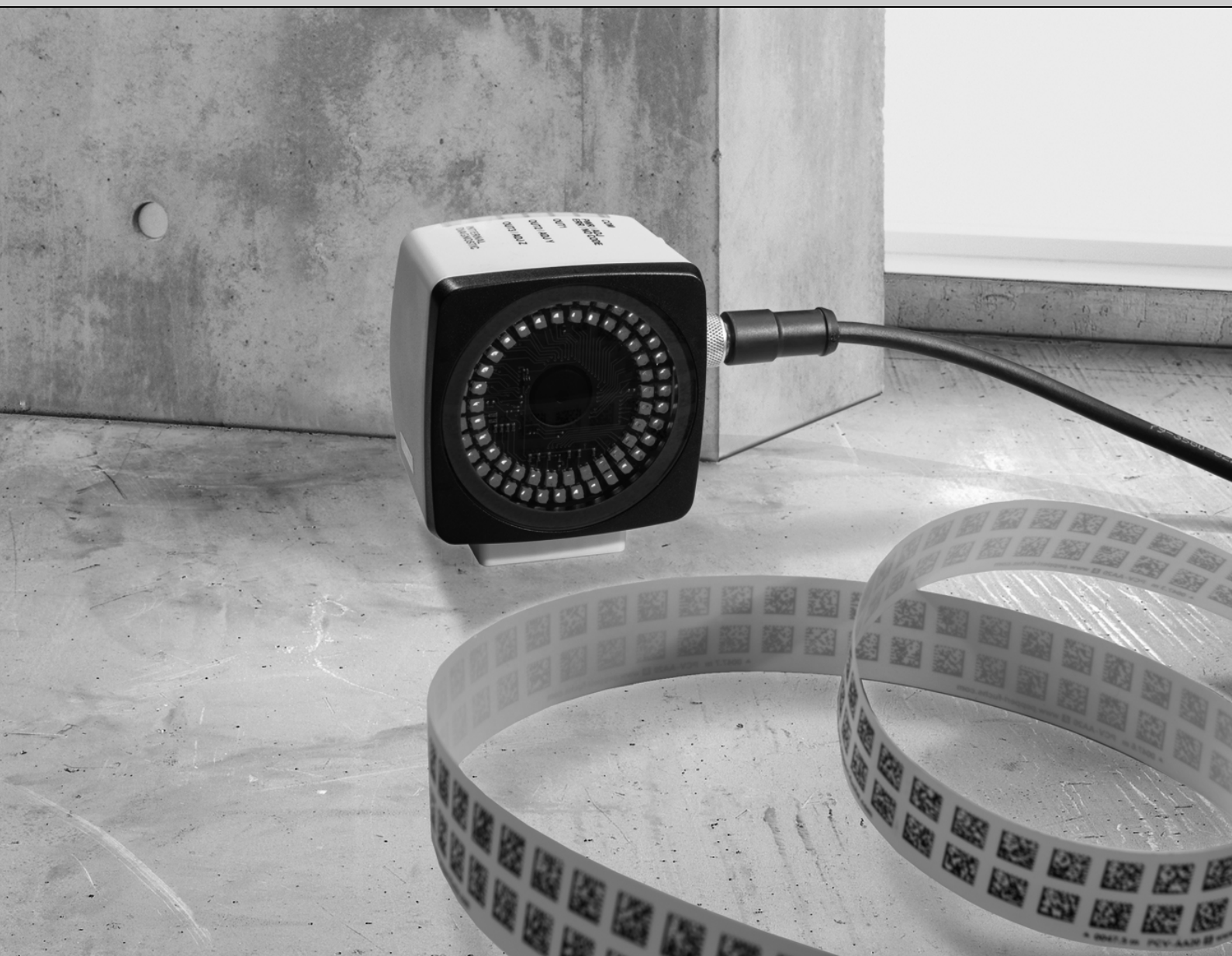




**SEW**  
**EURODRIVE**

# Manual



## Data Matrix Positioning System **PCV80A-F200-R4-V19-SEW**





## Contents

|          |  |           |
|----------|--|-----------|
| <b>1</b> | <b>General Information .....</b>                                 | <b>5</b>  |
| 1.1      | How to use this documentation .....                              | 5         |
| 1.2      | Structure of the safety notes .....                              | 5         |
| 1.2.1    | Meaning of signal words .....                                    | 5         |
| 1.2.2    | Structure of the section safety notes .....                      | 5         |
| 1.2.3    | Structure of the embedded safety notes .....                     | 5         |
| 1.3      | Rights to claim under warranty .....                             | 6         |
| 1.4      | Content of the documentation .....                               | 6         |
| 1.5      | Exclusion of liability .....                                     | 6         |
| 1.6      | Product names and trademarks .....                               | 6         |
| 1.7      | Copyright .....  | 6         |
| <b>2</b> | <b>Safety Notes .....</b>  | <b>7</b>  |
| 2.1      | Preliminary information .....                                    | 7         |
| 2.2      | Target group .....   | 7         |
| 2.3      | Designated use .....   | 8         |
| 2.4      | Other applicable documentation .....                             | 8         |
| 2.5      | Functional safety technology .....                               | 8         |
| 2.6      | Transport .....  | 8         |
| 2.7      | Installation/assembly .....                                      | 8         |
| <b>3</b> | <b>Product Description .....</b>                                 | <b>9</b>  |
| 3.1      | Use and application .....  | 9         |
| 3.2      | RS485 interface .....  | 9         |
| 3.3      | LED indicators and control elements .....                        | 10        |
| 3.4      | Accessories .....  | 11        |
| <b>4</b> | <b>Installation .....</b>  | <b>12</b> |
| 4.1      | Installing the code strip .....                                  | 12        |
| 4.1.1    | Code strips with a starting position of 0 m .....                | 13        |
| 4.1.2    | Code strips with different starting positions .....              | 14        |
| 4.2      | Mounting the read head .....                                     | 15        |
| 4.2.1    | Optimum read distance (z-axis) .....                             | 16        |
| 4.2.2    | Dimension drawing for the read head .....                        | 17        |
| 4.3      | Electrical connection .....                                      | 18        |
| 4.3.1    | Wiring diagram for the 8-pin connector of PCV80A .....           | 18        |
| 4.3.2    | X4011: RS485 interface – externally of PFF-HM31 .....            | 19        |
| 4.3.3    | Shielding cables .....   | 19        |
| <b>5</b> | <b>Startup .....</b>   | <b>20</b> |
| 5.1      | Aligning the read head .....                                     | 20        |
| 5.2      | Parameter setting .....  | 21        |
| 5.2.1    | Internal parameterization using parameter setting software ..... | 21        |
| 5.2.2    | External parameterization using code cards .....                 | 21        |
| 5.3      | Operation with repair tape .....                                 | 23        |



## Contents

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|          |  |           |
|----------|--|-----------|
| <b>6</b> | <b>Technical Data</b> .....                        | <b>24</b> |
| <b>7</b> | <b>Appendix</b> .....                              | <b>25</b> |
| 7.1      | Declaration of conformity .....                    | 25        |
| 7.2      | Code cards for external parameterization .....     | 25        |
| 7.2.1    | Code cards with special functions .....            | 26        |
| 7.2.2    | Code cards for setting the read head address.....  | 28        |
| 7.2.3    | Code cards for adjusting the resolution .....      | 29        |
| 7.2.4    | Code cards for setting the orientation.....        | 30        |
| 7.2.5    | Code cards for controlling image capture .....     | 31        |
| 7.2.6    | Code cards for setting the transfer rate .....     | 32        |
| 7.2.7    | Code cards for adjusting the bus termination ..... | 34        |
|          | <b>Index</b> .....                                 | <b>35</b> |



## 1 General Information

### 1.1 How to use this documentation

The documentation is an integral part of the product and contains important information on operation and service. The documentation is written for all employees who assemble, install, start up, and service this product.

The documentation must be accessible and legible. Make sure that persons responsible for the system and its operation, as well as persons who work independently on the unit, have read through the documentation carefully and understood it. If you are unclear about any of the information in this documentation, or if you require further information, contact SEW-EURODRIVE.

### 1.2 Structure of the safety notes

#### 1.2.1 Meaning of signal words

The following table shows the grading and meaning of the signal words for safety notes, warnings regarding potential risks of damage to property, and other notes.

| Signal word        | Meaning   | Consequences if disregarded                   |
|--------------------|---|---|
| <b>▲ DANGER</b>    | Imminent danger   | Severe or fatal injuries                      |
| <b>▲ WARNING</b>   | Possible dangerous situation  | Severe or fatal injuries                      |
| <b>▲ CAUTION</b>   | Possible dangerous situation  | Minor injuries                                |
| <b>NOTICE</b>      | Possible damage to property   | Damage to the drive system or its environment |
| <b>INFORMATION</b> | Useful information or tip: Simplifies the handling of the drive system. |   |

#### 1.2.2 Structure of the section safety notes

Section safety notes do not apply to a specific action but to several actions pertaining to one subject. The symbols used either indicate a general hazard or a specific hazard.

This is the formal structure of a section safety note:



#### **▲ SIGNAL WORD**

Type and source of danger.

Possible consequence(s) if disregarded.

- Measure(s) to prevent the danger.

#### 1.2.3 Structure of the embedded safety notes

Embedded safety notes are directly integrated in the instructions just before the description of the dangerous action.

This is the formal structure of an embedded safety note:

- **▲ SIGNAL WORD** Type and source of danger.  
Possible consequence(s) if disregarded.  
– Measure(s) to prevent the danger.



#### **1.3 Rights to claim under warranty**

A requirement of fault-free operation and fulfillment of any rights to claim under limited warranty is that you adhere to the information in the documentation. Therefore read the documentation before you start working with the unit.

#### **1.4 Content of the documentation**

This document contains additional safety-related information and conditions for operation in safety-related applications.

