

## DRC.. electronic motor



### Compact design and flexible gear unit interface

- Permanent magnet synchronous motor with integrated electronics in housing with no fan
- Complete mechatronic drive system in conjunction with SEW-EURODRIVE's full modular gear unit system as option
- With mechanical holding brake as option

### DRC.. sizes

- DRC..1: Nominal torque 2.6 Nm; nominal power 0.55 kW
- DRC..2: Nominal torque 7.2 Nm; nominal power 1.5 kW
- DRC..3: Nominal torque 14.3 Nm; nominal power 3.0 kW
- DRC..4: Nominal torque 19.1 Nm; nominal power 4.0 kW

<b>Designs</b>	<ul style="list-style-type: none"> <li>– Stand-alone motor with IEC flange</li> <li>– Gearmotor with helical gear unit R, parallel-shaft helical gear unit F, helical-bevel gear unit K or SPIROPLAN® right-angle gear unit W</li> </ul>
<b>Speed setting range and positioning performance</b>	<ul style="list-style-type: none"> <li>– Standard control range 1:2000</li> <li>- Single-turn encoder /ECR</li> <li>- Multi-turn absolute encoder /ACR</li> </ul>
<b>Overload capacity</b>	<ul style="list-style-type: none"> <li>– Up to 250%</li> <li>– Prevents oversizing in static operation</li> <li>– Reduces installed size of necessary supply infrastructure</li> <li>– Integrated overload protection device</li> </ul> <p>Max. overload 250%</p> <p>Seconds Minutes Continuous duty</p> <p>Motor utilization in continuous operation up to 100%</p> <p>Legend:  <span style="color: red;">■</span> Torque of a conventional decentralized drive  <span style="color: black;">■</span> Torque of a mechatronic drive  <span style="color: blue;">■</span> Load profile of conveyor equipment</p>
<b>Installation topologies</b>	<ul style="list-style-type: none"> <li>– Binary or AS-Interface for easy drive functions</li> <li>– SBus for applications with higher performance requirements</li> <li>– SNI – just one cable for power supply and communication <ul style="list-style-type: none"> <li>- Local CSW maintenance switch</li> <li>- SNI I/O system CIO for decentralized processing of parameterizable inputs and outputs</li> </ul> </li> </ul>
<b>Application options</b>	Reading and processing of sensor signals decentralized and close to drive via GIO12B and GIO13B application options
<b>Brake option</b>	<ul style="list-style-type: none"> <li>– BY1C for DRC..1</li> <li>– BY2C for DRC..2</li> <li>– BY4C for DRC..3/4</li> </ul>
<b>Functional safety</b>	<ul style="list-style-type: none"> <li>– Integrated STO (Safe Torque Off) safety function according to IEC 61800-5-2</li> <li>– Performance level e according to EN ISO 13849-1</li> </ul>




### The global motor

<b>Certifications / conformity</b>	CE (Europe) / UL-approved (USA and Canada) / UkrSEPRO (Ukraine) / EAC (Russia, Belarus, Kazakhstan)
<b>Connection voltage</b>	380 V – 500 V at 50/60 Hz

### Energy-saving potential

<b>Motor efficiency according to IEC 60034</b>	<ul style="list-style-type: none"> <li>– Corresponds to efficiency class IE4 (Super Premium Efficiency) according to IEC 60034</li> <li>– Energy-saving potential of up to 50%</li> </ul>
<b>Drive system efficiency according to EN 50598-2 (Power Drive System)</b>	Surpasses the highest defined energy efficiency class IES2 according to EN 50598-2

### Dimensions and weight\*

<b>DRC..1</b> 	<b>DRC..2</b> 	<b>DRC..3/4</b> 
13 kg	18 kg	36 kg (DRC..3) / 40 kg (DRC..4)

\* Weight with brake

### Design for special ambient conditions

<b>Surface protection</b>	Optional protective measure for particular ambient conditions (OS 1 – 4)
<b>Degree of protection</b>	IP65 and IP66

### Gear unit combinations

