19	CM71L	165	43	60	
31	24	CMP71L	137	85	119	
32	11 – 14	CMP63L	144	59	64	
32	19	CM71L	165	82	98	
41	19 – 28	CMP80L	167	116	106	
41	32 – 38	CMP112E	302	137	124	
42	14 – 19	CM71L	165	96	93	
42	24 – 28	CMP80L	167	200	197	
43	11 – 14	CMP63L	144	69	-	
43	19	CM71L	165	109	-	
51	24 – 38	CMP112E	302	261	261	
51	48	CMP112E	302	249	249	
52	19 – 28	CMP80L	167	196	196	
52	32 – 38	CMP112E	302	250	250	
53	14 – 19	CM71L	165	109	-	
53	24 – 28	CMP80L	167	184	-	
61	38 – 48	CMP112E	302	471	471	
61	55	CMP112E	302	455	455	
62	24 – 38	CMP112E	302	201	201	
62	48	CMP112E	302	440	440	
71	55	CMP112E	302	1011	1011	
72	38 – 48	CMP112E	302	367	367	
72	55	CMP112E	302	373	373	

<sup>&</sup>lt;sup>1)</sup> For the adapter shaft diameter, refer to the order documents.

 $<sup>^{2)}</sup>$  See chapter "Output designs" ( $\rightarrow$   $\$ 12).

i

## **INFORMATION**

The mass specifications in the table apply to stationary applications only. For mobile applications (e.g. travel drives), use the conversion formula below or consult SEW-EURODRIVE.

Conversion formula<sup>1)</sup> for calculating the maximum permitted motor mass in mobile applications:

$$m_{Mot\_dyn} = m_{Mot} \times \frac{g}{g+a}$$

$m_{\text{Mot\_dyn}}$	<ul> <li>Maximum permitted mass of the motor in mobile applications</li> </ul>	$[m_{Mot\_dyn}] = kg$
$m_{\text{Mot}}$	<ul> <li>Maximum permitted mass of the motor in stationary applications</li> </ul>	$[m_{Mot}] = kg$
g a	= Simple gravitational acceleration (9.81 m s <sup>-2</sup> ) = Acceleration of the mobile application	[g] = m s <sup>-2</sup> [a] = m s <sup>-2</sup>

<sup>1)</sup> Simplified, without consideration of the direction of acceleration and the mounting position.

## 5 Startup



#### **A WARNING**

Uncontrolled behavior in test mode.

Severe or fatal injuries.

- Secure the key in test mode without drive components.
- Also activate all the monitoring and protection devices in test mode.

#### NOTICE

Gear unit damage due to overheating of the lubricant.

Gear unit damage.

- · Check the surface temperature during startup.
- If the surface temperature exceeds 90 °C, stop the drive and contact SEW-EURODRIVE.



#### **A CAUTION**

The surfaces of the drive can be very hot during operation.

Risk of burns.

- Make sure that hot surfaces cannot be touched unintentionally or during normal operation. Install covers or warning signs according to regulations.
- · Let the motor cool down sufficiently before you start working on it.

Observe the following points during startup:

- In the event of unusual noises or vibrations, switch the gearmotor off. Determine the cause. It may be necessary to contact SEW-EURODRIVE.
- Operate the device only within the specified maximum limit values according to the order documents. It may be necessary to contact SEW-EURODRIVE.
- The permitted range for the ambient temperature is between -15 °C and +40 °C.
- The application environment should be dustfree as far as possible.
- Protect the gear unit against icing, because otherwise the seals may suffer damage.

## 5.1 Measuring the surface temperature

It is essential to measure the surface temperature at maximum load when starting up the gear unit. Commercially available thermometers can be used to measure the temperature.

Measure the surface temperature at the joint between gear unit and adapter, and at the joint between adapter and motor. The maximum surface temperature is reached after approx. 3 hours. It must not exceed a value of 90  $^{\circ}$ C.



# 6 Inspection/maintenance



#### **A WARNING**

Risk of injury if the drive starts up unintentionally.

Severe or fatal injuries.

- Disconnect the drive from the power supply before you start working on the unit.
- Prevent the drive from starting up unintentionally for example, by locking the key switch or removing the fuses from the current supply, and attach a warning sign that prohibits switching on the drive.