#### **1.5 Exclusion of liability**

You must comply with the information contained in this documentation to ensure safe operation and to achieve the specified product characteristics and performance features. SEW-EURODRIVE assumes no liability for injury to persons or damage to equipment or property resulting from non-observance of these operating instructions. In such cases, any liability for defects is excluded.

#### **1.6 Product names and trademarks**

All product names in this documentation are trademarks or registered trademarks of their respective titleholders.

#### **1.7 Copyright**

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Copyright law prohibits the unauthorized duplication, modification, distribution, and use of this document, in whole or in part.



## **2 Safety Notes**

### **2.1 Preliminary information**

The following basic safety notes must be read carefully to prevent injury to persons and damage to property. The operator must ensure that the basic safety notes are read and adhered to. Make sure that persons responsible for the system and its operation, as well as persons who work independently on the unit, have read through the operating instructions carefully and understood them. If you are unclear about any of the information in this documentation, or if you require further information, please contact SEW-EURODRIVE.

The following safety notes refer primarily to the use of PCV80A. If you use other SEW components, also refer to the safety notes for the respective components in the corresponding documentation.

Please also observe the supplementary safety notes in the individual chapters of this documentation.

### **2.2 Target group**

Any mechanical work may only be performed by adequately qualified personnel. Qualified personnel in the context of this documentation are persons familiar with the design, mechanical installation, troubleshooting and servicing of the product who possess the following qualifications:

- Training in mechanical engineering, e.g. as a mechanic or mechatronics technician (final examinations must have been passed).
- They are familiar with this documentation.

Any electronic work may only be performed by adequately qualified electricians. Qualified electricians in the context of this documentation are persons familiar with electrical installation, startup, troubleshooting and servicing of the product who possess the following qualifications:

- Training in electrical engineering, e.g. as an electrician or mechatronics technician (final examinations must have been passed).
- They are familiar with this documentation.

In addition to that, they must be familiar with the relevant safety regulations and laws, especially with the requirements of the performance levels according to DIN EN ISO 13849-1 and all other standards, directives and laws specified in this documentation. The above mentioned persons must have the authorization expressly issued by the company to operate, program, configure, label and ground units, systems and circuits in accordance with the standards of safety technology.

All work in further areas of transportation, storage, operation and waste disposal must only be carried out by persons who are trained appropriately.



### **2.3 Designated use**

In combination with a code strip with data matrix codes printed on it, this device is a high-resolution positioning system. This system can be used in all applications where exact positioning is required along extremely long travel paths irrespective of whether the travel path is straight, curved or with inclines or declines.

Read this manually carefully. Familiarize yourself with the device before installing, mounting, and operating it.

Always operate this device as described in this manual to ensure proper functioning of the device and connected systems. Protection of operating personnel and the system is only guaranteed if the device is operated according to its designated use.

### **2.4 Other applicable documentation**

Observe the corresponding documentation for all connected devices.

### **2.5 Functional safety technology**

The unit may not perform safety functions without higher-level safety systems unless these functions are described and expressly permitted in the relevant documentation.

### **2.6 Transport**

Inspect the shipment for any damage that may have occurred in transit as soon as you receive the delivery. Inform the shipping company immediately about any damage. It may be necessary to preclude startup.

Observe the information on climatic conditions as stated in chapter "Technical Data".

### **2.7 Installation/assembly**

The following applications are prohibited unless explicitly permitted:

- Use in potentially explosive atmospheres
- Use in areas exposed to harmful oils, acids, gases, vapors, dust, radiation, etc.
- Use in applications that are subject to mechanical vibration and shock loads in excess of the requirements in EN 61800-5-1.





## 3 Product Description

### 3.1 Use and application

The PCV80A read head is part of the positioning system of the incident light method used by SEW-EURODRIVE. The positioning system is equipped, among others, with a camera module with integrated illumination unit. In this way, the read head can detect position marks printed on a self-adhesive code strip in the form of data matrix codes.

The code strip is usually mounted in a stationary manner to a fixed part of the system (such as elevator shaft, overhead conveyor mounting rail). The read head is mounted in parallel to a moving "vehicle" (such as elevator cab, overhead conveyor chassis).

Max. length of the code strip:

| Resolution of the read head | Maximum length of the code strip |
|-----------------------------|----------------------------------|
| 10 mm                       | 10 km                            |
| 1 mm                        | 10 km                            |
| 0.1 mm                      | 1.5 km                           |

With appropriate resolution, the positioning system can also be used without limitations for large-scale systems.

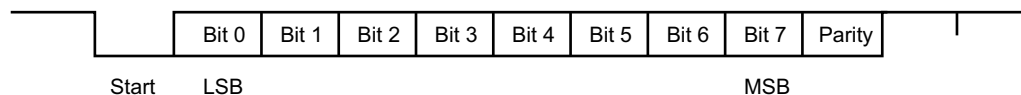
The extensive, user-friendly parameterization options and the freely configurable inputs and outputs of the read head allow for easily adapting the read head to the specific application.

### 3.2 RS485 interface

The read head is equipped with an RS485 interface for communication purposes, such as for parameterizing the read head functions or for reading out current process data during operation. This interface is operated in 8-E-1 mode and fitted with a terminating resistor that can be activated or deactivated by parameterizing the sensor head accordingly. The RS485 interface supports the following transfer rates:

- 38400 bit/s
- 57600 bit/s
- 76800 bit/s
- 115200 bit/s
- 230400 bit/s

Data structure of the RS485 interface:



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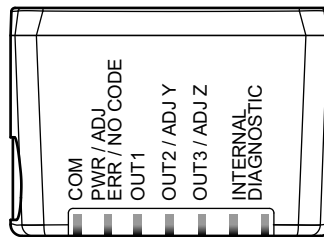
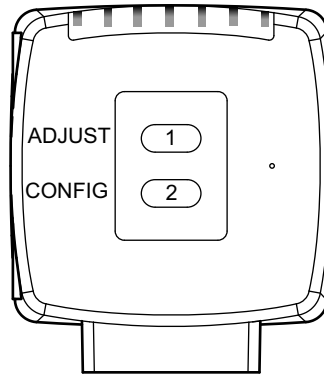


## Product Description

### LED indicators and control elements

### 3.3 LED indicators and control elements

The PCV80A read head is equipped with 7 indicator LEDs for visual function checks and fast diagnostics. Two buttons on the back of the read head are available for activating the alignment aid (see chapter "Aligning the read head") and parameter setting mode (see chapter "Parameter setting"). ADJUST appears next to button 1, and CONFIG next to button 2.



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|               |                         | LED (color)   |            |            |                              |               | Description  |
|---------------|-------------------------|---------------|------------|------------|------------------------------|---------------|--|
| COM           | PWR/ADJ/ERR<br>/NO CODE | OUT1          | OUT2/ADJ Y | OUT3/ADJ Z | INTERNAL<br>DIAGNOS-<br>TICS |               |  |
| (yel-<br>low) | (green/red)             | (yel-<br>low) | (yellow)   | (yellow)   | (yel-<br>low)                | (yel-<br>low) |  |
| Off           | Flashing green          | Off           | Off        | Off        | Off                          | Off           | Alignment Y > setpoint<br>f <sub>flash</sub> = 2 Hz  |
| Off           | Flashing green          | Off           | On         | Off        | Off                          | Off           | Alignment Y < setpoint<br>f <sub>flash</sub> = 2 Hz  |
| Off           | Flashing green          | Off           | Flashing   | Off        | Off                          | Off           | Alignment Y = setpoint<br>f <sub>flash</sub> = 2 Hz  |
| Off           | Flashing green          | Off           | Off        | Off        | Off                          | Off           | Alignment Z > setpoint<br>f <sub>flash</sub> = 2 Hz  |
| Off           | Flashing green          | Off           | Off        | On         | Off                          | Off           | Alignment Z < setpoint<br>f <sub>flash</sub> = 2 Hz  |
| Off           | Flashing green          | Off           | Off        | Flashing   | Off                          | Off           | Alignment Z = setpoint<br>f <sub>flash</sub> = 2 Hz  |
| Off           | Flashing red            | Off           | Off        | Off        | Off                          | Off           | Alignment of code strip not<br>within read range.<br>f <sub>flash</sub> = 2 Hz   |
| Off           | Lights up red           | Off           | Off        | Off        | Off                          | Off           | System error   |
| Off           | Lights up green         | x             | x          | x          | Off                          | Off           | Normal operation. No communi-<br>cation.<br>LEDs marked with "x" indicate<br>the state of the relevant output.                                 |
| Flash-<br>ing | Lights up green         | x             | x          | x          | Off                          | Off           | Normal operation. Communica-<br>tion active (f <sub>flash</sub> = 2 Hz).<br>LEDs marked with "x" indicate<br>the state of the relevant output. |



| COM           | PWR/ADJ/ERR<br>/NO CODE | LED (color)   |            |            | INTERNAL<br>DIAGNOS-<br>TICS |               | Description  |
|---------------|-------------------------|---------------|------------|------------|------------------------------|---------------|--|
|               |                         | OUT1          | OUT2/ADJ Y | OUT3/ADJ Z | (yel-<br>low)                | (yel-<br>low) |  |
| (yel-<br>low) | (green/red)             | (yel-<br>low) | (yellow)   | (yellow)   | (yel-<br>low)                | (yel-<br>low) |  |
| Flash-<br>ing | Flashing red            | x             | x          | x          | Off                          | Off           | No code strip within read range.<br>Communication active.<br>( $f_{\text{flash}} = 2 \text{ Hz}$ )<br>LEDs marked with "x" indicate<br>the state of the relevant output. |
| Flash-<br>ing | Flashing red            | Flash-<br>ing | Flashing   | Flashing   | Off                          | Off           | Normal operation. Indication for<br>2 s if a button is pressed when<br>the time lock is enabled.   |
| Off           | Off                     | Flash-<br>ing | Off        | Off        | Off                          | Off           | Preconfiguration/configuration<br>mode active.<br>$f_{\text{flash}} = 2 \text{ Hz}$  |
| Off           | Lights up red           | Flash-<br>ing | Off        | Off        | Off                          | Off           | Code card faulty.<br>$f_{\text{flash}} = 2 \text{ Hz}$ for 3 s   |
| Off           | Green, 1 s              | Flash-<br>ing | Off        | Off        | Off                          | Off           | Code card detected.<br>$f_{\text{flash}} = 2 \text{ Hz}$ for 3 s   |
| x             | Off                     | x             | x          | x          | Off                          | Off           | Time lock for buttons disabled.  |

X = LED status has no meaning

### 3.4 Accessories

Suitable accessories offer enormous savings potential. This lets you save a considerable amount of time and effort not only for initial startup but also for replacing and servicing our products.

The appropriate accessories from SEW-EURODRIVE can extend the service life of products used under harsh ambient conditions.

| Order designation  | Description   |
|--|---|
| PCV-SC12   | Grounding clip  |
| PCV-USB-RS485 converter set  | Interface converter USB – RS485   |
| PCV-KBL-V19-STR-RS485  | Cable unit with 24 V power supply and V19 connection cable to RS485 interface |
| Connection cable VG19-1.5M-PUR-ABG-V15B-G (length: 1.5 m, part number: 1950 0084)        | M12, 4-pin plug (PFF-HM31) on M12, 8-pin socket (PCV80A)                      |
| Connection cable VG19-3M-PUR-ABG-V15B-G (length: 3 m, part number: 1950 0076)            | M12, 4-pin plug (PFF-HM31) on M12, 8-pin socket (PCV80A)                      |
| Connection cable 0X01-F8AS-Sw-M5BS (variable length: 0.5 – 30 m, part number: 1814 5388) | M12, 4-pin plug (PFF-HM31) on M12, 8-pin socket (PCV80A)                      |



## 4 Installation

### 4.1 Installing the code strip

The code strip is made of silicone-free polyester film. A position mark is printed every 100 mm along the lower edge of the code strip (see "Dimensions, code strip"). The position marks are used, among others, for the precise positioning of the code strip during assembly. The reverse side of the code strip carries a permanent modified acrylate-based adhesive. Affix the self-adhesive code strip along the required travel range.

Proceed as follows:

1. Clean the surface to remove any greasy or oily deposits and dust.
2. Ensure that the surface is dry, clean, and stable.
3. Pull the protective foil at the beginning of the code strip a few centimeters forward. Place the code strip exactly at the required starting position on the underside, and press to attach it.
4. Affix the self-adhesive code strip along the required travel range. Remove the protective film gradually to prevent the code strip from adhering to the surface at an incorrect position. When affixing the code strip, ensure that the code strip does not crease or trap air bubbles.

The adhesive on the code strip hardens after 72 hours.

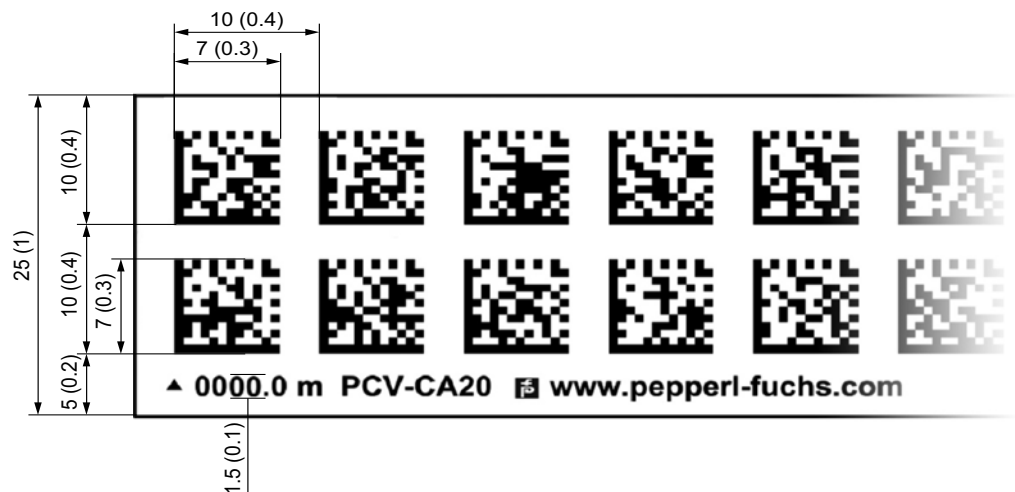


### INFORMATION

Thermal expansion of the code strip.

The heat expansion coefficient of the attached code strip corresponds to the heat expansion coefficient of the underside.

The following figure shows the dimensions of the code strip.

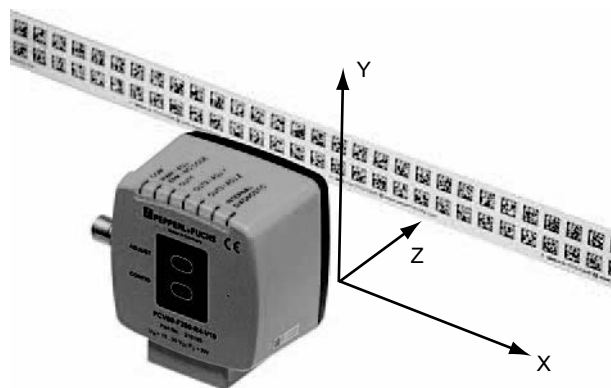


8068130443

All dimensions in mm (in).



Position the code strip in such a way that the [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com) label and the position marks are below the data matrix code. The position values then increase in X direction.



8069362699

The figure shows the orientation of a read head in the default position of 0°. You can configure the read head for other mounting positions using the interface.

#### 4.1.1 Code strips with a starting position of 0 m

| Order designation | Description                       |
|-------------------|-----------------------------------|
| PCV50M-AA20-0     | Code strip 2-track, length: 50 m  |
| ...               | ....                              |
| PCV100M-AA20-0    | Code strip 2-track, length: 100 m |



## Installation

### Installing the code strip

#### 4.1.2 Code strips with different starting positions

| Order designation   | Description  |
|---------------------|--|
| PCV100M-AA20-0      | Code strip 2-track, length: 100 m<br>Starting position: 0 m    |
| PCV100M-AA20-10000  | Code strip 2-track, length: 100 m<br>Starting position: 100 m  |
| PCV100M-AA20-990000 | Code strip 2-track, length: 100 m<br>Starting position: 9900 m |

#### Notes

- **Stop edges**

Maintain a code pattern of 10 mm when attaching another code strip to the end of the previous one.

- **Expansion joints**

If the system covers long distances, expansion joints are integrated in the system structure. We recommend to interrupt the code strip. The resulting gaps should be 20 mm wide (2 code grids).

- **Inclines and declines**

If you mount the code strip in inclines [1] or declines [2], cut the code strip several times at the transition point to the horizontal as shown below.



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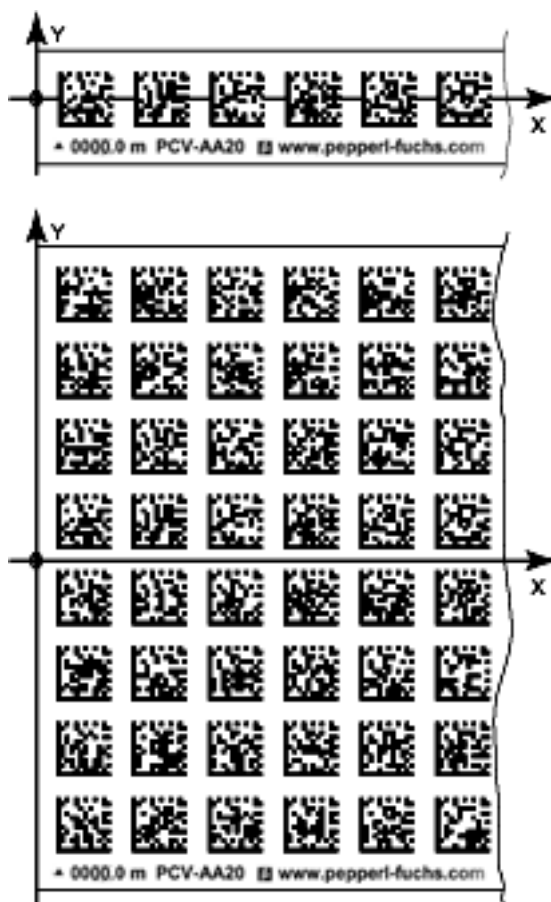
- **Code strips with different numbers of tracks**

The PCV-AA20 code strip has two rows of codes to compensate for slight deviations in the travel range in Y direction. The code strip is also available with other numbers of rows. The order number for the code strip is PCV-AAx0. The letter "x" represents the number of rows of code, which can be 1 or 2. More rows are available on request. Contact us for more information.

| Order designation | Description         |
|-------------------|---------------------|
| PCV*M-AA10-*      | Code strip, 1-track |
| PCV*M-AA20-*      | Code strip, 2-track |
| PCV*M-AA40-*      | Code strip, 4-track |
| ...               | ...                 |



- Hysteresis y-axis



8069371531

When the read head leaves the zero line when traveling along the x-axis, different threshold values will result depending on the number of tracks. If the deviation exceeds this threshold, a warning code is issued.

| Code strip       |       | Threshold |        |
|------------------|-------|-----------|--------|
| Number of tracks | Width | Exit      | Entry  |
| 1                | 15 mm | ±10 mm    | ±6 mm  |
| 2                | 25 mm | ±15 mm    | ±11 mm |
| 4                | 45 mm | ±25 mm    | ±21 mm |
| 6                | 65 mm | ±35 mm    | ±31 mm |
| 8                | 85 mm | ±45 mm    | ±41 mm |

## 4.2 Mounting the read head

Mount the PCV80A read head to the moving part of your system. To do so, use the 4 screws on the mounting adapter of the read head. Mount the read head in such a way that the lens with ring light and camera module are aligned towards the code strip.