#### **A WARNING**

Unsecured key skidding out of the keyway.

Severe or fatal injuries due to flying parts.

 Only operate the motor with attached customer output element (e.g. gear unit), or with a suitably secured key.



#### **A WARNING**

Risk of injury if preloaded shaft connections are loosened.

Severe or fatal injuries.

 Before releasing any shaft connections, make sure there is no active torsional torque present that could lead to tension within the system.



#### **A CAUTION**

The surfaces of the drive can be very hot during operation.

Risk of burns.

- Make sure that hot surfaces cannot be touched unintentionally or during normal operation. Install covers or warning signs according to regulations.
- Let the motor cool down sufficiently before you start working on it.



#### **▲ CAUTION**

Risk of slipping and hazard for the environment due to spilled or leaked lubricant. Injuries and environmental hazard.

 Absorb any leaked or spilled lubricant with a suitable binding agent. Dispose of the mixture in accordance with the regulations.

#### NOTICE

Damage to oil seal caused by cleaning the gear unit with a high pressure device. Gear unit damage.

• Do not clean the gear unit with a high-pressure cleaning device.

### **NOTICE**

Damage to gear unit due to ingress of foreign objects during maintenance and inspection work.

Gear unit failure.

• Prevent foreign particles from entering into the gear unit during maintenance and inspection work.

### **INFORMATION**



Perform a safety check and functional check following maintenance and repair work.

## 6.1 Inspection and maintenance intervals

#### **INFORMATION**



Maintain the inspection and maintenance intervals. This is necessary to ensure operational safety.

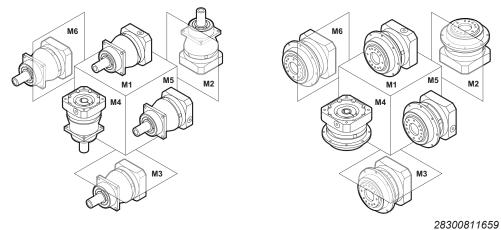
Time interval	What to do?
500 operating hours or 3 months after startup	Visual inspection for external damage and leakage at the seals.
	• Check the tightening torque of the clamping screws for the clamping ring. For the applicable tightening torque, refer to the table "Tightening torques for clamping screws" (→ ■ 21) or to the clamping ring.
	<ul> <li>Check the tightening torques of the screw connections between gear unit and machine (→   24) and between output elements and output shaft (→   32).</li> </ul>
Every 3 months	Visual check for external dam- ages and leakage at the seals.
• Annually	Check the tightening torque of the clamping screws for the clamping ring. For the applicable tightening torque, refer to the table "Tightening torques for clamping screws" (→      21) or to the clamping ring.
	<ul> <li>Check the tightening torques of the screw connections between gear unit and machine (→   24) and between output elements and output shaft (→  32).</li> </ul>

#### 6.2 Lubricants

All gear units are lubricated for life and filled at the factory with a high-quality synthetic lubricant from the SEW GearOil Poly E1 or SEW Grease HL2 E1 series. Both lubricants are also available for applications in the food industry (NSF H1).

# 7 Mounting positions

The following figure shows the mounting positions M1 – M6 by SEW-EURODRIVE.



Mount the gear unit in the mounting position as stated in the order documentation. The mounting position can be freely selected unless specified otherwise.

## 8 Technical data

# 8.1 Gear unit weight

The table specifies the maximum weight of the gear unit depending on the size. The actual weight may be lower, depending on the design. Refer to the nameplate for the actual weight.

Maximum mass	Size					
kg	21	31	41	51	61	71
P.NG.1, P.KG.1, P.VG.1 <sup>1)</sup>	3.0	6.5	14	25	55	72
P.BG.1, P.CG.1 <sup>1)</sup>	2.5	6.5	13	21	46	69

Maximum mass	Size					
kg	22	32	42	52	62	72
P.NG.2, P.KG.2, P.VG.2 <sup>1)</sup>	3.0	5.0	12	23	51	76
P.BG.2, P.CG.2 <sup>1)</sup>	2.5	5.0	11	22	42	73

Maximum mass	Size	
kg	43	53
P7BG.3 <sup>1)</sup>	7.5	17.7

<sup>1)</sup> See chapter "Output designs" ( $\rightarrow$  12).