The mounting and the guidance of the moving system component must be stable enough to prevent that the read head's depth of focus is lost during operation.

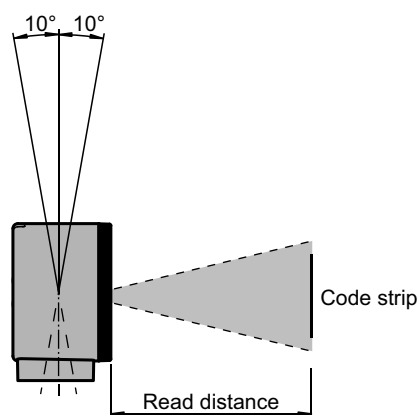
The distance between read head and code strip should be the same as the read distance of the read head.



## Installation

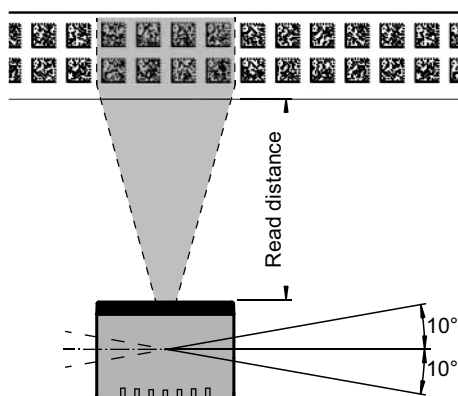
### Mounting the read head

Vertical alignment tolerance:



8069377291

Horizontal alignment tolerance:



8069380747

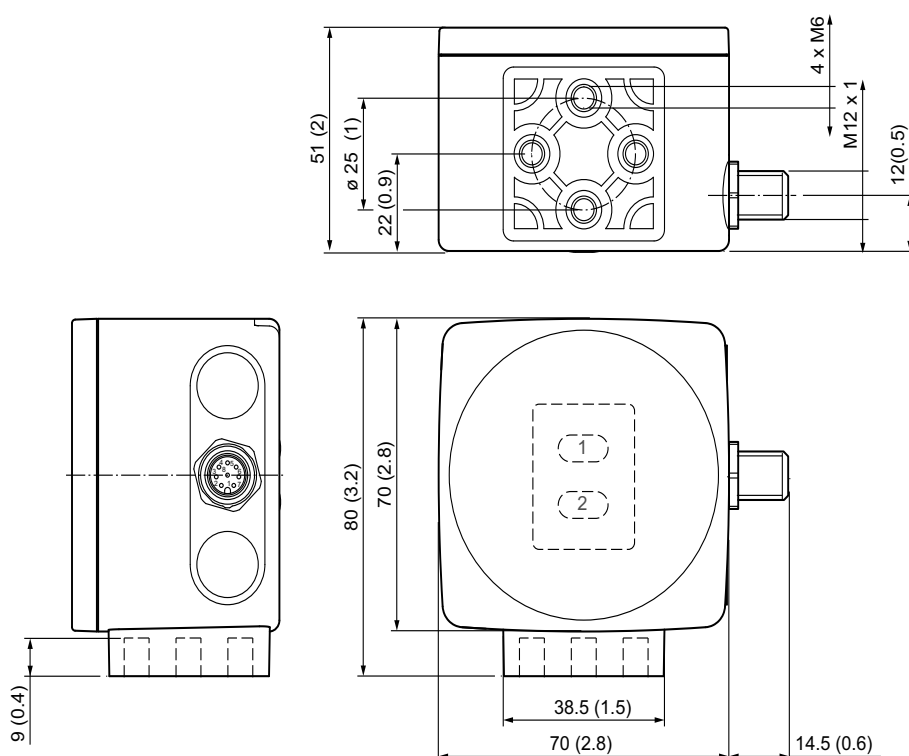
#### 4.2.1 Optimum read distance (z-axis)

| Order designation | Read distance | Depth of focus |
|-------------------|---------------|----------------|
| PCV80*            | 80 mm         | ±10 mm         |





#### 4.2.2 Dimension drawing for the read head



8069384459

All dimensions in mm (in)

#### NOTICE

Using longer retaining screws.

Damage to the read head.

Select the length of the retaining screws in such a way that the maximum insertion depth of the screws in the threaded inserts of the read head is 8 mm (0.3 in).

#### NOTICE

Tightening the screws with excessively high torque.

Damage to the read head.

The maximum torque of the retaining screws must not exceed 9 Nm.

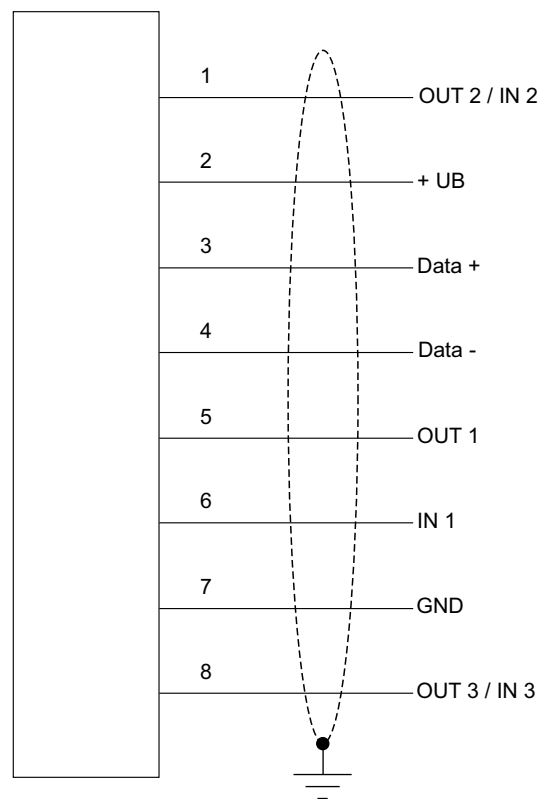


#### 4.3 Electrical connection

The PCV80A read head is connected electrically using an 8-pin M12 x 1 connector on the side of the housing. Power supply as well as communication with peripheral devices is implemented using this connection. This connection also provides the configurable inputs and outputs of the read head.

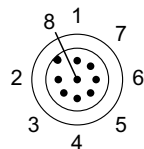
For connecting the PCV80A read head to the PFF-HM31A safety controller, use the pre-fabricated connection cables listed in chapter "Accessories". Connect the 8-pin M12 x 1 connector (see chapter "Wiring diagram for the 8-pin connector of PCV80A") to the side of the housing of PCV80A, and the 4-pin M12 x 1 connector to terminal X4011 (see chapter "X4011: RS485 interface – externally of PFF-HM31") of the safety controller.

##### 4.3.1 Wiring diagram for the 8-pin connector of PCV80A



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Connections 1 and 8 can be configured as inputs or outputs.

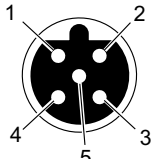


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### 4.3.2 X4011: RS485 interface – externally of PFF-HM31

The following table shows information about this connection:

| Function   |      |                     |
|--|------|---------------------|
| RS485 interface for external components  |      |                     |
| Connection type  |      |                     |
| M12, 5-pin, female, B-coded  |      |                     |
| Wiring diagram   |      |                     |
|  |      |                     |
| 2354431115   |      |                     |
| Assignment   |      |                     |
| No.  | Name | Function            |
| 1  | +24V | DC 24 V output      |
| 2  | RS - | RS485 data line (-) |
| 3  | GND  | Reference potential |
| 4  | RS + | RS485 data line (+) |
| 5  | res. | Reserved            |

### 4.3.3 Shielding cables

The shielding of cables is required to suppress electromagnetic interference. Establishing a low resistance or low impedance connection with the conductor or equipotential bonding circuit is particularly important to ensure that these interference currents do not become a source of interference themselves. Always use cables with braided shield, never use cables with a foil shield. The shield is connected at both ends: on the PFF-HM31A controller **and** on the PCV80A read head. Use the prefabricated connection cables as listed in chapter "Accessories". The grounding terminal available as an accessory (see chapter "Accessories") allows for easy integration into the equipotential bonding circuit.

In the following exceptional cases, the shielding of a connection at only one end might be more favorable:

- If an equipotential bonding cable is not laid or cannot be laid.
- If a film shield is used.

Also observe the following point for shielding cables:

- Use metal cable clips that cover large areas of the shield.
- Route protective grounding connections to a common point in a star configuration.
- The cross sections of cables used for grounding should be as large as possible.

#### NOTICE

Connecting PCV80A to alternating current or excessive supply voltage, or incorrect electrical connection with reversed polarity.

Damage to the device or malfunction.

- Connect the device to DC voltage.
- Ensure that the supply voltage rating is within the specified range of the sensor.
- Ensure that the connecting wires on the connection cables used are connected properly.





## 5 Startup

### 5.1 Aligning the read head

An integrated alignment aid is available to help you easily and accurately align the y and z coordinates of the read head in relation to the code strip.



#### INFORMATION

The alignment aid can only be activated within 10 minutes after switching on the read head.

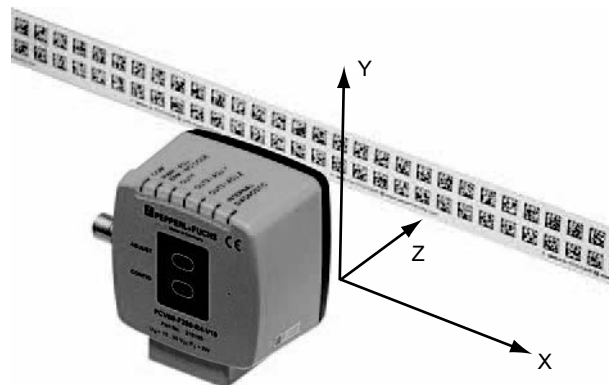
To change from normal operation to parameter setting mode, press button 1 (ADJUST) on the back of the read head.

To activate the alignment aid of the read head:

1. Press button 1 (ADJUST) for longer than 2 seconds.

The "PWR/ADJ/ERR/NO CODE" LED flashes green if a code strip was detected. If no code strip was detected, the "PWR/ADJ/ERR/NO CODE" LED flashes red.

2. Now align the z and y coordinates of the read head. The integrated LED indicators assist you in the process.



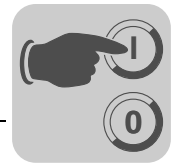
8069362699

#### – z-coordinate

If the distance of the camera to the code strip is too small, the "OUT3/ADJ Z" LED is lit yellow. If the distance is too great, the yellow "OUT3/ADJ Z" LED goes out. Within the target range, the yellow "OUT3/ADJ Z" LED and the green "PWR/ADJ/ERR/NO CODE" LED are flashing simultaneously. The optimal distance between read head and code strip is indicated by the yellow "OUT3/ADJ Z" LED flashing synchronously with the green "PWR/ADJ/ERR/NO CODE" LED.

#### – y-coordinate

If the optical axis of the read head is too low relative to the middle of the code strip, then the yellow "OUT2/ADJ Y" LED goes out. If the optical axis is too high, the yellow "OUT2/ADJ Y" LED goes out. Within the target range, the yellow "OUT2/ADJ Y" LED and the green "PWR/ADJ/ERR/NO CODE" LED are flashing simultaneously. Set the optimum height of the read head relative to the code strip so that the yellow "OUT2/ADJ Y" LED flashes in sync with the green "PWR/ADJ/ERR/NO CODE" LED. Briefly pressing button 1 (ADJUST) stops the alignment aid, and the read head returns to normal operation.



## 5.2 Parameter setting

The PCV80A read head can be optimally adapted to the specific requirements by setting its parameters accordingly. You can set the parameters for the read head either via the interface itself (internal parameterization) or by means of an optical parameterization code (external parameterization).

### 5.2.1 Internal parameterization using parameter setting software

You have to start internal parameterization of the read head via RS485 interface within the first 10 minutes after activation of the read head. A time lock disables the read head when this time has elapsed. The time lock remains inactive during the parameter setting process. The time lock only disables the read head if no parameters are set for more than 10 minutes.

The easy-to-use PCV Parameterization Tool lets you optimally configure the read head. This configuration software is available as a free download from [www.pepperl-fuchs.com](http://www.pepperl-fuchs.com). To install the software, follow the instructions on your screen.

If your PC does not have a built-in RS485 interface, you need a USB – RS485 interface adapter (see chapter "Accessories").

#### *How to parameterize the read head*

1. Connect the read head to your PC using the interface adapter. For detailed information, refer to the manual for the interface adapter.
2. Connect the read head to a suitable power supply.
3. Switch on the power supply.
4. Start the parameterization tool.
5. Set the read head parameters with the aid of the manual for the parameterization tool.
6. Transfer the parameter list to the read head.
7. Save the parameter setting.
8. Switch off the power supply to the read head.
9. Disconnect the read head from the interface adapter and from the power supply.

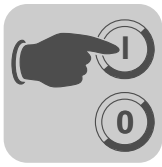
The read head is now parameterized according to your requirements and can be used in your application.

### 5.2.2 External parameterization using code cards

External parameterization means the read head optically scans the code cards and then sets the respective parameters. To do so, simply hold the corresponding code cards in front of the lens of the PCV80A read head at the proper distance (see chapter "Code cards for external parameterization").

You can set the following parameters using code cards:

- Read head address (0, 1, 2, 3)
- Read head resolution (0.1 mm, 1 mm, 10 mm).
- Read head orientation (0°, 180°, 0° or 180°, 0°, 90°, 180° or 270°)
- Trigger source (auto, hardware)
- Transfer rate (38400, 57600, 76800, 115200 or 230400 bit/s)
- Bus termination (on, off)



#### Activating programming mode



#### INFORMATION

You have to start external parameterization of the read head using code cards within the first 10 minutes after activation of the read head. A time lock disables the read head when this time has elapsed. The time lock remains inactive during the parameter setting process. The time lock only disables the read head if no parameters are set for more than 10 minutes.

If you press a button when the time lock is enabled, then all LEDs flash for 2 seconds.

To change from normal operation to parameter setting mode, press button 2 (CONFIG) on the back of the read head.

To activate parameter setting mode:

1. Press button 2 (CONFIG) for longer than 2 seconds.

The yellow "OUT1" LED flashes.

2. For final activation, hold the "ENABLE" code in front of the camera system of the read head.

If the "ENABLE" activation code is detected, the green "PWR/ADJ/ERROR/NO CODE" LED flashes for 1 second. If the activation code is not detected, the "PWR/ADJ/ERROR/NO CODE" LED lights up red for 2 seconds.

#### Parameter setting

Place the parameterization code in the field of view of the camera module.

If the parameterization code is detected, the green "PWR/ADJ/ERROR/NO CODE" LED lights up for 1 second. If the parameterization code is not detected, the "PWR/ADJ/ERROR/NO CODE" LED lights up red for 2 seconds.

#### Exiting parameter setting mode

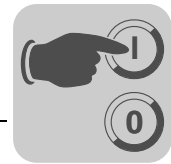
To save the configuration, hold the "STORE" code in front of the camera system of the read head.

If the "STORE" memory code is detected, the green "PWR/ADJ/ERROR/NO CODE" LED lights up for 1 second. The parameters are stored in the non-volatile memory of the read head, and parameter setting mode is terminated. You have now successfully set the parameters for the read head. If the memory code is not detected, the "PWR/ADJ/ERROR/NO CODE" LED lights up red for 2 seconds.



#### INFORMATION

Briefly pressing button 2 (CONFIG) in parameter setting mode immediately exits this mode. Any parameter changes you made but have not saved will be discarded. The read head continues to operate with the last valid parameters that were saved.



*The code cards  
"CANCEL", "USE"  
and "DEFAULT"*

Holding one of these cards in front of the read head exits parameter setting mode with the following consequences:

- **CANCEL**

Any parameter changes you made but have not saved will be discarded. The read head continues to operate with the last valid parameters that were saved.

- **USE**

For test purposes, the read head continues to operate with the parameters you have just changed. These parameters are not saved, however. Switching the read head off and on again has it operate with the last valid parameters that were saved.

- **DEFAULT**

All parameters in the read head are overwritten with the original default settings. This reset is saved in the non-volatile memory of the read head.

### 5.3 Operation with repair tape

The repair tape is a short code strip with a length of 1 meter. It is used to bridge defective or damaged areas of an existing code strip.

1. Cut the repair tape to the required length.
2. Cover the defective area of the code strip with the repair tape.



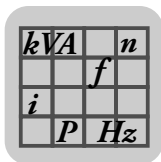
#### INFORMATION

When adhering the repair tape to the code strip, make sure that the repair tape continues the grid of the code strip as accurately as possible.

If repair is required, you can use the code strip generator at [www.codegenerator.sew-eurodrive.com](http://www.codegenerator.sew-eurodrive.com) as interim solution. The code strip generator lets you generate code strip segments online, which you can print out.

To do so, enter the start value in meters and the code strip length of the segment to be replaced in meters. The generator then creates a printable pdf file with the required code strip segment.

Use the printout only as temporary solution. The durability of the paper strip is very limited depending on the application. Immediately order a new code strip of the required length. For placing the order, use the order designation as given in chapter "Code strips with different starting positions".



## 6 Technical Data

| General technical data           |   |
|----------------------------------|---|
| Passage speed v                  | ≤ 8 m/s   |
| Measuring range                  | Max. 10000 m  |
| Light type                       | Integrated LED lightning (red)  |
| Read distance                    | 80 mm   |
| Depth of focus                   | ±10 mm  |
| Reading field                    | 40 mm × 25 mm   |
| Ambient light limit              | 100000 lux  |
| Resolution                       | ±0.1 mm   |
| Camera data                      |   |
| Type                             | CMOS, global shutter  |
| Processor data                   |   |
| Clock rate                       | 600 MHz   |
| Computation speed                | 4800 MIPS   |
| Functional safety related data   |   |
| MTTF <sub>d</sub>                | 20 years  |
| Service life (T <sub>M</sub> )   | 10 years  |
| Diagnostic coverage (DC)         | 0%  |
| Indicators/control elements      |   |
| LED display                      | 7 LEDs (communication, alignment aid, status information)   |
| Electrical data                  |   |
| Operating voltage U <sub>B</sub> | DC 15 – 30 V, PELV  |
| No-load current I <sub>0</sub>   | Max. 200 mA   |
| Power consumption P <sub>0</sub> | 3 W   |
| Interface                        |   |
| Type                             | RS485 interface   |
| Output code                      | Binary code   |
| Transfer rate                    | 38400 – 230400 bit/s  |
| Termination                      | Switchable terminating resistor   |
| Query cycle time                 | ≥10 ms  |
| Input                            |   |
| Input type                       | 1 to 3 function inputs, programmable  |
| Output                           |   |
| Output type                      | 1 to 3 switch outputs, PNP, programmable, short-circuit protected                                 |
| Switching voltage                | Operating voltage   |
| Switching current                | 150 mA each output  |
| Standard conformity              |   |
| Interference emission            | EN 61000-6-4:2007 + A1:2011   |
| Interference immunity            | EN 61000-6-2:2005   |
| Shock resistance                 | EN 60068-2-27:2009  |
| Vibration resistance             | EN 60068-2-6:2008   |
| Ambient conditions               |   |
| Operating temperature            | 0 – 60 °C (32 – 140 °F)<br>–20 to 60 °C (–4 to 140 °F) non-condensing; prevent icing on the lens) |
| Relative humidity                | 90%, non-condensing   |
| Mechanical data                  |   |
| Connection type                  | M12×1 connector, 8-pin  |
| Degree of protection             | IP67  |
| Housing material                 | PC/ABS  |
| Mass                             | Approx. 160 g   |
| Approvals and certifications     |   |
| UL approval                      | cULus Listed, General Purpose, Class 2 Power Source, Type 1 enclosure                             |
| CCC approval                     | Approval not required   |





## 7 Appendix

### 7.1 Declaration of conformity



#### INFORMATION

This product has been developed and produced in accordance with applicable European standards and guidelines. The declaration of conformity is available for download from the SEW website at ([www.sew-eurodrive.com](http://www.sew-eurodrive.com)) under "Documentation".