#### **Malfunctions** 9

#### 9.1 Gear unit malfunctions

Fault	Possible cause	Measure
Unusual, increased operating noise.	Evenly meshing/grinding noise:     Bearing damage or strain on motor mounting	Contact SEW-EURODRIVE.
	Evenly knocking noise: Damage to gearing	Contact SEW-EURODRIVE.
	Incorrect controller setting	Check the controller settings.
Loss of lubricant <sup>1)</sup> at the	Seal defective	Contact SEW-EURODRIVE.
<ul> <li>Adapter</li> </ul>	Increased internal pressure	Check that the air supply is unhindered.
Oil seal on the out-		Check the design.
put end		Check the wiring of the motor.
		Check the cooling of the motor.
		Check the ambient temperature.
		Contact SEW-EURODRIVE.
Increased operating temperature (> 90 °C)	Restricted air supply	Ensure unrestricted air supply and/or contact SEW-EURODRIVE.
	Speed/torque is too high	Check the configuration.
		Contact SEW-EURODRIVE.
	The motor heats up the gear unit	Check the configuration.
		Check the motor connection.
		Cool the motor.
		Contact SEW-EURODRIVE.
	Ambient temperature too high	Lower the ambient temperature.
		Check the configuration.
		Contact SEW-EURODRIVE.

<sup>1)</sup> Short-term lubricant leakage at the adapter or the oil seal is possible in the run-in phase (48 hours running time).

Have the following information available when you contact the SEW-EURODRIVE Service:

- All nameplate data
- Type and extent of the malfunction
- Time the problem occurred and any accompanying circumstances
- Assumed cause
- Digital photo, if applicable



# 10 Waste disposal

Dispose of the product and all parts separately in accordance with their material structure and the national regulations. Put the product through a recycling process or contact a specialist waste disposal company. If possible, divide the product into the following categories:

- · Iron, steel or cast iron
- Stainless steel
- Aluminum
- Copper
- Electronic parts
- Magnets
- Plastics

The following materials are hazardous to health and the environment. These materials must be collected and disposed of separately.

Oil and grease

Collect used oil and grease separately according to type. Ensure that the used oil is not mixed with solvent. Dispose of used oil and grease correctly.

# 11 Address list

Argentina			
Assembly Sales	Buenos Aires	SEW EURODRIVE ARGENTINA S.A. Ruta Panamericana Km 37.5, Lote 35 (B1619IEA) Centro Industrial Garín Prov. de Buenos Aires	Tel. +54 3327 4572-84 Fax +54 3327 4572-21 http://www.sew-eurodrive.com.ar sewar@sew-eurodrive.com.ar
Australia			
Assembly Sales Service	Melbourne	SEW-EURODRIVE PTY. LTD. 27 Beverage Drive Tullamarine, Victoria 3043	Tel. +61 3 9933-1000 Fax +61 3 9933-1003 http://www.sew-eurodrive.com.au enquires@sew-eurodrive.com.au
	Sydney	SEW-EURODRIVE PTY. LTD. 9, Sleigh Place, Wetherill Park New South Wales, 2164	Tel. +61 2 9725-9900 Fax +61 2 9725-9905 enquires@sew-eurodrive.com.au
Austria			
Assembly Sales Service	Vienna	SEW-EURODRIVE Ges.m.b.H. Richard-Strauss-Straße 24 1230 Wien	Tel. +43 1 617 55 00-0 Fax +43 1 617 55 00-30 http://www.sew-eurodrive.at sew@sew-eurodrive.at
Bangladesh			
Sales	Bangladesh	SEW-EURODRIVE INDIA PRIVATE LIMITED 345 DIT Road East Rampura Dhaka-1219, Bangladesh	Tel. +88 01729 097309 salesdhaka@seweurodrivebangladesh.com
Belarus			
Sales	Minsk	Foreign unitary production enterprise SEW- EURODRIVE RybalkoStr. 26 220033 Minsk	Tel. +375 17 298 47 56 / 298 47 58 Fax +375 17 298 47 54 http://www.sew.by sales@sew.by
Belgium			
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Service Competence Center	Industrial Gears	SEW-EURODRIVE n.v./s.a. Rue du Parc Industriel, 31 6900 Marche-en-Famenne	Tel. +32 84 219-878 Fax +32 84 219-879 http://www.sew-eurodrive.be info@sew.be
Brazil			
Production Sales Service	São Paulo	SEW-EURODRIVE Brasil Ltda. Estrada Municipal José Rubim, 205 – Rodovia Santos Dumont Km 49 Indaiatuba – 13347-510 – SP	Tel. +55 19 3835-8000 sew@sew.com.br
Assembly Sales Service	Rio Claro	SEW-EURODRIVE Brasil Ltda. Rodovia Washington Luiz, Km 172 Condomínio Industrial Conpark Caixa Postal: 327 13501-600 – Rio Claro / SP	Tel. +55 19 3522-3100 Fax +55 19 3524-6653 montadora.rc@sew.com.br
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Bulgaria			
Sales	Sofia	BEVER-DRIVE GmbH Bogdanovetz Str.1 1606 Sofia	Tel. +359 2 9151160 Fax +359 2 9151166 bever@bever.bg