### 7.2 Code cards for external parameterization

Here you find the code cards you can use for setting the parameters for some of the basic functions of the read head step by step. Refer to chapter "External parameterization using code cards" for a detailed description.



#### INFORMATION

When performing external parameterization with code cards, we recommend that you copy and print the relevant pages of this manual and cut out the required code cards. Doing so prevents the read head from detecting another code card on the same page by mistake. If you use this manual directly for setting the parameters, then do not cover unused code cards (with a sheet of paper for example).



### 7.2.1 Code cards with special functions

The following code cards have special functions:

- ENABLE
- STORE
- CANCEL
- USE
- DEFAULT

#### *ENABLE code card*

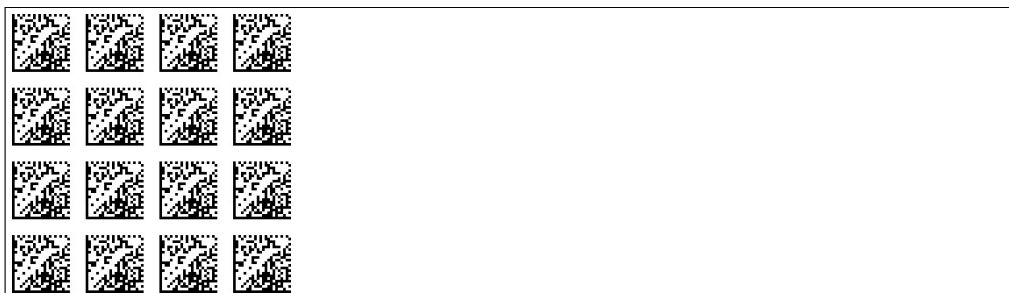
The ENABLE code card is used to activate external parameterization mode.



8090482955

#### *STORE code card*

The STORE code card stores the modified parameter setting in the non-volatile memory of the read head and terminates external parameterization mode.



8090486411

#### *CANCEL code card*

The CANCEL code card discards the modified parameter setting and terminates external parameterization mode. The read head switches to normal mode and adopts the last valid configuration that was saved.

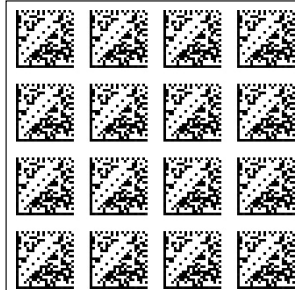


8099729931



*USE code card*

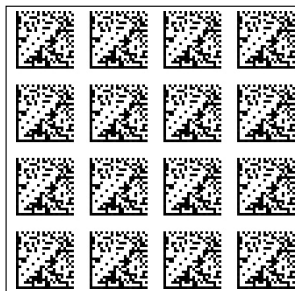
The USE code card stores the modified parameter setting in the volatile memory (RAM) of the read head and terminates external parameterization mode. The read head then operates with this configuration. However, when switching the read head off and on again, the configuration is lost and the read head operates with the last valid configuration that was saved. This is primarily used for test purposes.



8099733387

*DEFAULT code card*

The DEFAULT code card restores the factory setting of the read head and terminates external parameterization mode.



8099920267

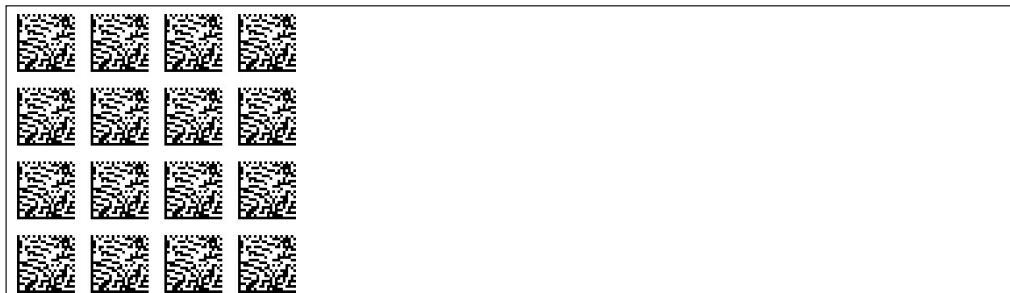


#### 7.2.2 Code cards for setting the read head address

A unique address must be assigned to the read head so that it can be activated via the interface. The address range extends from 0 to 3.

*Read head  
address 0*

The code card assigns address 0 to the read head.



8099957003

*Read head  
address 1*

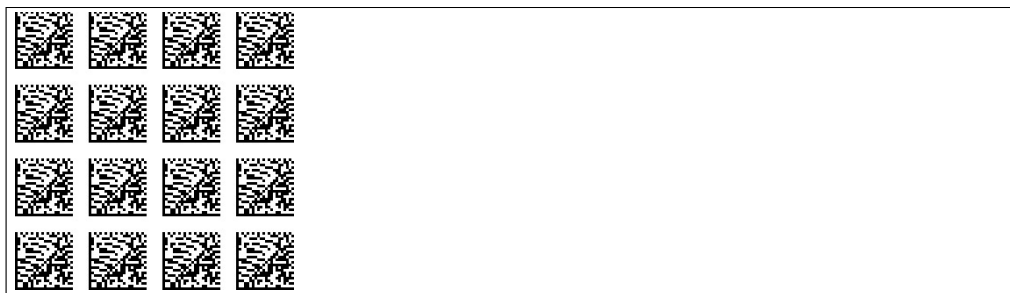
The code card assigns address 1 to the read head.



8100066827

*Read head  
address 2*

The code card assigns address 2 to the read head.



8100099979

*Read head  
address 3*

The code card assigns address 3 to the read head.



8193697931



### 7.2.3 Code cards for adjusting the resolution

You can assign the following position data resolutions to the read head by setting the parameters accordingly:

- 0.1 mm
- 1 mm
- 10 mm

#### 0.1 mm resolution

The code card assigns a position data resolution of 0.1 mm to the read head.



8193701387

#### 1 mm resolution

The code card assigns a position data resolution of 1 mm to the read head.



8194176395

#### 10 mm resolution

The code card assigns a position data resolution of 10 mm to the read head.



8194191371

Max. length of the code strip:

| Resolution of the read head | Max. length of the code strip |
|-----------------------------|-------------------------------|
| 10 mm                       | 10 km                         |
| 1 mm                        | 10 km                         |
| 0.1 mm                      | 1.5 km                        |

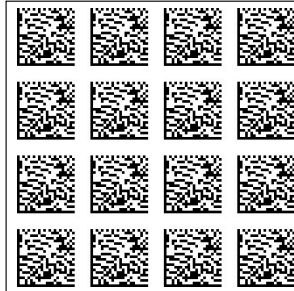


#### 7.2.4 Code cards for setting the orientation

If the direction of the read head does not correspond to the default, you have to adjust the orientation. You can set the orientation at an angle of  $0^\circ$ ,  $180^\circ$ , or to automatic detection in increments of  $90^\circ$ .

##### *$0^\circ$ orientation*

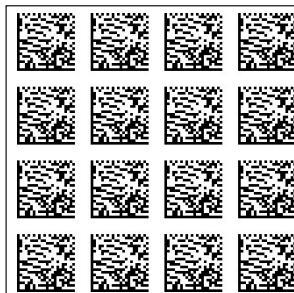
The code card assigns orientation  $0^\circ$  to the read head.



8194235019

##### *$180^\circ$ orientation*

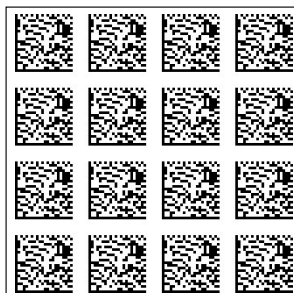
The code card assigns orientation  $180^\circ$  to the read head.



8194238859

##### *$0^\circ$ or $180^\circ$ orientation*

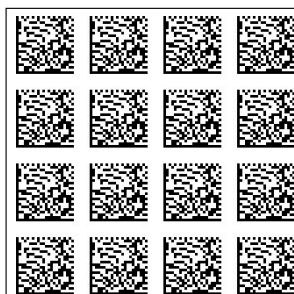
The code card automatically assigns orientation  $0^\circ$  or  $180^\circ$  to the read head.



8194242315

##### *$0^\circ$ , $90^\circ$ , $180^\circ$ or $270^\circ$ orientation*

The code card automatically assigns orientation  $0^\circ$ ,  $90^\circ$ ,  $180^\circ$  or  $270^\circ$  to the read head.



8195935115

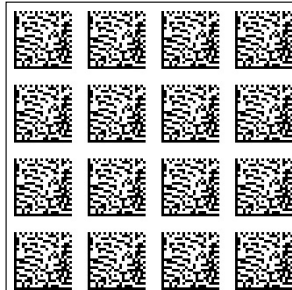


### 7.2.5 Code cards for controlling image capture

Parameterization lets you assign various methods for controlling image capture.

*Trigger source:*  
*auto*

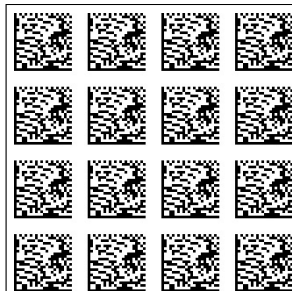
Image capture is controlled automatically by a pulse generated in the read head.



8195938571

*Trigger source:*  
*Hardware*

Image capture is controlled by a trigger signal at one of the read head inputs. The trigger signal can be an electrical signal from a controller or an external sensor, for example. The image is captured immediately.



8196731787



#### 7.2.6 Code cards for setting the transfer rate

Parameterization lets you assign various transfer rates to the read head for communication via the interfaces. You can set the following transfer rates:

- 38400 bit/s
- 57600 bit/s
- 76800 bit/s
- 115200 bit/s
- 230400 bit/s

*Transfer rate:*  
38400 bit/s

The transfer rate of the read head for communication via the interface is set to 38400 bit/s.



8196735243

*Transfer rate:*  
57600 bit/s

The transfer rate of the read head for communication via the interface is set to 57600 bit/s.



8196957323

*Transfer rate:*  
76800 bit/s

The transfer rate of the read head for communication via the interface is set to 76800 bit/s.



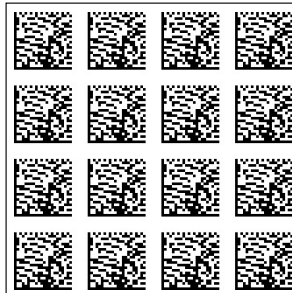
8197069963





*Transfer rate:*  
115200 bit/s

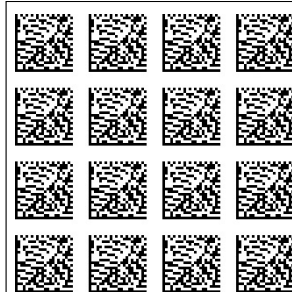
The transfer rate of the read head for communication via the interface is set to 115200 bit/s.



8215312651

*Transfer rate:*  
230400 bit/s

The transfer rate of the read head for communication via the interface is set to 230400 bit/s.



8215316107



#### 7.2.7 Code cards for adjusting the bus termination

Parameterization lets you switch a bus terminating resistor on and off in the read head.

*Bus termination:*  
**OFF**

The bus terminating resistor is deactivated.



8215323275

*Bus termination:*  
**ON**

The bus terminating resistor is connected.



8215377931



## Index

### A

|                              |    |
|------------------------------|----|
| Accessories, overview.....   | 11 |
| Aligning the read head ..... | 20 |

### C

|  |    |
|--|----|
| Code card                                      |    |
| Bus termination OFF .....                      | 34 |
| Bus termination ON .....                       | 34 |
| CANCEL .....                                   | 26 |
| ENABLE .....                                   | 26 |
| Orientation 0°, 90°, 180° or 270° .....        | 30 |
| Read head address 0 .....                      | 28 |
| Read head address 1 .....                      | 28 |
| Read head address 2 .....                      | 28 |
| Read head address 3 .....                      | 28 |
| STORE .....                                    | 26 |
| Transfer rate 115200 bit/s .....               | 33 |
| Transfer rate 230400 bit/s .....               | 33 |
| Transfer rate 38400 bit/s .....                | 32 |
| Transfer rate 57600 bit/s .....                | 32 |
| Transfer rate 76800 bit/s .....                | 32 |
| Trigger source auto .....                      | 31 |
| Trigger source hardware .....                  | 31 |
| USE .....                                      | 27 |
| 0.1 mm resolution .....                        | 29 |
| 0° or 180° orientation .....                   | 30 |
| 0° orientation .....                           | 30 |
| 1 mm resolution .....                          | 29 |
| 10 mm resolution .....                         | 29 |
| 180° orientation .....                         | 30 |
| code card                                      |    |
| DEFAULT .....                                  | 27 |
| Code cards for adjusting the bus termination   |    |
| Code card bus termination OFF .....            | 34 |
| Code card bus termination ON .....             | 34 |
| Code cards for adjusting the resolution        |    |
| Code card resolution 0.1 mm .....              | 29 |
| Code card resolution 1 mm .....                | 29 |
| Code card resolution 10 mm .....               | 29 |
| Code cards for controlling image capture       |    |
| Trigger source auto code card .....            | 31 |
| Trigger source hardware code card .....        | 31 |
| Code cards for external parameterization ..... | 25 |

|   |    |
|---|----|
| Code cards for setting the orientation            |    |
| Code card orientation 0° .....                    | 30 |
| Code card orientation 0° or 180° .....            | 30 |
| Code card orientation 0°, 90°, 180° or 270° ..... | 30 |
| Code card orientation 180° .....                  | 30 |
| Code cards for setting the read head address      |    |
| Code card for read head address 0 .....           | 28 |
| Code card for read head address 1 .....           | 28 |
| Code card for read head address 2 .....           | 28 |
| Code card for read head address 3 .....           | 28 |
| Code cards for setting the transfer rate          |    |
| Code card transfer rate 115200 bit/s .....        | 33 |
| Code card transfer rate 230400 bit/s .....        | 33 |
| Code card transfer rate 38400 bit/s .....         | 32 |
| Code card transfer rate 76800 bit/s .....         | 32 |
| Code cards with special functions                 |    |
| CANCEL code card .....                            | 26 |
| DEFAULT code card .....                           | 27 |
| ENABLE code card .....                            | 26 |
| STORE code card .....                             | 26 |
| USE code card .....                               | 27 |
| Code strips                                       |    |
| with a starting position of 0 m .....             | 13 |
| with different starting positions .....           | 14 |
| Connection  |    |
| RS485 interface .....                             | 19 |
| Control elements and LED indicators .....         | 10 |
| Copyright .....                                   | 6  |

### D

|   |    |
|---|----|
| Declaration of conformity .....           | 25 |
| Description of the product PCV80A .....   | 9  |
| Designated use .....                      | 8  |
| Dimension drawing for the read head ..... | 17 |

### E

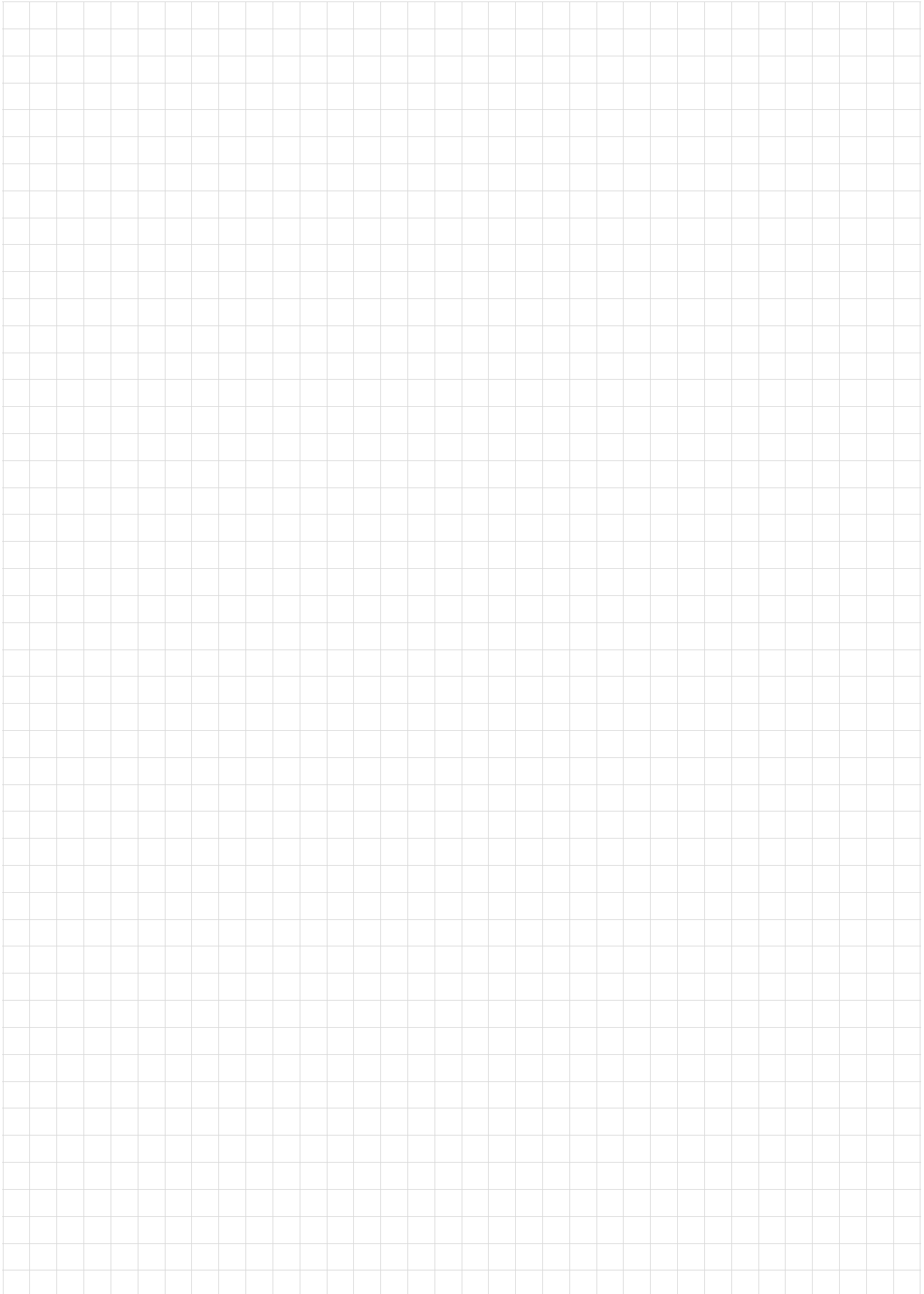
|  |    |
|--|----|
| Electrical connection of the read head ..... | 18 |
| Shielding cables .....                       | 19 |
| Embedded safety notes .....                  | 5  |
| Exclusion of liability .....                 | 6  |