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Service		Zeleni dol 10	Fax +385 1 4613-158
		10 000 Zagreb	kompeks@inet.hr
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Sales Service		Floriánova 2459 253 01 Hostivice	Fax +420 235 350 613 http://www.sew-eurodrive.cz
Service		255 01 HOSHVICE	sew@sew-eurodrive.cz
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Sales		Geminivej 28-30	Fax +45 43 9585-09
Service		2670 Greve	http://www.sew-eurodrive.dk
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Service	Vejle	SEW-EURODRIVE A/S	Tel. +45 43 9585 00
		Bødkervej 2 7100 Vejle	http://www.sew-eurodrive.dk sew@sew-eurodrive.dk
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Service		for Engineering & Agencies	Fax +202 44812685
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Service		B. P. 20185 67506 Haguenau Cedex	http://www.usocome.com sew@usocome.com
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France

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Lithuania			
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Luxembourg			
Representation: Belgiu	m		
Macedonia			
Sales	Skopje	Boznos DOOEL Dime Anicin 2A/7A 1000 Skopje	Tel. +389 23256553 Fax +389 23256554 http://www.boznos.mk
Malaysia			
Assembly Sales Service	Johor	SEW-EURODRIVE SDN BHD No. 95, Jalan Seroja 39, Taman Johor Jaya 81000 Johor Bahru, Johor West Malaysia	Tel. +60 7 3549409 Fax +60 7 3541404 sales@sew-eurodrive.com.my
Mexico			
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Sales Service	Puebla	SEW-EURODRIVE MEXICO S.A. de C.V. Calzada Zavaleta No. 3922 Piso 2 Local 6 Col. Santa Cruz Buenavista C.P. 72154 Puebla, México	Tel. +52 (222) 221 248 http://www.sew-eurodrive.com.mx scmexico@seweurodrive.com.mx
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Morocco			
Sales Service Assembly	Bouskoura	SEW-EURODRIVE Morocco SARL Parc Industriel CFCIM, Lot. 55/59 27182 Bouskoura Grand Casablanca	Tel. +212 522 88 85 00 Fax +212 522 88 84 50 http://www.sew-eurodrive.ma sew@sew-eurodrive.ma
Namibia			
Sales	Swakopmund	DB MINING & INDUSTRIAL SUPPLIES CC Einstein Street Strauss Industrial Park Unit1 Swakopmund	Tel. +264 64 462 738 Fax +264 64 462 734 anton@dbminingnam.com
Netherlands			
Assembly Sales Service	Rotterdam	SEW-EURODRIVE B.V. Industrieweg 175 3044 AS Rotterdam Postbus 10085 3004 AB Rotterdam	Tel. +31 10 4463-700 Fax +31 10 4155-552 Service: 0800-SEWHELP http://www.sew-eurodrive.nl info@sew-eurodrive.nl





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Sales	Region	Pureland Ind. Complex	Fax +1 856 845-3179			
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Zambia		Anh St, Ha Noi, Viet Nam				