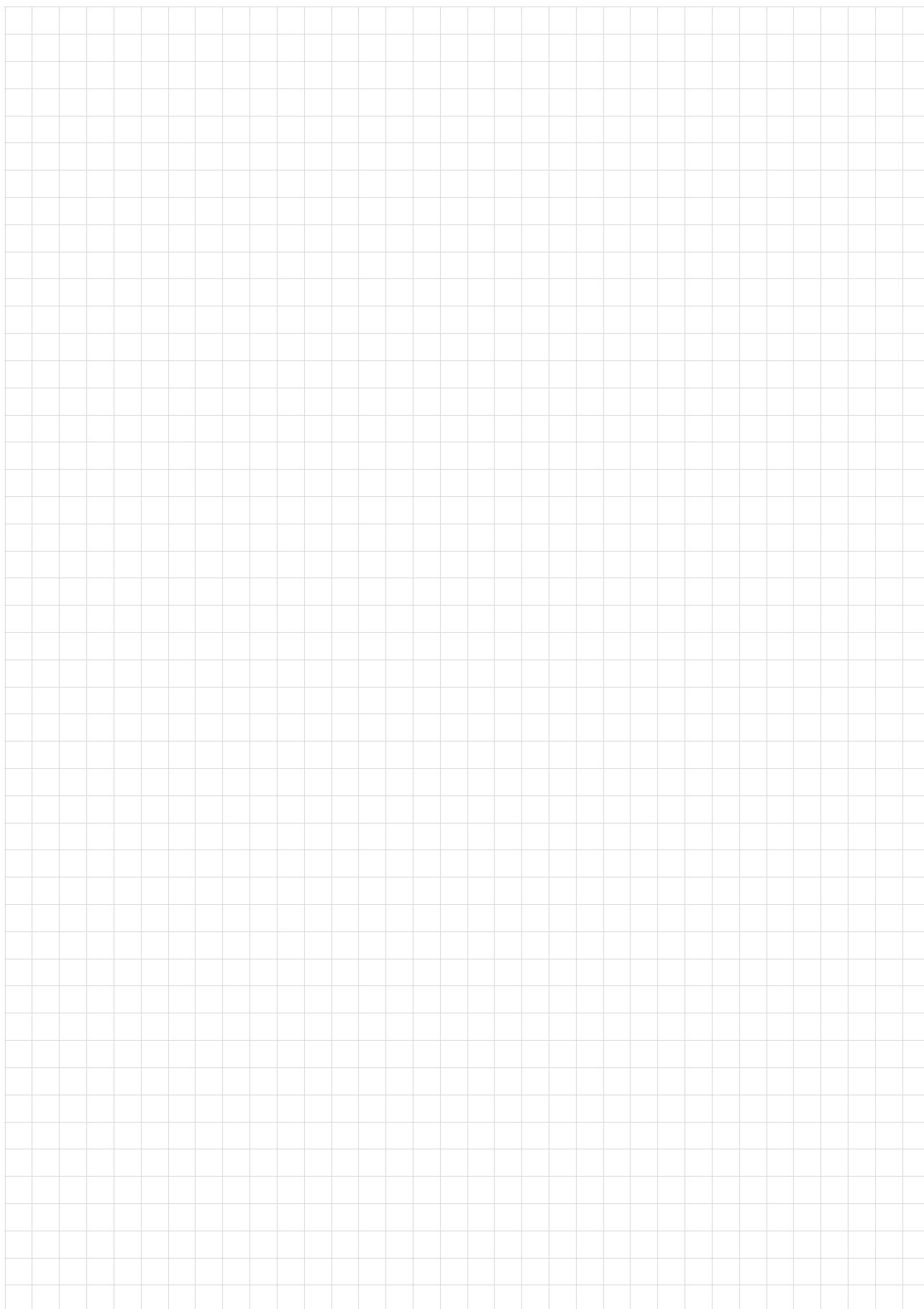
### F

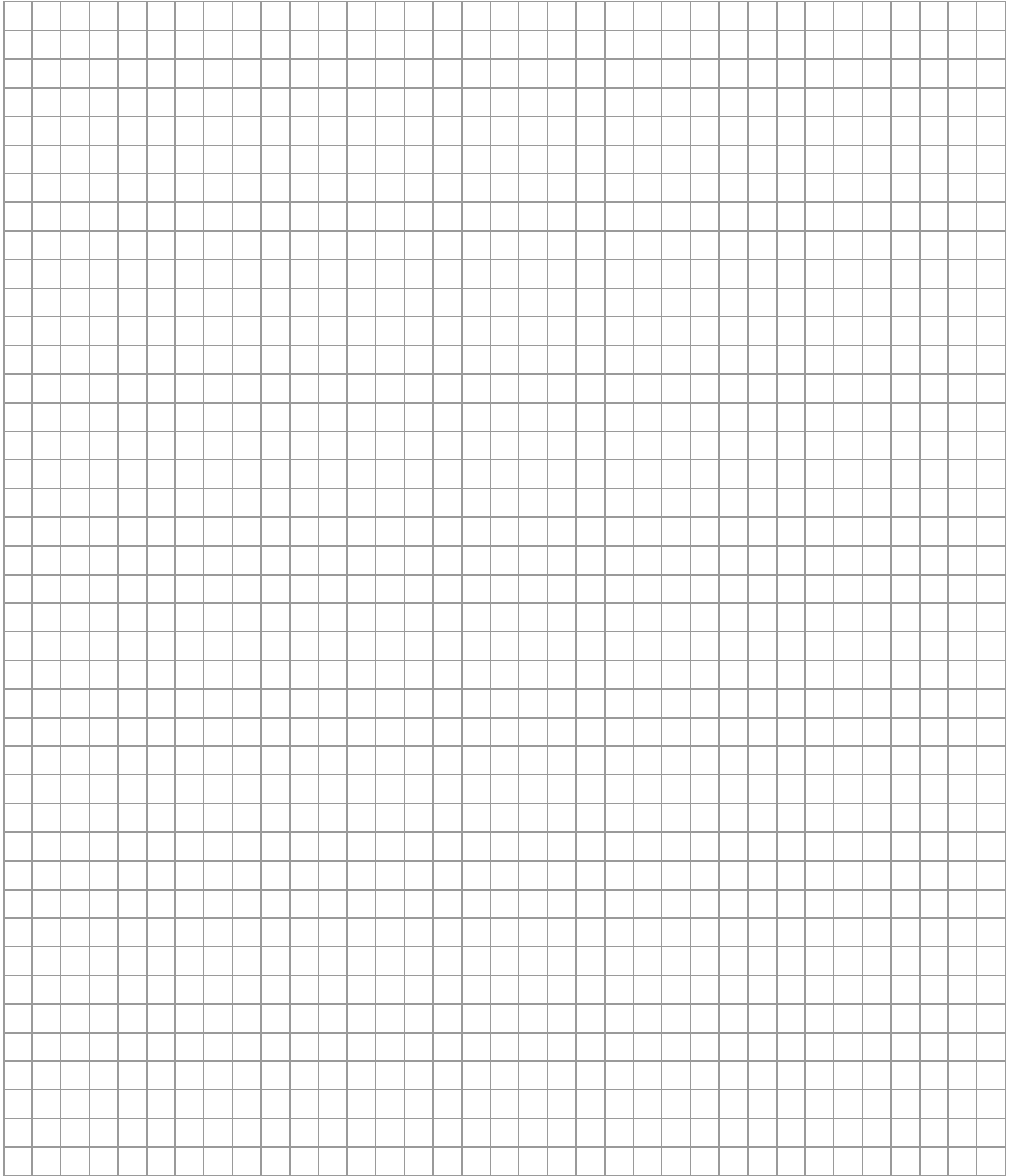
|                              |   |
|------------------------------|---|
| Functional safety technology |   |
| Safety note .....            | 8 |



|   |    |   |    |
|---|----|---|----|
| <b>I</b>  |    | <b>R</b>  |    |
| Installation .....                                  | 12 | Read head   |    |
| Electrical connection of the read head .....        | 18 | Aligning .....                                    | 20 |
| Installing the code strip .....                     | 12 | Electrical connection .....                       | 18 |
| Mounting the read head .....                        | 15 | Mounting .....                                    | 15 |
| Safety notes .....                                  | 8  | Rights to claim under warranty .....              | 6  |
| Installing the code strip .....                     | 12 | RS485 interface .....                             | 9  |
| Code strips with a starting position of 0 m .....   | 13 | Connection .....                                  | 19 |
| Code strips with different starting positions ..... | 14 |   |    |
| Interface, see also RS485 .....                     | 19 | <b>S</b>  |    |
|   |    | Safety functions .....                            | 8  |
| <b>L</b>  |    | Safety notes                                      |    |
| LED indicators and control elements .....           | 10 | Designation in the documentation .....            | 5  |
|   |    | Installation .....                                | 8  |
| <b>M</b>  |    | Preliminary information .....                     | 7  |
| Mounting the read head .....                        | 15 | Structure of the embedded safety notes .....      | 5  |
| Dimension drawing .....                             | 17 | Structure of the section safety notes .....       | 5  |
| Optimum read distance (z-axis) .....                | 16 | Section safety notes .....                        | 5  |
|   |    | Setting read head parameters                      |    |
| <b>N</b>  |    | Externally using code cards .....                 | 21 |
| Notes   |    | Internally using parameter setting software ..... | 21 |
| Designation in the documentation .....              | 5  | Setting the parameters of the read head .....     | 21 |
|   |    | Shielding cables .....                            | 19 |
| <b>O</b>  |    | Signal words in safety notes .....                | 5  |
| Optimum read distance (z-axis) .....                | 16 | Startup .....                                     | 20 |
|   |    | Aligning the read head .....                      | 20 |
| <b>P</b>  |    | Setting the read head parameters .....            | 21 |
| Product description PCV80A                          |    |   |    |
| Accessories .....                                   | 11 | <b>T</b>  |    |
| LED indicators and control elements .....           | 10 | Target group .....                                | 7  |
| RS485 interface .....                               | 9  | Technical data .....                              | 24 |
| Use and application .....                           | 9  | Trademarks .....                                  | 6  |
| Product names .....                                 | 6  | Transport .....                                   | 8  |
|   |    |   |    |
|   |    | <b>U</b>  |    |
|   |    | Use .....   | 8  |
|   |    |   |    |
|   |    | <b>X</b>  |    |
|   |    | X4011 .....                                       | 19 |









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