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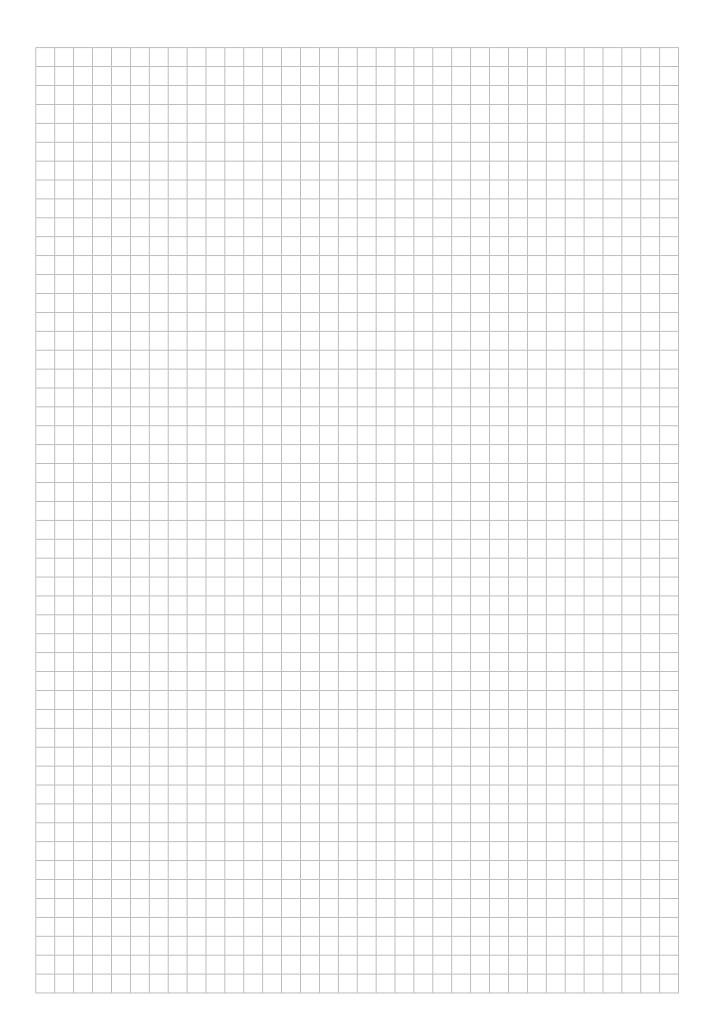
Installation

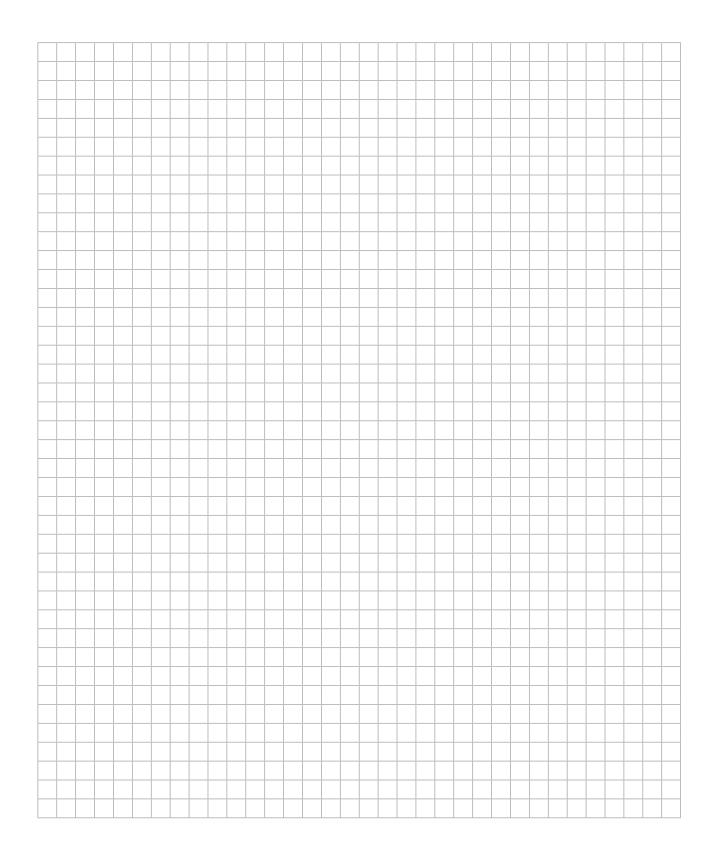
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